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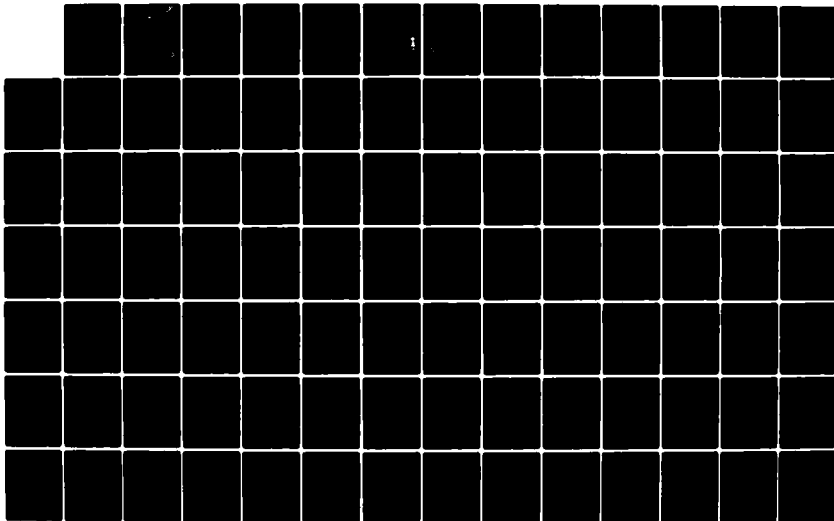
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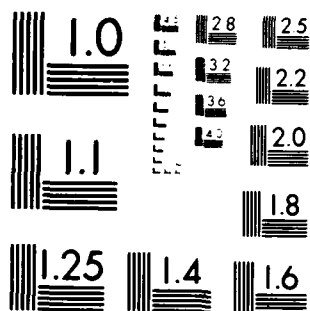
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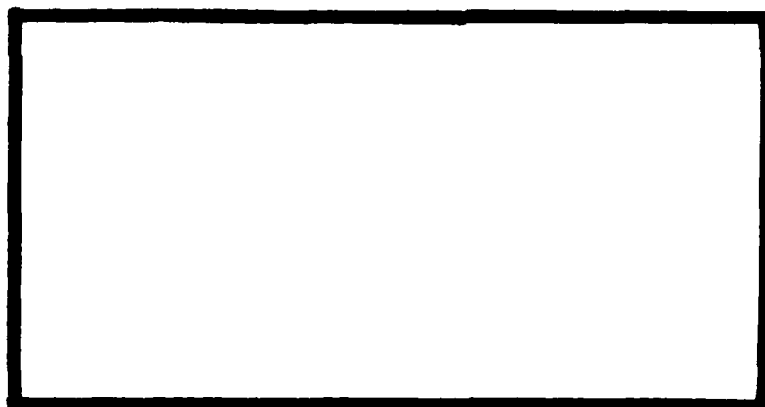
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A STUDY TO DEMONSTRATE THE
APPLICATION OF A GRAPHICAL METHOD
TO DETERMINE AN OPTIMAL
MAINTENANCE TASK INTERVAL
FOR AN ITEM IN AIR FORCE INVENTORY

Douglas C. Beckwith, Captain, USAF
Anthony R. Roclevitch, Captain, USAF

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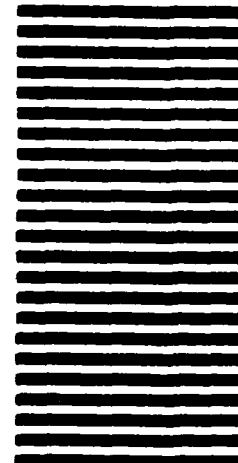
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Determining maintenance task intervals is an important part of any scheduled maintenance program. Criteria for determining optimal intervals is usually based on an objective function designed to minimize average long-term (expected) cost. This study demonstrates a graphical method, developed by Bergman in 1977, for determining a maintenance task interval using the KT-73 Inertial Measurement Unit installed on the A7-D. The method establishes intervals on a "hard time" replacement policy, but can also be used under an "on-condition" maintenance policy. The authors sought to discuss this study within the context of the Reliability-Centered Maintenance Program, but to deviate from the traditional age exploration concept and cost-benefit analyses. Instead, Bergman's simple, but rigorous, method is employed to find a task interval based on a control strategy which balances cost of replacement with cost of failure and results in a minimum total long-run average cost per unit time. Among the advantages of Bergman's method are that the underlying failure distribution need not be known and that a sensitivity analysis can be performed to examine the effects of cost uncertainty with regard to changes in the optimal interval.

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A STUDY TO DEMONSTRATE THE APPLICATION OF A GRAPHICAL
METHOD TO DETERMINE AN OPTIMAL MAINTENANCE
TASK INTERVAL FOR AN ITEM IN
AIR FORCE INVENTORY

A Thesis

Presented to the Faculty of the School of Systems and Logistics
of the Air Force Institute of Technology
Air University

In Partial Fulfillment of the Requirement for the
Degree of Master of Science in Logistics Management

By

Douglas C. Beckwith, BS
Captain, USAF

Anthony R. Roclevitch, BS
Captain, USAF

September 1982

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This thesis, written by

Captain Douglas C. Beckwith

and

Captain Anthony R. Roclevitch

has been accepted by the undersigned on behalf of the
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Captain Beckwith: I wish to express loving gratitude to my wife, Cindy, and daughter, Sarah, for their patience, understanding and selfless cooperation through the graduate program.

Captain Roclevitch: I dedicate my work to my wife, Sylvia, and son, Tony, whose love I could not do without, and for whom, I do everything.

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CHAPTER I

INTRODUCTION

Determining maintenance task intervals is an important part of any scheduled maintenance program. Criteria for determining optimal intervals are usually based on an objective function designed to minimize average long-term (expected) cost. Cost can be expressed in terms of dollars, availability, or readiness, to name a few. This study will demonstrate a graphical method developed by Bo Bergman in 1977 to determine an optimal maintenance task interval for an item in Air Force inventory.

A maintenance task is categorized into one of three recognized maintenance processes: hard time replacement, on-condition, or condition monitoring.

A "hard time" maintenance policy consists of establishing interval time periods of constant "T" at the end of which a unit is replaced, regardless of condition, as a means of precluding failure (1:5; 26:A2-3).

An "on-condition" maintenance policy consists of establishing interval time periods to inspect a unit for measurable wear with a decision to replace based on exceeding set limits (1:6; 22:51).

A "condition monitoring" maintenance policy does not require maintenance tasks. Under this policy, units

not safety or economically significant are permitted to fail and are replaced when discovered (1:7; 22:66).

Bergman's method will be used in this study to determine an optimal task interval based on the hard time concept. The chief advantages of Bergman's method are that the method is simple, the underlying failure distribution need not be known, and the method can be used to analyze any maintenance item for which failure and cost data are available.

A great deal of theory exists on the subject of optimal maintenance policies (see Chapter II). This study attempts to apply some of that theory within the context of an existing maintenance program.

Terminology

Any discussion of maintenance task interval determination in the Air Force is fundamentally tied to Reliability-Centered Maintenance (RCM) concepts. Therefore, the following terms, used throughout this paper, are defined:

Actuarial Analysis: "Statistical analysis of failure data to determine the age-reliability characteristics of an item [22:453]."

Age Exploration: "The process of collecting and analyzing information from in-service equipment to determine the reliability characteristics of each item under actual operating conditions [22:453]."

Age Replacement: Replacement of a unit at failure or some specified age, whichever occurs first (25:139).

Decision Diagram: "In RCM analysis, a graphic display of the decision process in which the answers to an ordered sequence of yes/no questions lead to an identification of the appropriate maintenance action for an item without regard to appropriate level [22:455]."

Failure Modes and Effects Analysis (FMEA): "An analysis, initially performed by the equipment (aircraft) manufacturer, on all the major assemblies, subsystems and systems to demonstrate how the equipment will perform when various items fail [22:80]."

Failure Cycle: The time from renewal to failure of an item.

Item: "Any level of the equipment or its sets of parts isolated as an entity for study [22:459]."

Reliability-Centered Maintenance: "A logical discipline for developing a scheduled maintenance program that will realize the inherent reliability levels of complex equipment at minimum cost [22:463]."

Renewal: Restoring an item to a "good-as-new" condition.

Significant Item: "An item whose functional failures have safety or significant economic consequences [22:464]."

The term "significant" is a subjective value

assignment made through decision processes which are outside the scope of this study.

Task Interval: "The task interval assigned in a maintenance program, subject to adjustment on the basis of findings from actual operating experience through a process called age exploration [22:459]."

AFLC: Air Force Logistics Command

AFSC: Air Force Systems Command

AGMC: Aerospace Guidance and Metrology Center

DOD: Department of Defense

MDS: Mission-Design-Series

WUC: Work Unit Code

Background

Early aircraft were primitive, and redundancy was practically absent in aircraft design due to weight penalties. Consequently, maintenance programs attempted to preclude the failure of every part. The idea that a direct relationship existed between reliability and safety led to the belief that the more scheduled maintenance, the more reliable the aircraft. Thus, "hard time" replacement policy drove early maintenance programs (1:1-2). Aircraft components were replaced after a specified time which, by best estimates, would be before failure (22:51,65,370).

After World War II, advances in design, materials and manufacturing of aircraft began to erode traditional

beliefs about the relationship between reliability and safety. The airline industry, during the 1950s, introduced new alternatives to "hard time" concepts. Eventually the process of inspecting against measurable standards became a second maintenance process. It would later be referred to as the "on-condition" process (22:383; 1:2).

During the 1960s, studies conducted by the airlines, technological advances, complexity of design, and the need to maintain more efficient and cost-effective maintenance programs eventually led to the recognition that certain items do not benefit from scheduled maintenance. This discovery resulted in the advent of a third maintenance process called "condition monitoring." Under this process, items are permitted to operate until failure. Maintenance tasks do not exist under this process (22:66; 1:7).

The introduction of the Boeing 747 aircraft with all of its complexities reinforced the need for new approaches to maintenance. Major airline operators and Federal Aviation Agency representatives formed a maintenance steering group (MSG-1) which developed a decision tree technique for determining maintenance requirements. The technique was refined, expanded, and published in a universal document called Airline/Manufacturer Maintenance Program Planning Document: MSG-2 in 1970. The fundamental concept behind the program was that maintenance actions can only prevent

deterioration of the inherent design levels of equipment reliability (1:10; 22:Preface).

The objective of MSG-2 was to outline the organization and decision processes for determining scheduled maintenance requirements for new aircraft. In other words, the MSG-2 document would facilitate the development of initial scheduled maintenance programs (1:9).

As new airline programs based on MSG-2 decision logic began to grow, the Department of Defense (DOD) experimented with the program, beginning with the Navy P-3 aircraft. Believing that benefits could be derived from the MSG-2 program, especially in terms of manhour savings and increased equipment availability, the DOD between 1974 and 1978 issued several directives and memorandums to implement the "Reliability-Centered Maintenance Program (RCMP)" across all services (1:22-88).

Initially, the program did not address the problems of establishing task intervals, consolidating tasks into work packages, or making decisions where no information is available. These areas were addressed, but not resolved, later in an authoritative text by Nowlan and Heap entitled, Reliability-Centered Maintenance (22:Preface).

Nowlan and Heap wrote their text (1978) under contract to the Office of Assistant Secretary of Defense for Manpower, Reserve Affairs and Logistics. The text was intended to provide the necessary information to understand,

develop and implement RCM programs (22:DD Form 1473). In general, RCM implementation for a given aircraft system consists of an initial failure modes and effects analysis (FMEA) for significant items, identification of tasks via use of the decision logic diagram, and determination of task intervals (22:7).

The first requirement above is satisfied initially by the builder of the airframe through Government contract. The second requirement is fulfilled on a continuing basis by the armed services (AFSC, AFLC in the Air Force) by modifying task requirements based on engineering analysis. The third requirement is discussed by Nowlan and Heap under the general heading of age exploration, but no method for determining optimal task intervals has been developed and published by the Air Force. Currently, Air Force engineers are using the Mean Time Between Failure (MTBF) and Incipency methods. The MTBF method is

. . . based on a 70 to 90 percent probability of detecting a pending failure. This is equivalent to inspection at 10 to 30 percent of the MTBF. An alternative method called the Incipency Concept holds that the inspection interval should be a function of the time between first discernible degradation in performance and loss of the function [28:12].

There are also two computerized programs available (discussed in Chapter II), but they are designed primarily as program management tools.

The Army has published an Appendix C to DARCOM-P 750-16, DARCOM Guide to Logistic Support Analysis,

which defines a general methodology for determining maintenance task intervals based on replacement cost, safety and readiness criteria, and equipment failure rates. The method uses age exploration and seeks to minimize cost, but it involves subjective trade-off considerations (33:C1-C44).

Frick and Sasser (1979) investigated a method to improve the preventive maintenance checks and services program for the M60A1 main battle tank. In the study, Frick and Sasser developed a questionnaire sent to operating units. Each question represented a variable, such as technician skill level, which was analyzed using multiple regression to establish correlations between type and time interval estimates for individual maintenance tasks. The results were subjected to network analysis to produce a preventive maintenance checks and services schedule (14:72-73). The research was extremely subjective since it sought opinions rather than substantive data.

Thus far, the Air Force has successfully integrated the majority, but not all, of its aircraft inventory into the RCM program through contract with the airframe builders. System Managers monitor and update programs using the decision logic criteria outlined in MIL-M-5096D and AFLCP 66-35. (A proposed AFSC/AFLC combined regulation is being drafted which will greatly expand AFLCP 66-35.) However, maintenance

task interval determination remains an area without a proven applicable analytical technique.

Although RCM is a DOD program, each service is pursuing the program objectives individually. There is no apparent consistency of effort. The major problem seems to be lack of guidance from DOD which can best be characterized by the fact that DOD, despite its emphasis on implementing the RCMP within the services, has yet to define the program (1:84-85).

Justification for Research

The Air Force recently experienced a large incidence of failure of the fifth stage compressor disc for the J-85 engine (20:3). Attention to the problem was brought about by an aircraft accident. The aircraft accident board attributed the accident to failure of the disc and also discovered that the replacement interval for the disc had been changed by AFLC from the 3200 hours recommended by General Electric to 4000 hours. The disc failed less than 100 hours from replacement and resulted in the loss of the aircraft. Consequently, the replacement interval has been changed to 3600 hours (20:1-3). The board findings illustrate the need to develop a methodology for determining optimal maintenance intervals.

An excerpt from a HQ USAF Reliability-Centered Maintenance Program Status Report dated 29 May 1981, identifies an Air Force Logistics Management Center (AFLMC)

tasking to pursue a means of improving the analytical process for determining scheduled maintenance task intervals during FY 82 and the outyears (19:4).

The latest effort by AFLMC was a contract study which resulted in a report authored by Singpurwalla and Talbott and published in January 1981. The report reviewed key ideas in the area of preventive maintenance replacement policies, and concluded that sufficient theory exists for practical applications (26:A2-16,17).

There is, indeed, much theory (see Chapter II) concerning optimal maintenance policies used to determine task intervals. The policies are typically based on the objective of finding the interval which minimizes cost. Bergman's method, the subject of this study, also seeks to minimize cost. However, as these methods are presented in theoretical form, application of the theory needs to be explored.

The MSG-2 maintenance concept did not address the problem of establishing task intervals (22:Preface). Any maintenance task can be made effective in terms of failure prevention if the intervals are made short enough, but this ignores, among other things, the opportunity cost of being unable to operate the equipment during maintenance (22:91,95).

Nowlan and Heap discuss maintenance task interval determination in terms of age exploration and actuarial analysis. Basically, intervals are established at an age when a large number of failures begin to occur, but before

which very few failures occur (22:390). Approaching the problem of cost-effectiveness, they employ a decision logic technique. Specifically, they recommend at least four proposed intervals be examined to determine whether a cost-effective interval does exist, based on the most favorable cost-benefit ratio (22:102).

Their approach tends to suboptimize the last of the four objectives of an operator's maintenance program. Those objectives are

- To ensure realization of the inherent safety and reliability levels of the equipment.
- To restore safety and reliability to their inherent levels when deterioration has occurred.
- To obtain the information necessary for design improvement of those items whose inherent reliability proves inadequate.
- To accomplish these goals at a minimum total cost, including maintenance costs and the costs of residual failures [22:Preface].

Nowlan and Heap do not approach the problem of determining "optimal" intervals by balancing the cost of replacement and the cost of failure.

Perhaps a key word is "costs." Concerted efforts to assess benefits derived from implementation of RCM programs in DOD have generated controversy because of the difficulty in delineating cost-savings directly attributable to RCM and in quantifying benefits such as increased equipment availability (1:68-69).

An unending cycle exists in which appropriate cost data is not available to fully test new methods for determining maintenance task intervals, while on the other hand,

the adoption of an acceptable methodology might warrant changes in data systems to facilitate collection of needed cost information.

Nevertheless, a need exists to begin bridging the gap between theoretical and practical application of methodology to determine maintenance task intervals.

Problem Statement

DODD 4151.16, AFR 66-14, AFR 66-30, AFLCP 66-35 and MIL-M-5096D provide definitions, outline responsibilities and explain the use of reliability data as applied to equipment maintenance, but the Air Force does not present a standard analytical approach for determining maintenance task intervals in published form.

Research Objective

The objective of this study is to demonstrate the feasibility of applying a new and simple graphical method for determining optimal maintenance task intervals using actual field data for equipment used on aircraft. The method is based on a control strategy which balances cost of replacement with the cost of failure resulting in a minimum total long-run average cost per unit time.

Research Question

Can Bergman's graphical method be applied in determining an optimal maintenance task interval based on the

objective of minimizing total long-run average cost per unit time using actual field data?

Since the research question involves application of actual field data for an existing item in Air Force inventory, two questions secondary to the research question are

1. How does the calculated optimal interval for the units tested compare with the current interval for that item?
2. How sensitive is the calculated optimal interval to the uncertainty of cost?

Scope and Limitations

The Reliability-Centered Maintenance Program is a DOD program and applies to all military services. There are three basic steps for incorporating a major equipment end item into the program: (1) a failure modes and effects analysis (FMEA) for all significant items, (2) identification of maintenance tasks based on the decision logic, and (3) determination of maintenance task intervals. This study is concerned with the third requirement and is limited to its application in the Air Force, though results could be generalized to any equipment maintenance program. Bergman's graphical technique was chosen among the many available theoretical models because it is a simple, but rigorous method.

The units selected for the study were taken from the Air Force aircraft inventory of equipment primarily to facilitate data collection.

The unit selected for study was by no means an ideal one. The KT-73 Inertial Measurement Unit (IMU) is used on the A7-D and AC-130A aircraft. This study collected data for only those units installed on the A7-D. A complete description of the unit is contained in Appendix A. As an electronic component, the KT-73 IMU currently does not have a maintenance task interval assigned to it. Like other electronic units, the KT-73 is assumed to have an exponential failure distribution (16). Thus, the item is maintained under a condition monitoring or "fly-to-failure" policy. A hard time replacement policy is appropriate for those items which exhibit wearout characteristics for which an economic life-limit can be identified. A unit which is already maintained under a hard time replacement policy would better illustrate the application of Bergman's graphical method.

Availability of failure data dictated the choice of unit for study. Bergman's method requires the use of observational data. The KT-73 is repaired by the Aerospace Guidance and Metrology Center (AGMC) and tracked by serial number and field operating hours on the G078C Maintenance Data Collection System. Since no other data collection system could be found which provided the same type of

nonaggregated data, the C078C was the logical choice. The KT-73 was selected among other IMUs because of early acquisition.

The greatest limitation on this study centers around the availability of appropriate cost data. In order to find an optimal replacement interval which minimizes cost, the cost to replace an item (scheduled maintenance) as well as the cost of an in-service failure (unscheduled maintenance) must be known. These costs are actually random variables, not constants. Since Bergman's method treats these costs as constants, an expected value for each cost will be used in lieu of a probability distribution description. Furthermore, since the cost data covers several years, it is assumed that these historical costs are representative of actual costs.

The cost of in-service failure can be obtained from data collected by the Resources Division at AGMC and is expressed in terms of the actual dollar amount required to repair each failed unit. Adding to this, the cost of transporting units to and from depot and the cost of labor to trouble-shoot failed units gives the total cost of failure.

Replacement cost is the cost of transporting units to and from depot plus the cost that would be incurred to renew a nonfailed unit which is removed after a specified interval of time, presumably before failure. This entails repair or replacement of unit subcomponents which are

approaching failure, thus, restoring the unit to a "good-as-new" condition (renewal) (24:53). Since the KT-73 IMU is a hermetically-sealed unit, any unit received by AGMC, whether failed or nonfailed, is subjected to the same test and repair procedures (Appendix A contains a checklist used for testing units) (16). Consequently, the same cost is incurred to repair a nonfailed unit as a failed unit.

The difference between cost of replacement and cost of failure is the cost of trouble-shooting. Other costs which could be considered are the loss of equipment availability or readiness. But these costs are much too difficult to quantify.

Actual cost to repair a failed unit is documented as an annual average for each fiscal year. Transportation costs are documented quarterly by WUC 73FAO in the K051 system. By adding the repair cost, transportation cost and trouble-shooting cost, a total cost of in-service failure can be assigned to each unit in the sample. The range of these values can be evaluated for parameters and used for sensitivity analysis under Bergman's method. A limitation exists in that individual trouble-shooting costs cannot be linked to individual unit failures by serial number. Cost data provided by AGMC and the K051 data collection system is presented in aggregated form from which averages (expected costs) must be derived.

It should be noted that a unit might have failed in a quarter previous to the one in which it arrived at and was repaired by AGMC. In cases where this is true, the costs of transportation and trouble-shooting for a unit may be included in a different quarter than the quarter in which the repair cost for the same unit is recorded. However, since expected per unit costs in this study are computed based on annual averages, the problem is limited to when the discrepancy occurs between the last quarter of a given year and the first quarter of the following year. Hence, the use of annual averages tends to smooth or reduce the scope of the mismatch problem.

Since in-service failure of the KT-73 will not cause a mission abort or damage to other components in the system, an attempt will not be made here to quantify the effects of aircraft Not-Mission-Capable (NMC) time generated by failure of the KT-73 unit. This kind of opportunity cost (the cost of being unable to operate the aircraft) is contingent on too many variables to attempt an adequate measure. To illustrate this difficulty, a Government Accounting Office (GAO) study in November 1976, an Air Force Audit Agency (AFAA) audit in April 1977, and an Air Force study in November 1977 sought to measure benefits derived from RCM using the same kind of variables. General comments from these reports concluded that ". . . RCM appeared to have had an effect that could not be quantified [1:68]."

The validity of the findings of this study is dependent on the accuracy of the data contained in the G078C and K051 systems. Inaccuracies in the data are probably the most often cited shortcoming of the entire range of maintenance data collection systems (3:12). Badalamente and Clark (1978) discuss these and other problems in their technical report. The advantage in using data collected from the G078C is that operating hours are tracked by a mechanical time indicator as opposed to being tracked by manual observation.

Methodology

The objective of this study is to demonstrate the application of Bergman's graphical method for determining optimal maintenance task intervals. To accomplish this, field data for the KT-73 Inertial Measurement Unit representing operating time to failure, replacement cost, and cost of in-service failure will be collected from the G078C and K051 Maintenance Data Collection Systems. The failure data will be scaled and used to construct a Total Time on Test (TTT)-plot representing a transform of the empirical failure distribution for the unit. The cost data will be scaled and used to plot a point, which represents the cost of replacement, through which a line can be drawn tangent to the TTT-plot. The abscissa of the tangent point denotes the index for the optimal replacement interval.

The function that Bergman's method performs is to minimize total long-run average cost per unit time, $C(T)$, by maximizing the reciprocal of the objective function, $[C(T)]^{-1}$.

The calculated interval can be compared to the existing interval, which is infinite (fly-to-failure), and a sensitivity analysis performed using a range of values for cost of replacement to observe their effect on changes in the optimal interval.

Research Assumptions

1. Units upon which data are collected are subjected to identical and constant maintenance policy.
2. Field data was accurately entered into the G078C and K051 Maintenance Data Collection Systems.
3. The replacement cost provided by AGMC is a valid estimate of long-run average cost to replace.
4. The item used in this study is not safety-critical.
5. Organizations operating the units under study consider the effect of a unit's failure on mission in the same way. Essentially, the effect which the unit has on aircraft status in the Mission Essential Subsystems List (MESL) is the same. For example, if the anti-skid system on a T-39 aircraft is not operational, all units would record the aircraft status as Partial-Mission-Capable (PMC). This

assumption is necessary since the priority given to failure of a KT-73 unit could affect base labor costs.

CHAPTER II

LITERATURE REVIEW

Introduction

For over two decades, there has been a large and continuing interest in the field of reliability and maintainability concerning maintenance models for items with stochastic failures. This interest has its roots in many military and industrial applications [23:353].

As Pierskalla and Voelker point out in their survey paper, there are a number of maintenance models. This review is concerned with those models which pertain to the maintenance of simple (i.e., single component) equipment and which involve an optimal decision to replace a unit in service (scheduled, hard time maintenance). These types of maintenance policies are known as "Replacement Policies" and involve the single uncertainty of when a failure will occur (26:A2-1).

The maintenance models presented here address objective of minimizing total cost or maximizing availability. In addition to the optimal concepts presented, the U.S. Army's use of age exploration (in determining hard time replacement intervals) as well as two computer-assisted maintenance programs are discussed. The literature has been divided into the three sections indicated in Figure 2-1.

- I. Optimal Replacement Policies
 - A. Age replacement
 - B. Block replacement
 - C. Periodic replacement with minimum repair at failure
 - D. Sequential replacement over a finite time span
 - E. Optimal replacement under damage accumulation model
- II. Age Exploration
- III. Computer Assisted Maintenance Programs

Fig. 2-1. Summary of Preventive Maintenance Literature

Discussion

Optimal Replacement Policies

This section considers policies pertaining to scheduled maintenance actions on a hard time replacement basis so as to preclude failure during operation. These policies specify a replacement interval, T , which minimizes total long-run average cost per unit of time, $C(T)$.

Age Replacement. In general, an age replacement policy is in effect when a part is replaced at failure or at some specified age, whichever occurs first (6:85; 18:213; 7:751). This policy makes intuitive sense only if the cost of replacement is less than the cost of an in-service failure and only if all costs are nonnegative (6:85; 18:213; 7:751).

According to Barlow and Proschan, the specified decision variable, age of replacement (i.e., T), can be random (for a finite time span) or fixed (for an infinite time

span) (6:72,86). Most of the age replacement literature is for an infinite time span, whereby, the underlying failure distribution is assumed to be known and continuous, the optimum age replacement interval is a constant, a replacement restores the system to a good-as-new condition, and the restoration process goes on indefinitely (6:86).

Ingram and Scheaffer assert that if the underlying failure distribution is completely known, then finding the optimum replacement interval is simply an analysis problem (18:213). However, if the underlying distribution is not completely known, they show that an estimate of the optimum interval, T , can be found by minimizing a consistent estimator, $C_n(T)$, of the objective function $C(T)$. The consistent estimator, $C_n(T)$, assumes a form or property of the failure distribution. They treat four cases: (1) a Weibull distribution with unknown scale parameter, (2) a gamma distribution with unknown scale parameter, (3) an empirical distribution, and (4) a distribution specified only as having an increasing failure rate (18:213). They conclude that the empirical estimator of the optimum replacement interval is close to the estimators of the cases in which the distribution is known (18:219).

Berg notes that previous authors have assumed that an age replacement policy is appropriate for a replacement scenario. In his paper (7:751-759), he proves that an age replacement policy is the optimal procedure among a range of replacement policies for which a replacement time can be

well-defined (7:752). He accomplishes this by showing that the expected long-run cost per unit time for an optimal age replacement policy is less than or equal to the expected cost associated with other common replacement policies (7:758).

Scheaffer introduces an optimal age replacement policy with an increasing cost factor for an infinite time horizon. Specifically, he addresses the exponential life distribution with an exponential cost factor (25:142), i.e., the cost of replacing a unit increases with age. For example, the trade-in value of a rubber tire may decrease with wear. This has the effect of increasing the cost of replacement with age. Using numerical illustrations, he shows that when the objective function includes an increasing cost factor, the optimum replacement interval yields a smaller average cost per unit time than the interval found under a replacement policy whose objective function does not include an increasing cost factor (25:144).

According to Glasser, the analytical solution for finding the optimal age replacement interval is generally known (15:83). In his paper, he asserts that the optimal interval depends upon: (1) the ratio of cost of failure to cost of replacement, and (2) the average service life in standard deviation units (15:86). For the truncated normal, the gamma and the Weibull distributions, he charts cost ratio versus service life for each case to obtain a graphical

means for locating the optimal replacement interval based on changing values for the two variables (15:87-89).

Fox considers a discounted cost criterion when determining an optimal age for replacement. Assuming a continuous IFR failure distribution, he shows that for each stage (replacement to replacement) on an infinite time span, there is an optimal replacement interval which minimizes loss (12:534). For example, if a replacement interval is fixed at age T and a failure occurs before age T , then a loss is incurred. Fox seeks to find an optimal interval which minimizes this loss (12:534-535).

Block Replacement. Barlow and Proschan define a block replacement policy as one in which an item is replaced at equal time intervals independent of age and at failure (6:67). This policy has the practical advantage of not having to maintain records of failure times or age. When compared to an age replacement policy, block replacement results in a greater number of total removals. However, the expected number of failures is fewer under block replacement, provided failure increases with age (6:67). The objective is to minimize average cost per unit of time.

Berg and Epstein acknowledge that block replacement policies (BRPs) result in the replacement of fairly new items. Some modifications to the BRP have been made to avoid this drawback. One model allows minimal repair of a failed

item which is equivalent to replacing the item with a working one of the same age (8:15). Another model permits a failed item to remain idle until scheduled block replacement occurs (8:16). They propose a third model called a Modified BRP.

In Berg and Epstein's Modified BRP, failed items are still replaced immediately, but items of age "b" or less are permitted to remain in service when a scheduled block replacement point arrives. Within the interval $(0, t)$, there is an age b such that $0 < b < t$. The objective function, $C(b, t)$, is then minimized for values of b and t (8:16-17).

Singpurwalla and Talbott point out that, although the problem of replacing relatively new items is overcome, an additional problem is created by requiring knowledge of an item's age (26:A2-13).

Periodic Replacement with Minimum Repair at Failure.

Barlow and Hunter developed Policy II, a variation of the block replacement concept. Under this policy, system replacement occurs at a fixed time, regardless of the number of previous failures. For failures which occur prior to planned replacement, only minimal repairs are made so that the system failure rate is unchanged (5:92). "This repair action is mathematically equivalent to replacing the failed item by another working item of the same age [8:15]." Under this policy, complex systems appear to be single units aging over time.

Sequential Replacement Over a Finite Time Span. In a sequential replacement policy where an item has a finite life, replacements are scheduled only for the next interval such that the next planned replacement time is found which minimizes expected cost over the remaining life of the system (6:98). Hence, a new optimal replacement time is computed after each replacement rather than at fixed time intervals. Barlow and Proschan compared the results of a sequential policy versus an age replacement policy and found that the difference was quite small (about one percent of expected cost) (6:105). Their work was reviewed by Singpurwalla and Talbott who stated, "Only in cases of very high maintenance costs should sequential replacement policies be considered [26:A2-15]."

Optimal Replacement Under Damage Accumulation Model. Taylor presents an optimal replacement policy based on additive damage which seeks to balance the cost of replacement with the cost of failure, and which results in minimum total long-run average cost per unit time (29:1). The damage accumulation model uses a shock failure model in which shocks to the system occur in a Poisson fashion and accumulate additively. The total accumulated damage dictates the probability of system failure (29:4). Assuming that the accumulated damage can be continually observed by a controller, a decision to replace can be made based on the current

value of total damage (29:2). Taylor shows that an optimal policy exists which enables the controller to replace the system upon reaching a critical damage threshold. Replacement also occurs upon failure, regardless of the amount of damage, and a penalty cost is incurred (29:5).

Singpurwalla and Talbott conclude that models of this type have limited usefulness because they are highly structured and require a great deal of user information (26:A2-15).

Age Exploration

Nowlan and Heap's concept of age exploration (discussed in Chapter I) considers cost measurement subjectively without giving a truly optimal method for determining maintenance task intervals. Although the U.S. Army uses this concept for determining hard time replacement intervals, the procedure below must be considered outside the context of "optimal" age replacement policies.

Essentially, the Army establishes two types of hard time limits: safety and readiness. In each case, a cumulative failure distribution is first established (or assumed) for the item under study. For safety limits, replacement intervals are established based on extremely low probabilities of failure. Readiness hard time intervals are established for items which affect mission success. The readiness interval is identified through a trade-off process involving the cost of replacement, the cost of failure and the

readiness requirement of the equipment under consideration (33:C6-C19). Although an objective function is formulated, the trade-off process actually represents a "search" process for an acceptable, rather than an optimal, solution.

Computer-Assisted Maintenance Programs

The Computer Monitored Inspection Program (CMIP) developed by Lockheed, and the Vought RCM Update System developed by LTV Corporation are designed to help managers keep scheduled maintenance programs current and cost-effective while maintaining design levels of safety and reliability. They are similar in that both programs use a series of computer routines to reduce data collected by the Air Force. These programs are currently in limited use by the Air Force for determining intervals for scheduled maintenance programs and are projected for widespread use on many MDS aircraft.

Essentially, the program outputs are designed to provide analysts and decision makers with the information necessary to evaluate maintenance task requirements. Decisions can be made whether to add or drop certain maintenance tasks and whether or not to change task intervals. Additionally, information is provided concerning the effects of these changes on associated manhours (17:29; 19:4).

The programs differ primarily in output. The CMIP output is more condensed than the Vought output and was designed as an exception report which makes recommendations

to the manager about changing requirements. The Vought program output provides considerably more information designed for the analyst's use. It does make recommendations, but it provides enough information to permit in-depth analysis for trends in changing requirements. For this reason, the CMIP is more applicable to aircraft with well-screened maintenance programs; i.e., multi-engine aircraft with numerous redundant systems. On the other hand, the Vought program is more applicable to fighter-type aircraft (17:17).

Both programs recommend changes in maintenance task intervals based on a "target probability" of having no malfunctions occur between scheduled maintenance for the item being considered. Once the target probability is established, an exponential failure distribution is assumed and an interval is calculated. The Vought program uses a fixed 85 percent target probability while the CMIP permits input of user-controlled target probabilities (17:31; 19:12). Although the programs refer to calculated intervals as "optimum" ones, the objective is not that of minimum cost or maximum availability. Cost considerations are treated separately from intervals and are limited only to evaluation of associated manhour requirements.

Summary

This chapter has examined the literature on maintenance policies designed to establish hard time replacement

intervals. Pertinent information was provided concerning optimum replacement policies, Nowlan and Heap's notion of age exploration and computer-assisted maintenance programs to lay a basic framework for the research project.

The literature authored by Berg, Ingram and Scheaffer; Barlow and Campo; Bergman; and Singpurwalla and Talbott greatly influenced the direction of this project. Berg's paper shows that an age replacement policy is the optimal decision rule among all reasonable replacement policies. Research conducted by Ingram and Scheaffer presents a method of determining an estimate of the optimum age replacement interval where an empirical distribution function may be used with no serious loss of information. Barlow and Campo originally introduced the TTT-plot technique that Bergman later uses.

Bergman's research adds to the efforts of Ingram and Scheaffer, and Barlow and Campo, and derives a graphical technique used to obtain an estimate of the optimum age replacement interval. This technique provides an easy method to perform sensitivity analysis with respect to often uncertain cost. It has advantages in application in that it uses an empirical failure distribution versus an assumed/theoretical failure distribution, and provides some intuitive feeling for the uncertainties involved in the estimation. Singpurwalla and Talbott concluded that among the age replacement policies, Bergman's graphical technique was

the most promising because of its ease of application and theoretical correctness.

However, they cautioned that ". . . data over a limited time span, may not adequately represent the true failure distribution thereby introducing sampling error [26:A2-10]." Large samples are necessary for application of the method.

Because of the above stated reasons, it was decided that this research project would focus on Bergman's graphical technique.

CHAPTER III

METHODOLOGY

The objective of this research is to demonstrate that Bergman's method can be used to determine optimal maintenance task intervals based on a control strategy which balances cost of replacement with the cost of failure and results in a minimum total long-run average cost per unit time. To accomplish this objective, field data for a given piece of equipment will be analyzed using a Total Time on Test (TTT)-plot originally introduced by Barlow and Campo (1975) and presented in simple form by Bergman. Under this method, the life distribution is assumed to be unknown and observational data are provided (9:468). Once the data is analyzed, a graphical method is applied to obtain a reasonable nonparametric age replacement policy.

It should be noted that Bergman's method to obtain an optimal age replacement policy provides "hard time" intervals for scheduled rework or discard tasks.

The explanation of the methodology used in this research involves a discussion of cost measurement, TTT-plot, graphical solution, sensitivity analysis, sample space and data collection.

Cost Measurement

For any unit which is believed to be more prone to failure with age, it may be beneficial to replace the old unit with a new one at some point in time. Under an age replacement policy, maintenance tasks are scheduled at intervals. To find the optimal interval requires balancing cost of replacement (scheduled maintenance) with cost of failure (unscheduled maintenance).

For any age replacement policy, there is a cost of replacement (nonfailed item), C_0 , and cost of in-service failure, C_0+k , where k represents the difference between the cost of replacement and the cost of failure. Therefore, an age replacement policy is advantageous when $(C_0+k) > C_0$.

Bergman expresses cost, C , as a constant which is equal to the cost of replacement standardized to units of k dollars. Thus, if

C_0 = actual cost of replacement in dollars

C_0+k = actual cost of failure in dollars

Then for all positive C_0 and k ,

$C = C_0/k$, the standardized cost of replacement

$C+1 = C_0/k + k/k$, the standardized cost of failure

To illustrate, let $C_0 = \$100$, and $k = \$200$, then $C_0+k = \$300$. Since $C = C_0/k$, then $C = 100/200 = 0.5$ is the cost of replacement in terms of k dollars. $C+1 = 1.5$ is the cost of failure.

In terms of Bergman's graphical technique, the cost of replacement, C , is a fixed value.

Total Time on Test-plot: Analysis of Failures

In arriving at an optimum age replacement policy, the underlying failure distribution, $F(T)$, must be known and often, when the distribution is unknown, assumptions are made. Arunkumar (1972) attempted to resolve this problem by estimating the distribution using ordered failure time data (26:A2-5):

$$X_1 \leq X_2 \leq \dots \leq X_n$$

Bergman simplifies Arunkumar's procedure and applies it to the TTT-plot technique. Given n lifetime observations (t_1, \dots, t_n) , which are ordered according to size, the i th observation, t_i , represents the operating life for the i th unit. Then, total time on test through the i th failure time is calculated as

$$T_i = \sum_{j=1}^i = (n-j+1) (t_{(j)} - t_{(j-1)}), \quad i = 1, \dots, n$$

where $t_{(0)} = 0$. T_i is the total time generated by the n units before age $t_{(i)}$.

The ratio T_i/T_n , $i = 1, \dots, n$ is the scaled total time on test at age T_i denoted by U_i , i.e., $U_i = T_i/T_n$. The TTT-plot is obtained by plotting U_i against i/n . The result is a function of an empirical cumulative distribution function, $F_n(T)$.

The following example illustrates the process for constructing a TTT-plot. Given that 10 units are observed to failure, the life times ($t_{(i)}$) are scaled as follows:

i	$t_{(i)}$	T_i	U_i
1	10.8	108.0	.3397
2	18.5	177.3	.5577
3	27.9	252.5	.7943
4	30.0	267.2	.8405
5	31.1	273.8	.8613
6	35.1	293.8	.9242
7	40.2	314.2	.9884
8	40.6	315.4	.9921
9	41.7	317.6	.9991
10	42.0	317.9	1.0000

A FORTRAN Program (Figure 3-1) will calculate values for T_i and U_i reading from the data tape (identified as Tape 11), and will output results in tabular form (Table 3-1).

Figure 3-2 shows the TTT-plot for the sample data. If the failure rate is an increasing function of age (IFR), the plot is concave. If the failure rate is decreasing, the plot is convex. If the failure rate is constant, the plot is a 45-degree slope. Figure 3-3 illustrates the three possibilities.

Nonparametric Age Replacement

Bergman's method is a mathematical representation of a stochastic process known as a renewal process (when an

```

100=    PROGRAM TTITLEOT
110=0
120=    REFL Y(100),T(100),U(100)
130=    INTEGER I,J,K,N,K
140=0
150=0    DEFINITIONS: TAFE11 CONTAINS ALL
160=0    OBSERVATIONS SMALL T(I)
170=0    N=TOTAL NUMBER OF OBSERVATIONS PLUS ONE
180=0    Y(I)=CAPITAL T(I), U(I)=U(I), I,J,K,X
190=0    ARE INDEXES.
200=0
210=    N=11
220=    K=1
230=0
240=    DATA Y,T,U/332*0.0/
250=0
260=    READ(11,*) (T(X),X=2,N)
270=    PRINT '(1X,10X,"T",6X,"OBSERV",5X,"TOTAL",5X,"SCALED")'
280=    PRINT '(1X,12X,"NO.",6X,"TIME",6X,"TIME",7X,"TIME",//)'
290=0
300=    DO 10 I=2,N
310=        J=I-1
320=        Y(I)=(N-J)*(T(I)-T(K))+T(K)
330=        K=K+1
340=10    CONTINUE
350=0
360=    J=1
370=    DO 20 I=2,N
380=        U(I)=Y(I)/Y(N)
390=        PRINT 40,J,T(I),Y(I),U(I)
400=        WRITE(12,')( " "F0.5)'U(I)
410=        J=J+1
420=20    CONTINUE
430=0
440=40    FORMAT(1X,12X,10,5X,F6.1,4X,F6.1,5X,F6.4)
450=    RETURN
460=    END

```

Fig. 3-1. Program for Scaling Observed Data

TABLE 3-1
PROGRAM OUTPUT

I NO.	OBSERV TIME	TOTAL TIME	SCALED TIME
1	18.8	188.6	.3397
2	18.5	177.2	.5577
3	27.9	252.5	.7943
4	38.8	267.2	.8485
5	31.1	273.6	.8613
6	35.1	293.8	.9242
7	48.2	314.2	.9884
8	48.6	315.4	.9921
9	41.7	317.6	.9991
10	42.8	317.9	1.0000
END TTTPLOT			

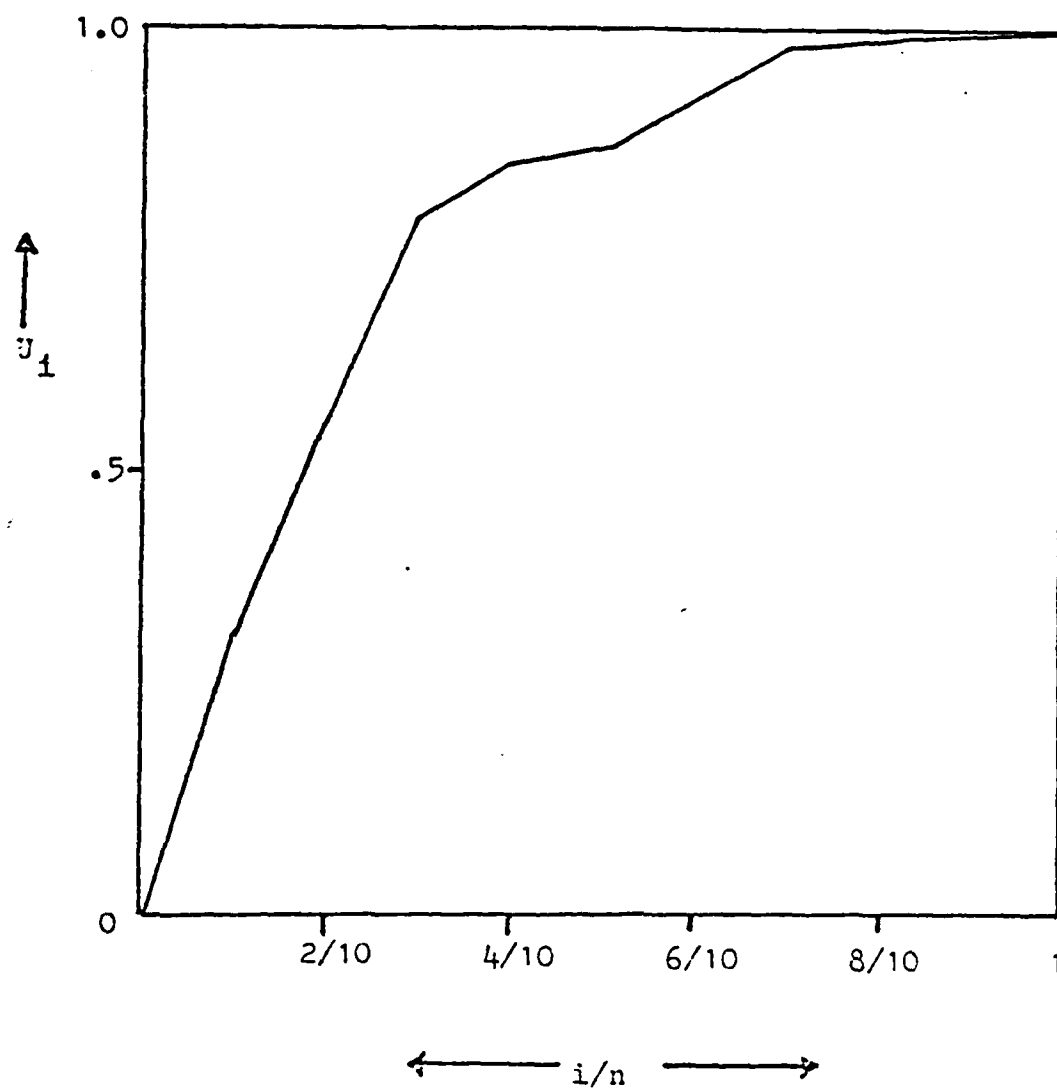
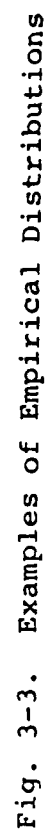


Fig. 3-2. TTT-plot



item is failed or replaced, the cycle starts over again). When rewards or costs (negative rewards) apply, the renewal reward theorem (24:53) states:

$$\text{average long-term cost} = \frac{\text{expected cost in a cycle}}{\text{expected cycle length}}$$

In order to minimize average long-run cost, the objective is then,

$$\text{MIN} \left[\frac{\text{expected cost/cycle}}{\text{expected cycle length}} \right]$$

This can be expressed as follows (9:467) (for $T \geq 0$):

$$\text{MIN } C(T) = \left[\frac{C+F(T)}{\int_0^T (1-F(t)) dt} \right] \quad (1)$$

Thus, in finding an estimate of the optimal age replacement interval, a value for T must be found which minimizes cost $C(T)$. Using the empirical life distribution,

$$F_n(t) = (i/n)$$

that is, substituting $F_n(T)$ for $F(T)$ in Equation (1), then:

$$C_n(T) = \left[\frac{C+F_n(T)}{\int_0^T (1-F_n(t)) dt} \right] \quad (2)$$

Relying on a proof presented by Ingram and Scheaffer (18:216), Bergman states that to estimate the optimal age replacement

interval, it is enough to find the index for t , call it j , with minimizes

$$C_n(t_j) = \left[\frac{C + F_n(t_j)}{\int_0^T (1 - F_n(t)) dt} \right] \quad (3)$$

Using the definition of the empirical distribution function

$$F_n(t_j) = j/n \text{ and the fact that } \int_0^T (1 - F_n(t)) dt = 1/n(T_j), \quad j = 1, \dots, n$$

then, Equation (3) becomes

$$C_n(t_j) = \frac{C + j/n}{1/n(T_j)} \quad (4)$$

By manipulation,

$$\frac{C + j/n}{1/n(T_j)} = \frac{C + j/n}{1/n(T_n)(T_j/T_n)} = \frac{C + j/n}{1/n(T_n)(U_j)}$$

Thus,

$$C_n(t_j) = \frac{1}{1/n(T_n)} \left[\frac{C + j/n}{U_j} \right]$$

where T_n and U_j , $j = 1, \dots, n$, are defined under the TTT-plot.

One way to minimize the discrete function $C_n(t_j)$ is by complete enumeration, but with large numbers of failures, enumeration is tedious. Bergman's graphical approach seeks to minimize $C(T)$ by maximizing its reciprocal $[C(T)]^{-1}$.

Therefore,

$$\frac{1}{C_n(t_j)} = 1/n(T_n) \left[\frac{(U_j)}{C+j/n} \right]$$

Since $(1/n(T_n))$ is a constant determined from the discrete sample, to maximize $1/C_n(t_j)$ is to maximize $(U_j/(C+j/n))$.

Moreover,

$$\frac{1}{C_n(t_j)} \text{ is proportional to } \frac{1}{1/n(T_n)(C_n(t_j))} \text{ which is}$$

equal to the slope of any line passing through the point $(-c,0)$ and some point on the TTT-plot (Figure 3-3). Recall from earlier discussion that C is a calculated, fixed, scaled value for cost, and that

$$\frac{1}{(C_n(t_j))} \text{ is proportional to } \frac{U_j}{C+j/n} .$$

So to maximize $(1/C_n(t_j))$ is to maximize $(U_j/C+j/n)$ and is to maximize slope $[1/(1/n(T_n))(C_n(t_j))]$. More specifically (refer to Figure 3-4), in order to maximize

$$\frac{U_j}{C+j/n}$$

U_j in the numerator must be made as large as possible (Y-axis on the graph) and j/n in the denominator must be made as small as possible (X-axis on the graph). Cost C in the denominator is a fixed value. By constructing the line through the point $(-c,0)$ tangent to the TTT-plot, the reciprocal $[C_n(t_j)]^{-1}$ of the objective function is maximized

and the objective function $C_n(t_j)$ is minimized. The value j_0/n is the abscissa of the tangent point and j_0 denotes the index of the optimal age replacement interval.

Using earlier cost and TTT-plot examples, a graphical solution for an optimal replacement interval is in Figure 3-4. For this example, the abscissa of the tangent point is $j_0/n = 3/10$. Hence, the optimal index, j_0 , for the replacement interval is 3. Referring to Table 3-1, the value of t_i (observed time) for the third interval is 27.9 hours. The optimal replacement interval for this example is 27.9 hours. Again, the preciseness of this estimate improves with larger samples. It becomes evident that a finite replacement interval can only be obtained with an IFR distribution since a tangent drawn to a DFR or exponential distribution results in an infinite interval. The decision in the latter two cases would be not to replace.

Sensitivity Analysis

Though Bergman's method is based on calculation of a fixed cost C , a sensitivity analysis on cost can be performed.

A researcher may consider a range of values for C , for example, $c \pm e$, where c is an estimate of cost and e represents error within a specified interval. By locating the points $(-c, 0)$, $(-(c-e), 0)$, $(-(c+e), 0)$ and drawing lines through these points tangent to the TTT-plot, a range is

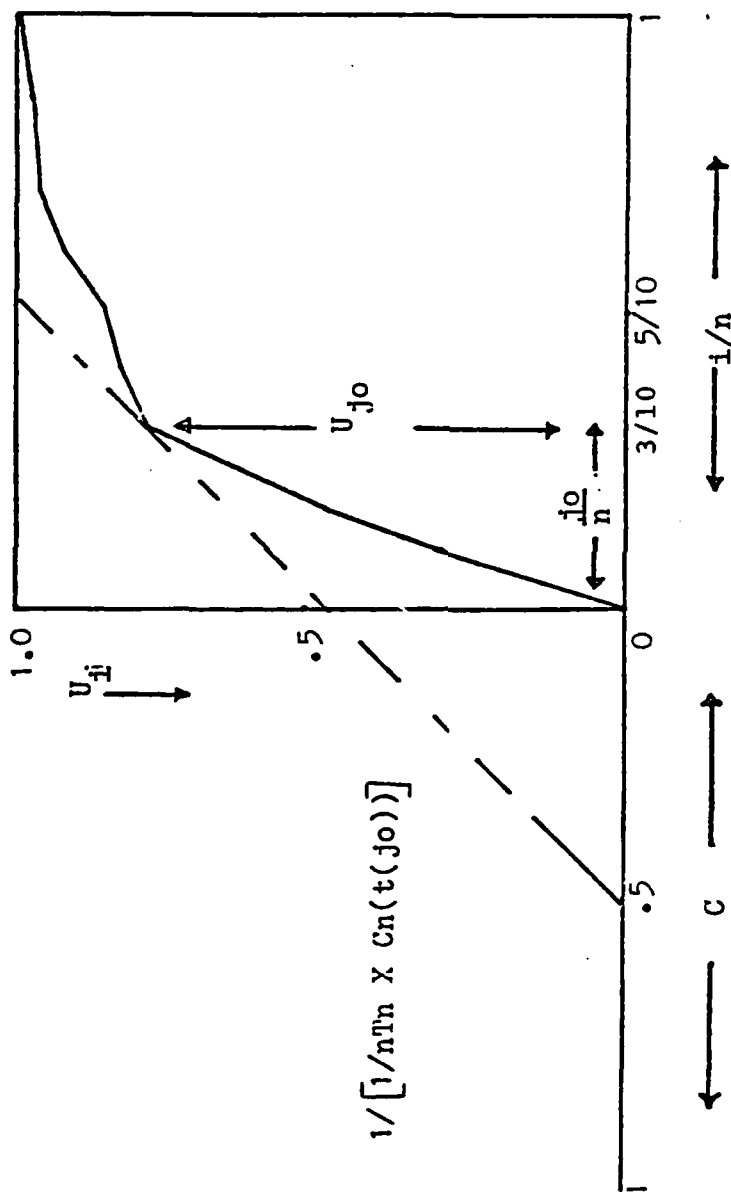


Fig. 3-4. Graphical Solution

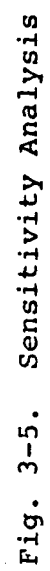
constructed about the optimal replacement interval index ($j_1 \geq j_0 \geq j_2$) shown in Figure 3-5. In this example, $j_1 = j_0 = j_2$.

To illustrate further, for an IFR distribution, if $(-(c+e), 0)$ is close to $(0, 0)$, then the optimal index, j , will be small. This suggests that units should be replaced more often when the difference between cost of replacement and cost of failure is large (c is small). The difference then, must grow smaller as $(-(c-e), 0)$ moves away from the origin. But the effect of cost on changes in the index j is also dependent upon the shape of the TTT-plot. Figure 3-6 shows that as an IFR distribution becomes more concave, the optimal index j becomes less sensitive to cost. As an IFR distribution becomes less concave, the optimal replacement interval becomes more sensitive to cost.

Performing sensitivity analysis with actual data requires collecting cost data as described in a later section for each in-service failure used in this study. The data will be analyzed using the Statistical Package for the Social Sciences (SPSS) condscriptive computer routine to identify the cost estimates from the sample. The objective of the analysis is to examine the effects of changes in cost C with regard to the index j for the optimal replacement interval.

The Sample

Selection of a piece of equipment to use was a difficult choice. The KT-73 Inertial Measurement Unit



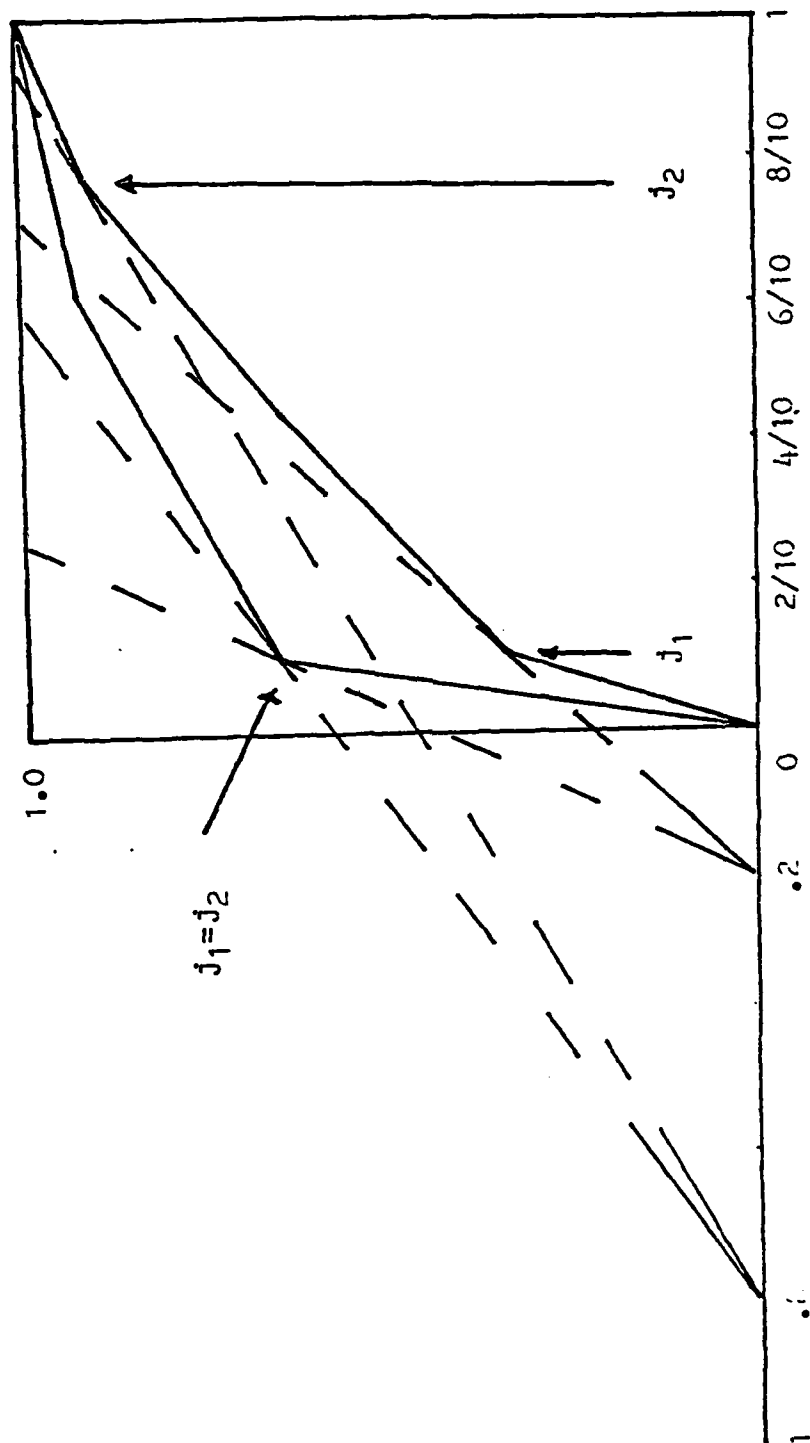


Fig. 3-6. Effects of Shape of Failure Curve on Sensitivity

used on the A-7D aircraft was chosen based on the following considerations:

Consideration A: In Chapter I, attention was given to expectations concerning available cost data. This study requires data for cost of replacement and cost of in-service failure. Since the cost to remove and replace a KT-73 IMU from an aircraft would be the same for both failure and non-failure, this cost is ignored.

The cost of in-service failure must be the sum of the trouble-shooting costs, the cost of transportation to and from depot, and the cost of repair. Since the units are hermetically sealed, repair is made only at the Aerospace Guidance and Metrology Center (AGMC). Thus, repair costs can be retrieved from a single source. Trouble-shooting costs are the costs incurred on the flight line to identify the IMU as having failed.

The cost of replacement must include the cost to transport a unit to and from depot and the cost to renew a nonfailed unit which is removed after a specified interval of time, presumably before failure. This entails repair or replacement of subcomponents from the unit which are approaching failure, thus, restoring the unit to a "good-as-new" condition (renewal). Costs which could be included are labor, materials, laboratory testing, setup costs and opportunity costs.

Consideration B: An in-service failure of the unit must not cause damage to other equipment in the system since this would create an additional variable cost of failure.

Consideration C: The unit must not be safety-critical.

Consideration D: The unit must fail often enough to provide adequate sample failure data.

Consideration E: The units must be traceable by some means of identification and field operating times specified so that failure cycles can be established.

The population of elements for this research study includes all KT-73 Inertial Measurement Units purchased by the Air Force and used on the A-7D aircraft. The sample includes all serial-numbered units beginning with an alpha prefix of "AF" ordered by the Air Force as spares prior to 19 April 1978. The purpose in limiting the sample space is to avoid the complications involving truncation of data. Truncation occurs when units which are not accounted for are removed from the sample. This destroys the validity of the life test.

Cost data for KT-73 in-service failures is available as a cost to repair through the AGMC Resources Division and is added to a cost of trouble-shooting and a cost of transportation, which are available through the K051 Maintenance Data Collection System. The cost to repair will be provided

by AGMC as an actual cost to repair based on averages for each fiscal year. This same cost to repair and cost of transportation will represent the cost of replacement so that the difference, k , will be the cost of trouble-shooting.

In-service failure of the unit does not cause damage to other equipment, and the unit is not critical to safe operation of the aircraft. Failure does occur often enough to provide adequate data, and units can be traced by serial number, cycle number, and field operating hours. A functional description of the KT-73 IMU is contained in Appendix A.

While Bergman's method may be used to analyze any maintenance item where the objective is to minimize cost, inferences made from this study are applicable only to the sample space.

Data Collection

Using data collection methods of Crowe and Loman (11:31-38), actual failure data for the KT-73 units will be collected from the G078C Maintenance Data Collection System.

Data from the G078C includes an elapsed time indicator, a cycle number, and an identification serial number. The elapsed time indicator ensures that the time a unit is awaiting repair and in supply channels is not added to the operating time of the units. The identification serial number is necessary to identify the failure cycles associated with a particular unit. A failure cycle is

defined as the operating time of a unit between renewal and failure.

Using both the "Aircraft Listing" and the "Field Operating Hours (FOH) by Cycle-Quarterly" G078C reports, failure Cycle 1 for each serial number included in the sample is identified. The field operating hours for each unit in Cycle 1 is then recorded and the times ordered from the smallest to largest. This can be accomplished through a simple FORTRAN program. The failure times are transferred to a data tape for use in calculating values for the TTT-plot (Figure 3-1).

According to MIL-STD-785B, Requirements for Military Programs (for Systems and Equipment/Development and Production); MIL-STD-781B, Reliability Tests: Exponential Distribution; and MIL-STD-756A, Reliability Prediction, the military services apply the basic assumption that failures are exponentially distributed; and, in fact, MIL-STD-785B permits a contractor to assume that equipment failures follow an exponential distribution whenever the standard is specified in the contract. The Computer Monitored Inspection Program uses this assumption (17:30). Herein lies one of the advantages of using the TTT-plot to analyze failure data. The TTT-plot method assumes that the life time distribution is unknown and analysis is based purely on observational data.

Since some units are expected to survive for a long period of time (calendar years), only old spares buys coded by "AF" serial numbers for the KT-73 IMU will be collected from the G078C Data Collection System.

The sample will be limited to those KT-73 IMU spares ordered by the Air Force prior to 19 April 1978 to ensure that a record of at least one failure for each unit has been recorded or that the unit is accounted for. The cutoff date is a convenient point between procurement packages in which large quantities of spares were ordered. A unit can be accounted for as not having been operated (on a supply shelf), discarded, or lost prior to normal failure (aircraft attrition). Units which are accounted for can be removed from the sample without bias. The period of time from which the data is drawn will depend upon the time the last unit in the sample fails. Conclusions from this study are limited to the data window.

Part of the cost of replacement is provided by AGMC and is the actual average cost to repair a unit for each fiscal year. Transportation costs are added to the cost to repair to arrive at the total cost of replacement, C_0 . The cost to repair is obtained from data collected by the Resources Division (MAW) at AGMC in terms of dollar amount and is presented as an average actual cost to repair by fiscal year. Transportation costs are provided by the K051 datasystem at Headquarters AFLC. Data is extracted by the

Mission-Design-Series (MDS) of A-7D and by Work Unit Code (WUC) 73FAO for the KT-73 IMU. Under the WUC, a transportation cost in terms of dollar amount is recorded.

The cost of in-service failure, $C_0 + k$, will consist of three parts: (1) the cost to repair, (2) the cost of transportation to and from depot, and (3) trouble-shooting cost. The preceding paragraph described how values for C_0 (cost to repair plus cost of transportation) are found. The remaining element, trouble-shooting cost, is provided by the K051 data system under the same MDS, WUC and format as transportation cost. However, trouble-shooting costs are listed as quarterly totals under a separate column labeled "field maintenance" (base labor).

These three costs (repair, transportation, trouble-shooting) cannot be directly matched to the serial-numbered units in the sample, but they are presented as annual averages (for repair), and quarterly totals (for transportation and trouble-shooting), the latter of which can be summed over each fiscal year and averaged using the number of units repaired for each fiscal year, as provided by AGMC. This limitation was discussed in Chapter I.

To arrive at values for k , the difference between the cost of replacement and the cost of failure, C_0 is subtracted from $C_0 + k$ for each fiscal year. The value of " k " in this study is the cost to trouble-shoot. Dividing each C_0 by each k , then, provides a range of cost values,

standardized to units of k dollars, which can be used to calculate an expected value for cost, C. The necessary calculations can be accomplished by a simple FORTRAN program.

The validity of the TTT-plot and graphical solution are dependent on the accuracy of the data collected from the G078C and K051 files. Limitations in this area were addressed in Chapter I. Additionally, a consistent maintenance policy must be assumed, and care will be taken to ensure that either none or all of the KT-73 units included in the sample have undergone modification.

Answering the Research Question

Before proceeding to the actual experiment, the research question should be readdressed within the context of the methodology.

The Research Question asks if Bergman's method can be applied in determining an optimal maintenance task interval based on the objective of minimizing total long-run average cost per unit time using actual field data. An optimal maintenance interval can be determined for the item used in this study by collecting data, as discussed in the previous section, for the cost of replacement and cost of failure, and by collecting failure data for the item. Based on the cost data, a value for C can be calculated and plotted. The observed failures collected from the G078C can be scaled and a TTT-plot constructed. Using Bergman's graphical technique, a tangent can be drawn from the point $(-c, 0)$ to

the failure curve, and the index of the optimal replacement interval can be located at the abscissa (j_0/n). If the following specific criteria are met, the research question can be answered in the affirmative.

Must know:

1. Cost of replacement
2. Cost of failure
3. Time from renewal to failure (cycle) for all units in the sample

Must have:

A large sample of life times (greater than 30), since the estimate of the optimal interval improves with larger samples.

Must be able to:

1. Standardize cost of replacement and cost of failure to "k" units of dollars
2. Scale observed life times to Bergman's TTT-plot
3. Construct a graph of the scaled empirical life distribution
4. Construct a tangent to the failure curve with the greatest slope passing through the point plotted for replacement cost
5. Identify the index for the optimal interval using Bergman's graphical technique

If the research question can be answered in the affirmative, there are two secondary questions. Secondary Question "a" asks if the calculated interval for the units tested compares with the existing interval for the item. Since the KT-73 IMU has never had a maintenance interval assigned to it, its current interval is infinite. This study would recommend an infinite interval (fly-to-failure) if the empirical life distribution constructed on the TTT-plot from actual failure data is a 45-degree line (exponential) or convex (DFR). Figure 3-3 illustrates these possibilities. If the following required knowledge and procedures can be satisfied, secondary question "a" can be evaluated.

1. Know the current interval
2. Identify the distribution of observed failure data
3. Identify the index for the optimal interval using Bergman's graphical technique
4. Compare the current and calculated optimal intervals
5. Explain or reconcile differences, if any, between the current and calculated optimal intervals

Secondary Question "b" asks how sensitive the calculated optimal interval is to the uncertainty of cost. Based on individual cost data collected, a range of values for "C" can be calculated and analyzed using the Statistical Package for the Social Sciences (SPSS) Condescriptive

computer program to identify the mean and standard deviation for C. Using values for C of plus and minus a given standard deviation from the mean, new tangents can be drawn to the failure curve and observations can be made concerning the effects of changes in C on the optimal replacement interval index. If the following required procedures can be satisfied, secondary question "b" can be evaluated.

1. Identify the mean and standard deviation of standardized cost values
2. Designate values for "C" above and below the mean, based on the mean and standard deviation
3. Identify the index for the optimal interval using Bergman's graphical technique for new values of "C," based on the standard deviation
4. Draw conclusions about the sensitivity of the optimal interval to uncertainty in cost

CHAPTER IV

APPLICATION AND ANALYSIS

Demonstrating Bergman's graphical method to determine an optimal maintenance task interval for an item in Air Force inventory requires application of the methodology described in Chapter III.

The Failure Data

Failure data for all KT-73 Inertial Measurement Units were collected for all units with serial numbers coded with an alpha prefix of "AF" ordered prior to 19 April 1978. This includes data on units coded AFORSSG, AFOTST1 and AF00001 through AF00094 for the first failure cycle (acquisition to first failure). The data was retrieved by cross-referencing both the "Aircraft Listing" and the "Field Operating Hours (FOH) by Cycle-Quarterly" reports from the G078C Data Collection System. Excerpts containing data from these reports are contained in Appendix B. Table 4-1 lists the units in the sample by serial number and corresponding times to failure for Cycle 1. The times to failure are listed in G078C reports under Cycle 1 of each serial number and denoted by "ETI IN," the elapsed time indicator reading (actual operating hours) upon arrival at AGMC. There are

TABLE 4-1

TIMES TO FAILURE BY SERIAL NUMBER

AFPRSSG	0855	AF00044	0285
AFOTST1	1111	AF00045	0426
AF00001	0099	AF00046	0490
AF00002	0229	AF00047	0180
AF00003	0615	AF00048	0211
AF00004	0127	AF00049	0161
AF00005	0121	AF00050	2764
AF00006	0853	AF00051	0434
AF00007	0349	AF00052	0150
AF00008	0487	AF00053	0109
AF00009	0558	AF00054	1001
AF00010	0852	AF00055	3007
AF00011	0260	AF00056	0183
AF00012	0181	AF00057	0217
AF00013	Attrited	AF00058	0701
AF00014	0932	AF00059	0240
AF00015	1837	AF00060	0164
AF00016	0182	AF00061	0101
AF00017	0508	AF00062	0565
AF00018	0107	AF00063	0120
AF00019	Attrited	AF00064	0222
AF00020	0498	AF00065	0122
AF00021	0492	AF00066	0299
AF00022	1081	AF00067	0212
AF00023	1408	AF00068	0377
AF00024	1099	AF00069	Attrited
AF00025	0828	AF00070	Attrited
AF00026	0164	AF00071	0129
AF00027	0388	AF00072	Attrited
AF00028	0414	AF00073	0645
AF00029	0417	AF00074	0122
AF00030	0103	AF00075	0764
AF00031	4126	AF00076	Attrited
AF00032	0334	AF00077	0292
AF00033	0109	AF00078	0365
AF00034	0153	AF00079	0454
AF00035	0163	AF00080	0897
AF00036	0093	AF00081	2132
AF00037	0483	AF00082	0347
AF00038	0414	AF00083	1081
AF00039	0451	AF00084	0873
AF00040	0095	AF00085	0220
AF00041	2045	AF00086	Attrited
AF00042	0254	AF00087	0332
AF00043	0141	AF00088	0163

TABLE 4-1 -Continued

AF00089	0814	AF00092	0154
AF00090	0436	AF00093	1765
AF00091	0121	AF00094	1560

eighty-nine units in the sample and times to failure were recorded on a raw data file called "TAPE 11" (Figure 4-1).

During collection of the failure data, it was noted that seven serial numbers could not be located: AF00013, AF00019, AF00069, AF00070, AF00072, AF00076 and AF00086. According to information received from AGMC, the KT-73 IMU Item Manager and Singer-Kearfott (manufacturer) any units that are lost to the system, that is, lost, stolen or demolished in an aircraft accident, are no longer tracked and the serial numbers are dropped from the rolls (2;10;16). Since the units contained in the sample used for this study are among the oldest spares buys made by the Air Force (circa 1970), the seven units for which serial numbers are missing are said to have attrited (2;10;16). A zero condemnation rate for the KT-73 IMU makes this the only reasonable conclusion. Hence, the seven units were removed from the sample without bias.

Total Time on Test-plot

Once the raw data was recorded on TAPE 11, it was necessary to order the failure times from smallest to largest. This was accomplished using the simple FORTRAN

130=0655	420=4126	700=0121
110=1111	410=0334	710=4565
120=0679	420=0109	720=0128
130=0229	430=0153	730=0222
140=0615	440=0163	740=0122
150=0127	450=0093	750=0299
160=0121	460=0463	760=0212
170=0253	470=0414	770=0377
180=0349	480=0451	780=0129
190=0407	490=0095	790=0645
200=0556	500=2345	800=0122
210=0652	510=0254	810=0764
220=0240	520=0141	820=0292
230=0161	530=0205	830=0365
240=0932	540=0426	840=0454
250=1837	550=0490	850=0097
260=0102	560=0160	860=2132
270=0506	570=0211	870=0347
280=0107	580=0161	880=1001
290=0498	590=2764	890=0070
300=0492	600=0434	900=0220
310=1001	610=0150	910=0332
320=1408	620=0107	920=0163
330=1399	630=1001	930=0014
340=0020	640=0007	940=0436
350=0164	650=0103	950=0121
360=0503	660=0217	960=0154
370=0414	670=0701	970=1765
380=0417	680=0240	980=1563
390=0103	690=0164	..

Fig. 4-1. TAPE 11: Raw Failure Data

program shown in Figure 4-2. The output, TAPE 12, from the program contains eighty-nine ordered failure times (Figure 4-3).

Having ordered the observed life time, $t_{(i)}$, the times were scaled to the total time on test, T_i , denoted by U_i . This was accomplished by inputting TAPE 12 to the FORTRAN program illustrated in Figure 4-4. The output of the program is shown in Table 4-2 which contains the observation number (i); the observed life times ($t_{(i)}$); the total time on test (T_i); and the scaled total time on test (U_i). The program also outputs a data file, TAPE 13 (Figure 4-5), containing all of the calculated U_i 's.

Using Table 4-2, a Total Time on Test-plot was constructed for the eighty-nine observations in the sample. As in the example of Chapter III, Figure 4-6 illustrates the TTT-plot for the KT-73 IMUs used in this study.

An examination of the empirical life distribution shown on the TTT-plot for the eighty-nine observations indicates a failure curve which is slightly DFR (decreasing failure rate). Since the curve represents a plot of observed data, it is not smooth, but it would become smoother with larger samples. Most notable is the immediate leap from 0 to .16 which represents the smallest observed time to failure, 93 hours. Superimposed over the TTT-plot is an assumed theoretical exponential failure curve. The theoretical distribution is derived from consistently large historical sampling and is a perfectly smooth 45-degree slope.


```

120=    PROGRAM ORDER
110=C
120=    REAL T(89),TIME(89),T1(89)
130=    INTEGER I,J,X
140=C
150=C    ORDER FAILURE DATA
160=C
170=    DATA TIME/89*8.8/
180=    READ(11,*) (T(X),X=1,89)
190=C
200=    DO 10 I=1,89
210=        J=I
220=        DO 20 J=1,89
230=            TIME(I)=MAX(TIME(I),T(J))
240=20    CONTINUE
250=        X=I
260=        DO 30 X=1,89
270=            IF (T(X).EQ.TIME(I)) THEN
280=                T(X)=8.8
290=                GO TO 10
300=            END IF
310=30    CONTINUE
320=10    CONTINUE
330=        DO 40 I=1,89
340=            J=90-I
350=            T1(J)=TIME(I)
360=40    CONTINUE
370=        DO 50 I=1,89
380=            WRITE(12,')( " ",F8.1)'T1(I)
390=50    CONTINUE
400=C
410=    RETURN
420=    END

```

Fig. 4-2. Program to Order Failure Data

100=	93.0	400=	217.0	700=	509.0
110=	95.0	410=	222.0	710=	555.0
120=	99.0	420=	222.0	720=	565.0
130=	101.0	430=	229.0	730=	615.0
140=	103.0	440=	240.0	740=	645.0
150=	107.0	450=	254.0	750=	701.0
160=	109.0	460=	260.0	760=	764.0
170=	109.0	470=	255.0	770=	814.0
180=	120.0	480=	292.0	780=	828.0
190=	121.0	490=	299.0	790=	852.0
200=	121.0	500=	332.0	800=	853.0
210=	122.0	510=	334.0	810=	855.0
220=	122.0	520=	347.0	820=	873.0
230=	127.0	530=	349.0	830=	897.0
240=	129.0	540=	365.0	840=	932.0
250=	141.0	550=	377.0	850=	1001.0
260=	150.0	560=	388.0	860=	1001.0
270=	153.0	570=	414.0	870=	1001.0
280=	154.0	580=	414.0	880=	1099.0
290=	161.0	590=	417.0	890=	1111.0
300=	163.0	600=	426.0	900=	1408.0
310=	163.0	610=	434.0	910=	1560.0
320=	164.0	620=	436.0	920=	1765.0
330=	164.0	630=	451.0	930=	1837.0
340=	168.0	640=	454.0	940=	2645.0
350=	181.0	650=	463.0	950=	2132.0
360=	182.0	660=	487.0	960=	2764.0
370=	183.0	670=	490.0	970=	3607.0
380=	211.0	680=	492.0	980=	4126.0
390=	212.0	690=	496.0	..	

Fig. 4-3. TAPE 12: Ordered Failure Data

```

100=      PROGRAM TTTPLOT
110=C
120=      REAL Y(90),T(90),U(90)
130=      INTEGER I,J,K,N,X
140=C
150=C      DEFINITIONS: TAPE12 CONTAINS ALL
160=C      OBSERVATIONS SMALL T(I)
170=C      N=TOTAL NUMBER OF OBSERVATIONS PLUS ONE
180=C      Y(I)=CAPITAL T(I), U(I)=U(I), I,J,K,X
190=C      ARE INDEXES
200=C
210=      N=90
220=      K=1
230=C
240=      DATA Y,T,U/270*0.0/
250=C
260=      READ(12,*) (T(X),X=2,N)
270=      PRINT '(1X,10X,"T",6X,"OBSERV",5X,"TOTAL",5X,"SCALED")'
280=      PRINT '(1X,12X,"K0.",6X,"TIME",6X,"TIME",7X,"TIME",/)'
290=C
300=      DO 10 I=2,N
310=          J=I-1
320=          Y(I)=(N-J)*(T(I)-T(K))+Y(K)
330=          K=K+1
340=10      CONTINUE
350=C
360=      J=1
370=      DO 20 I=2,N
380=          U(I)=Y(I)/Y(N)
390=          PRINT 40,J,T(I),Y(I),U(I)
400=          WRITE(13,1) (" ",F9.6)'U(I)
410=          J=J+1
420=20      CONTINUE
430=C
440=40      FORMAT(1X,12X,10,5X,F6.1,3X,F9.1,5X,F6.4)
450=      RETURN
460=      END

```

Fig. 4-4. Program to Scale Total Time on Test

TABLE 4-2
SCALED TIMES TO FAILURE

I NO.	OBSERV TIME	TOTAL TIME	SCALED TIME				
				46	377.0	25370.0	.4763
1	93.0	8277.0	.1579	47	380.0	25346.0	.4673
2	95.0	8453.0	.1612	48	414.0	26638.0	.5381
3	99.0	8531.0	.1679	49	414.0	26638.0	.5381
4	101.0	8970.0	.1712	50	417.0	26753.0	.5194
5	103.0	9143.0	.1744	51	426.0	27189.0	.5171
6	107.0	9479.0	.1803	52	434.0	27413.0	.5229
7	109.0	9645.0	.1840	53	436.0	27487.0	.5243
8	109.0	9645.0	.1840	54	451.0	28227.0	.5346
9	120.0	10536.0	.2010	55	454.0	28132.0	.5326
10	121.0	10616.0	.2025	56	463.0	29113.0	.5554
11	121.0	10616.0	.2025	57	487.0	29253.0	.5580
12	122.0	10694.0	.2040	58	490.0	29346.0	.5598
13	122.0	10694.0	.2040	59	492.0	29438.0	.5618
14	127.0	11074.0	.2112	60	498.0	29580.0	.5644
15	129.0	11224.0	.2141	61	508.0	29870.0	.5699
16	141.0	12112.0	.2310	62	558.0	31278.0	.5966
17	152.0	12769.0	.2436	63	563.0	31467.0	.6003
18	153.0	12935.0	.2477	64	615.0	32767.0	.6251
19	154.0	13056.0	.2491	65	645.0	33517.0	.6394
20	161.0	13546.0	.2564	66	701.0	34851.0	.6658
21	163.0	13684.0	.2610	67	764.0	36210.0	.6926
22	163.0	13684.0	.2610	68	814.0	37410.0	.7136
23	164.0	13751.0	.2623	69	828.0	37784.0	.7192
24	164.0	13751.0	.2623	70	852.0	38184.0	.7284
25	180.0	14791.0	.2821	71	853.0	38293.0	.7287
26	181.0	14855.0	.2834	72	855.0	38293.0	.7294
27	182.0	14918.0	.2846	73	873.0	38545.0	.7353
28	183.0	14988.0	.2858	74	897.0	38729.0	.7426
29	211.0	16688.0	.3163	75	932.0	39454.0	.7526
30	212.0	16748.0	.3195	76	1001.0	40428.0	.7710
31	217.0	17043.0	.3251	77	1031.0	41460.0	.7909
32	220.0	17217.0	.3284	78	1081.0	41460.0	.7909
33	222.0	17331.0	.3306	79	1099.0	41653.0	.7947
34	229.0	17723.0	.3381	80	1111.0	41778.0	.7969
35	240.0	18323.0	.3496	81	1402.0	44451.0	.8479
36	254.0	19084.0	.3640	82	1568.0	45667.0	.8711
37	263.0	19402.0	.3701	83	1765.0	47102.0	.8985
38	285.0	20732.0	.3949	84	1837.0	47504.0	.9067
39	292.0	21357.0	.4017	85	2045.0	48574.0	.9266
40	299.0	21489.0	.4034	86	2132.0	48922.0	.9332
41	302.0	22026.0	.4092	87	2764.0	50819.0	.9694
42	304.0	22122.0	.4111	88	3697.0	51234.0	.9787
43	347.0	23733.0	.4517	89	4126.0	52423.0	1.0000
44	349.0	23825.0	.4545				
45	365.0	24545.0	.4612				

100=	.157689	400=	.325105	700=	.569741
110=	.161246	410=	.328425	710=	.596647
120=	.167684	420=	.330599	720=	.630252
130=	.171165	430=	.335277	730=	.625053
140=	.174406	440=	.349618	740=	.639357
150=	.180818	450=	.364039	750=	.664994
160=	.180984	460=	.370185	760=	.692635
170=	.183984	470=	.394983	770=	.713618
180=	.200988	480=	.401713	780=	.719226
190=	.202587	490=	.426389	790=	.725363
200=	.202587	500=	.439235	800=	.728745
210=	.203994	510=	.441066	810=	.729432
220=	.203994	520=	.452721	820=	.735269
230=	.211243	530=	.454476	830=	.742594
240=	.214184	540=	.466211	840=	.752689
250=	.231844	550=	.478282	850=	.771836
260=	.243576	560=	.467385	860=	.790874
270=	.247687	570=	.508136	870=	.790874
280=	.249051	580=	.508136	880=	.794651
290=	.258398	590=	.518425	890=	.796748
300=	.261353	600=	.517120	900=	.847929
310=	.261830	610=	.522919	910=	.871125
320=	.262289	620=	.524531	920=	.856499
330=	.262289	630=	.534632	930=	.936737
340=	.280147	640=	.536635	940=	.926573
350=	.280349	650=	.555443	950=	.933216
360=	.284570	660=	.557961	960=	.969384
370=	.285752	670=	.559792	970=	.976654
380=	.310334	680=	.568975	980=	1.000000
390=	.319475	690=	.564489	..	

Fig. 4-5. TAPE 13: Calculated U_i 's

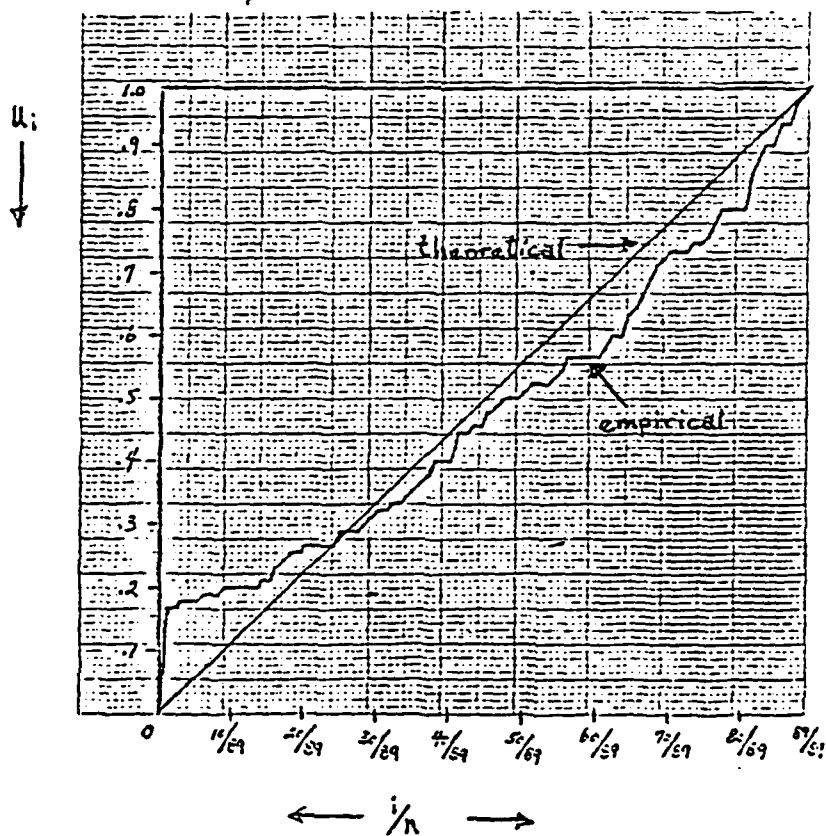


Fig. 4-6. Total Time on Test-plot

According to MIL-STD-756A and engineers at AGMC, a complex electronic component, such as the KT-73 IMU, when in steady state operation, is assumed to exhibit exponential failure characteristics (the flat portion of a typical bathtub curve).

Visually examining the two distributions, the difference in their shapes does not appear dramatic. While the assumed distribution exhibits a constant failure rate, the empirical distribution exhibits a slightly decreasing failure rate. The statistical significance of the difference was not analyzed. With Bergman's method, the empirical distribution can be visually recognized as a DFR, exponential or IFR (9:468).

Cost Data

To find the optimal replacement interval, requires balancing the cost of replacement (scheduled maintenance), C_0 , with the cost of failure (unscheduled maintenance), $C_0 + k$, where k represents the difference between cost of replacement and cost of failure.

The collection of cost data was influenced by the formats used by the data collection systems which contained the needed information. As explained in Chapters I and III, the cost of replacement includes the cost to repair and the cost of transporting units to and from depot. The cost of failure includes these costs plus the additional cost of trouble-shooting. Cost data was collected for the period

from FY 72 through FY 81 to generally coincide with the time period during which failures occurred for units in the sample. However, since the cost data collected for this period was in aggregated form, they represent the expected costs for the entire population of KT-73 IMUs repaired and processed through the system.

The cost to repair a unit at depot was provided by the AGMC Resources Division and represents an actual cost to repair based on averages for each fiscal year beginning with FY 81 and going back to FY 72. Table 4-3 contains average repair cost by fiscal year and total number of units repaired for each time period. It should be noted that AGMC provided separate averages for FY 76 (ending 30 June 1976) and for the transition quarter 76T (ending 30 September 1976). A single average for FY 76 was derived by multiplying the average cost per unit for FY 76 times four and adding the average cost per unit for 76T, then dividing by five.

TABLE 4-3
AVERAGE COST TO REPAIR KT-73 IMU

Period	Average Cost/ Unit	Total Units Repaired
FY 81	\$4350	312
FY 80	4053	358
FY 79	3378	358
FY 78	4104	335
FY 77	2873	360

TABLE 4-3—Continued

Period	Average Cost/ Unit	Total Units Repaired
FY 76	\$4138	489
FY 75	3126	447
FY 74	2967	502
FY 73	4005	344
FY 72	3203	73

Transportation costs were extracted from the K051 Maintenance Data Collection System as quarterly totals under "packing-shipping cost" for WUC 73FAO. The listing was found under the Logistic Support Cost Breakdown for the A7-D Aircraft. Copies of the microfiche files containing the data are contained in Appendix C. Cost data was only available as far back as the fourth quarter of FY 72, and not all of the information was available at Headquarters AFLC. Data for the second quarter of FY 79 was retrieved by telephone from the Sacramento Air Logistics Center. Table 4-4 contains the quarterly transportation cost totals for each quarter beginning with the fourth quarter of FY 81 and going back to include the fourth quarter of FY 72. Annual averages were then computed by summing the four quarterly totals in each fiscal year and dividing by the number of known units repaired by AGMC (Table 4-3) in the same year. For FY 76, an annual average was derived by summing the four quarterly totals for FY 76 and the quarterly total for 76T, then dividing by the number of units repaired

in FY 76 (which includes 76T). The average transportation cost per unit for FY 72 was derived by counting the number of units repaired by AGMC between the 183 and 274 days (fourth quarter) of FY 72 using the G078C reports and dividing that number into the fourth quarter total for FY 72.

TABLE 4-4
TROUBLE-SHOOTING AND TRANSPORTATION COSTS
QUARTERLY TOTALS

Period	Trouble-shooting	Transportation
4 FY 81	\$108367	\$2841
3 FY 81	91920	1527
2 FY 81	95520	1951
1 FY 81	105206	2071
4 FY 80	124926	2868
3 FY 80	132477	3134
2 FY 80	85000	4531
1 FY 80	65264	2822
4 FY 79	97117	5129
3 FY 79	69190	3505
2 FY 79	71969	2992
1 FY 79	94732	3932
4 FY 78	98908	5386
3 FY 78	72248	3896
2 FY 78	69022	2961
1 FY 78	63424	2546
4 FY 77	69613	3543
3 FY 77	66644	3769
2 FY 77	66932	2384
1 FY 77	64854	3154
FY 76T	88377	4313
4 FY 76	78458	5407
3 FY 76	75966	2877
2 FY 76	57687	2970
1 FY 76	75126	3942
4 FY 75	79169	3926
3 FY 75	89018	5700
2 FY 75	58926	3476
1 FY 75	76344	3669
4 FY 74	55584	3898
3 FY 74	43003	2711
2 FY 74	40731	2659

TABLE 4-4—Continued

Period	Trouble-shooting	Transportation
1 FY 74	\$ 44290	\$3173
4 FY 73	51740	3424
3 FY 73	47143	1930
2 FY 73	39361	1750
1 FY 73	41243	2249
4 FY 72	34127	814

Once annual averages were collected for the cost to repair and computed for the cost of transportation, these two costs were added for each corresponding fiscal year to produce annual averages for the cost of replacement, C_o , for FY 72 through FY 81.

The cost of failure includes the cost of replacement, C_o , plus an additional cost, k . For this study, the additional cost or difference, k , was defined as the cost to trouble-shoot a unit failure. Trouble-shooting costs, like transportation costs, were collected from the Logistic Support Cost Breakdown of the K051 MDC System (Appendix C). The quarterly totals are listed under "field maintenance cost" for WUC 73FAO. Annual average trouble-shooting costs per unit failure were derived in the same way that transportation costs were computed. Table 4-4 contains the quarterly trouble-shooting cost totals for the same time period that transportation costs were collected.

In order to facilitate Bergman's graphical method, the cost of replacement, C_o , must be standardized to units

of k dollars. Bergman refers to this standardized value as "C." To find C , the cost of replacement, C_0 , which includes the cost of repair and the cost of transportation, must be divided by the additional cost of failure, k . In this study, a value for C was calculated for each fiscal year, from FY 72 through FY 81.

The entire range of calculations necessary to arrive at values for C for each fiscal year were accomplished using a FORTRAN program (Figure 4-7). The program calculates annual values for C_0 , k and C . Data input included TAPE 20 and TAPE 21 which contained values transcribed from Tables 4-3 and 4-4, respectively (Figures 4-8 and 4-9). The output TAPE 22, displays ten values for C , one for each fiscal year (Figure 4-10).

Since Bergman requires a single fixed value for C , which represents an average long-term cost of replacement, a mean value for C based on the sample was required. Values for both the mean and standard deviation were found by subjecting TAPE 22 to the SPSS Condescriptive computer program. The program and results are contained in Figure 4-11.

Graphical Solution

Using the mean value of 5.206 for C , the point $(-c,0)$ was located and a tangent drawn to the failure curve. Figure 4-12 indicates that the tangent point is at the upper right most portion of the failure curve. The abscissa of the

```

100=  PROGRAM= COST
110=C
120=C  COMPUTE COST OF REPLACEMENT IN TERMS OF "K" DOLLARS
130=C  FOR GRAPHICAL ANALYSIS
140=C
150=  REAL CO(10),K(30),TRANS(30),C(10)
160=  INTEGER NREP(10),I,J
170=C
180=  DATA CO,K,TRANS,C,NREP/9648.8,10*0/
190=C
200=  READ(20,*) (CO(I),NREP(I),I=1,10)
210=  READ(21,*) (K(I),TRANS(I),I=1,30)
220=  J=1
230=C
240=  DO 10 I=1,10
250=      TRANS(I)=TRANS(J)
260=      IF (J.EQ.30) GO TO 50
270=      J=J+1
280=      TRANS(I)=TRANS(I)+TRANS(J)
290=      J=J+1
300=      TRANS(I)=TRANS(I)+TRANS(J)
310=      J=J+1
320=70  TRANS(I)=TRANS(I)+TRANS(J)
330=      J=J+1
340=      IF (J.EQ.25) GO TO 70
350=50  TRANS(I)=TRANS(I)/NREP(I)
360=10  CONTINUE
370=C
380=  J=1
390=  DO 20 I=1,10
400=      K(I)=K(J)
410=      IF (J.EQ.30) GO TO 60
420=      J=J+1
430=      K(I)=K(I)+K(J)
440=      J=J+1
450=      K(I)=K(I)+K(J)
460=      J=J+1
470=60  K(I)=K(I)+K(J)
480=      J=J+1
490=      IF (J.EQ.25) GO TO 60
500=60  K(I)=K(I)/NREP(I)
510=20  CONTINUE
520=C
530=  DO 30 I=1,10
540=      CO(I)=CO(I)+TRANS(I)
550=30  CONTINUE
560=C
570=  DO 40 I=1,10
580=      C(I)=CO(I)/K(I)
590=      WRITE(22,*) (" ",FS.2)'C(I)'
600=40  CONTINUE
610=C
620=  RETURN
630=  END
..

```

Fig. 4-7. Program to Calculate Cost "C"

<u>Cost</u>	<u>No.</u>	<u>FY</u>
100-4353	312	81
110-4253	358	80
120-3376	358	79
130-4194	335	78
140-2973	363	77
150-4138	489	76
160-3126	447	75
170-2967	502	74
180-4005	344	73
190-3293	73	72

..

Fig. 4-8. TAPE 20: Average Cost to Repair
and Total Number of Units Repaired

<u>Trouble-</u> <u>shooting</u>	<u>Trans</u>	<u>FY</u>
100=100067	2841	
110=91920	1527	81
120=95523	1951	
130=105206	2071	
140=124926	2068	
150=132477	3134	80
160=85000	4531	
170=65264	2022	
180=97117	5129	
190=69190	3505	79
200=71969	2692	
210=94732	3932	
220=98908	5386	
230=72248	3896	78
240=69022	2961	
250=60424	2546	
260=69613	3543	
270=66644	3769	77
280=66932	2304	
290=64854	3154	
300=80377	4313	76T
310=78458	5407	
320=75966	2877	76
330=57607	2970	
340=75126	3942	
350=79169	3926	
360=89018	5700	75
370=58926	3476	
380=76044	3669	
390=55584	3898	
400=43003	2711	74
410=43701	2659	
420=44290	3173	
430=51740	3424	
440=47143	1930	73
450=39061	1750	
460=41243	2249	
470=04127	814	72

Fig. 4-9. TAPE 21: Costs of Trouble-shooting and Transportation

<u>Cost</u>	<u>"C"</u>	<u>FY</u>
100=	3.41	81
110=	3.59	80
120=	3.68	79
130=	4.58	-78
140=	3.91	77
150=	5.44	76
160=	4.86	75
170=	8.18	74
180=	7.73	73
190=	6.60	72

..

Fig. 4-10. TAPE 22: Standardized Cost of Replacement "C"


```

RUN NAME      CON
VARIABLE LIST  C
VAR LABEL     C-COST OF REPLACEMENT/
INPUT FORMAT   FREEFIELD
INPUT MEDIUM  DISC
N OF CASES     10
CONDSCRIPTIVE  C
STATISTICS     ALL
READ INPUT DATA

```

00035500 CM NEEDED FOR CONDSCRIPTIVE

CON
2

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FILE - NAME (CREATED - 08/25/82)

VARIABLE C	COST OF REPLACEMENT			
MEAN	5.206	STD ERR	.564	STD DEV
VARIANCE	3.179	KURTOSIS	-1.048	SKEWNESS
MINIMUM	3.410	MAXIMUM	8.180	SUM
C.V. PCT	34.246	.95 C.I.	3.931	17

Fig. 4-11. SPSS Condscriptive Routine and Results

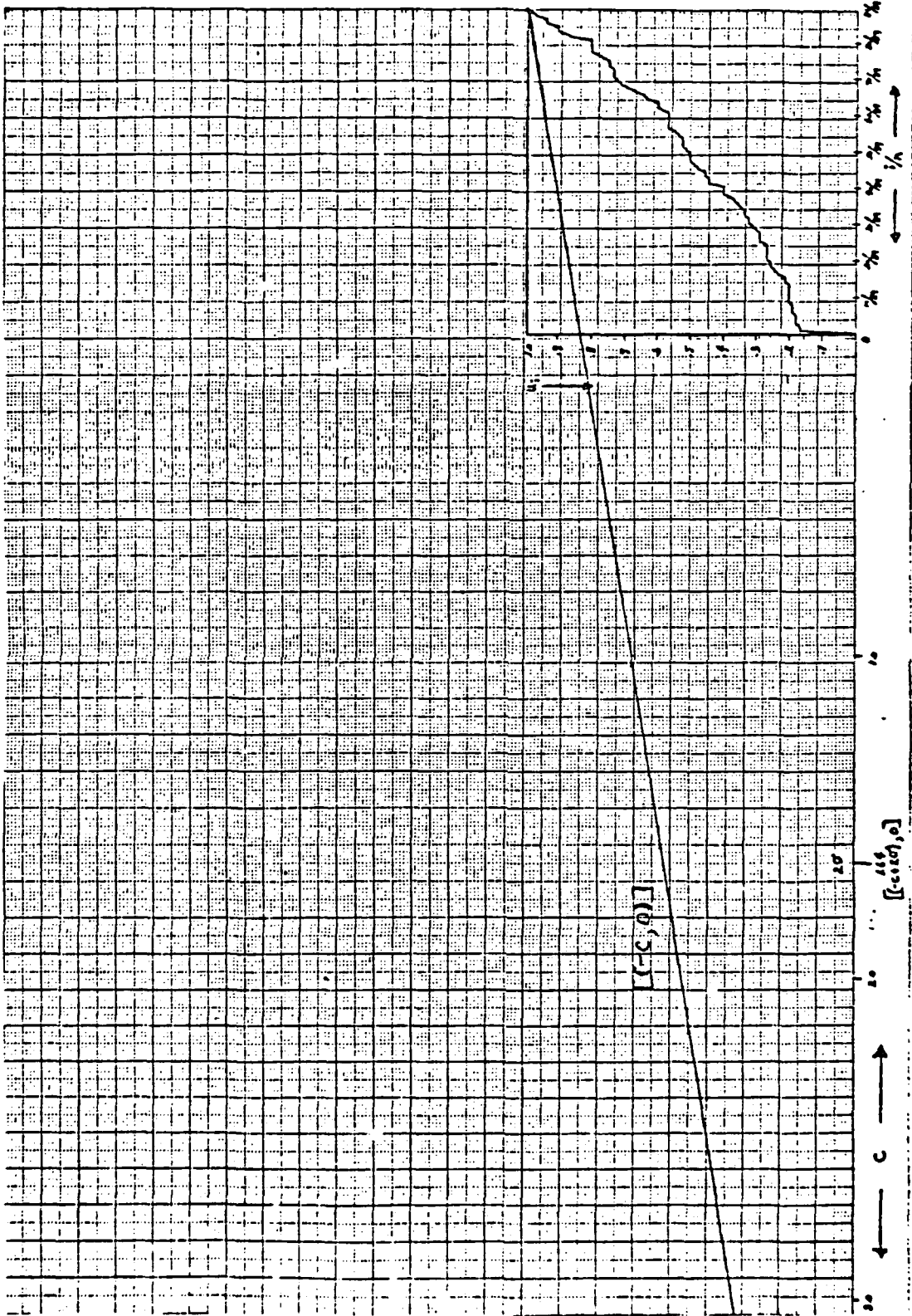


Fig. 4-12. Graphical Solution

AD-A123 025

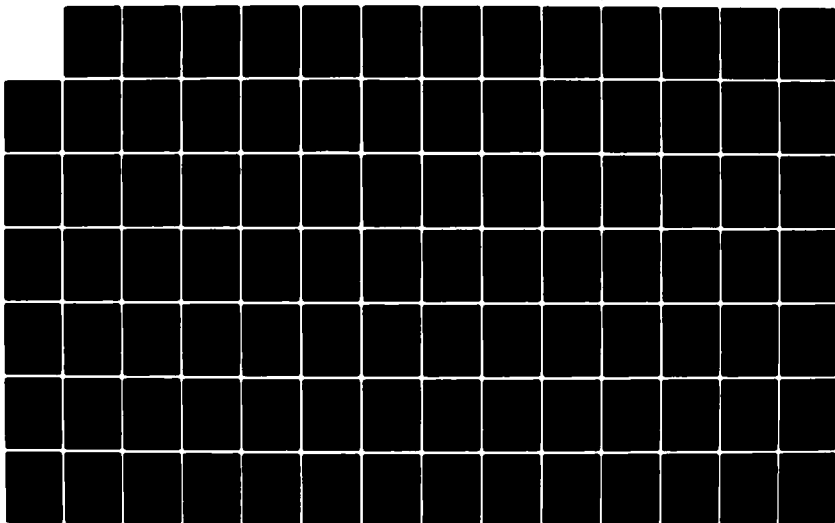
A STUDY TO DEMONSTRATE THE APPLICATION OF A GRAPHICAL
METHOD TO DETERMINE..(U) AIR FORCE INST OF TECH
WRIGHT-PATTERSON AFB OH SCHOOL OF SYST..

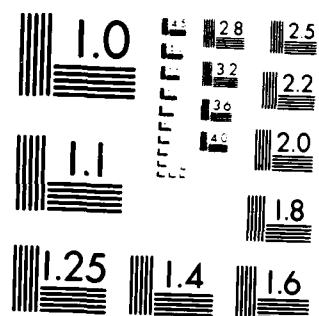
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NATIONAL BUREAU OF STANDARDS-1963-A

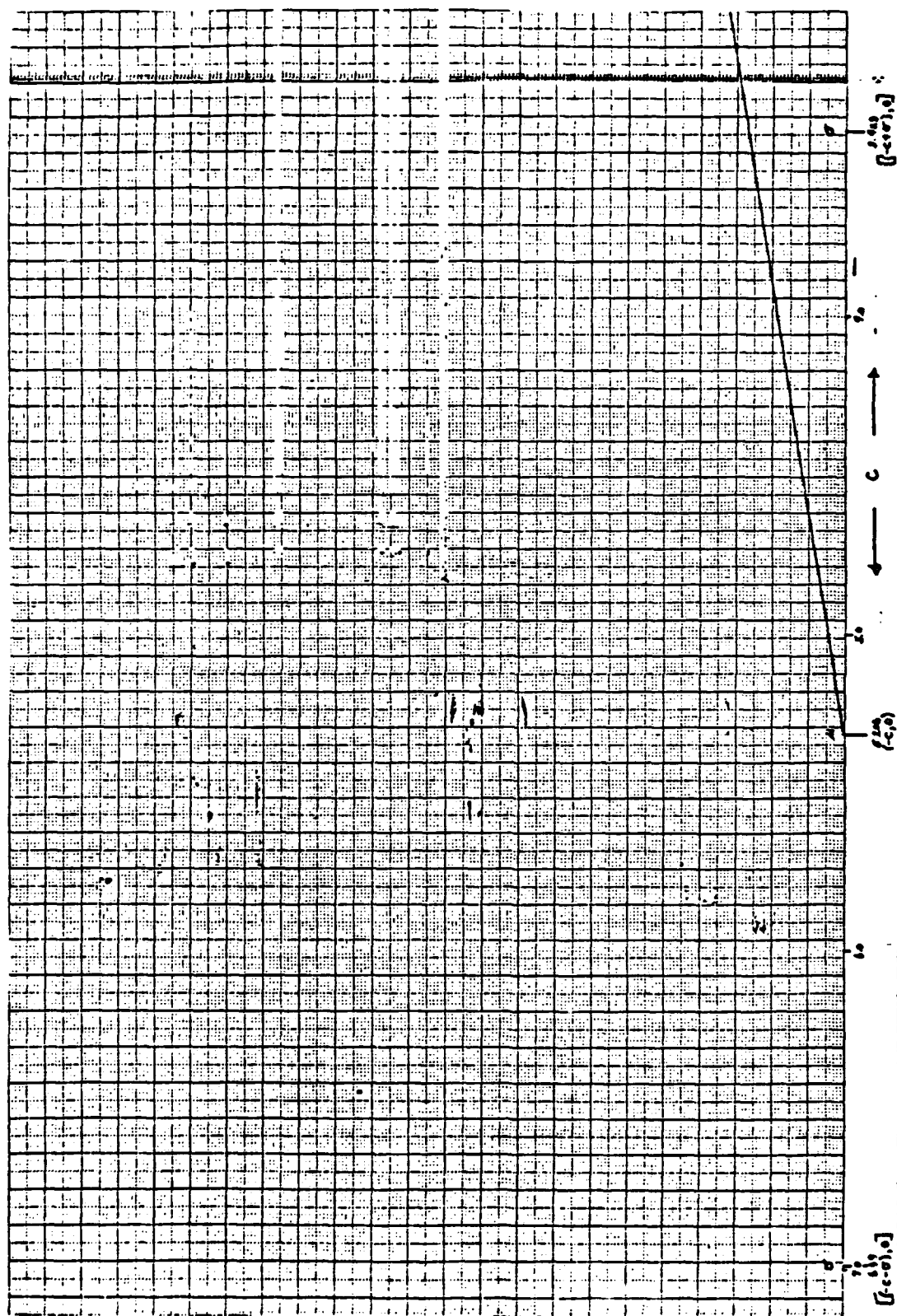


Fig. 4-12—Continued

tangent point is the value 89/89 or 1 and denotes the index of the optimal replacement interval, j_0 . In this case, the estimate of the optimal replacement interval was interpreted to be infinite. As explained in Chapter III, this conclusion could have been reached without having performed the graphical solution since, by definition, exponential and DFR curves yield infinite replacement intervals.

The current interval and the optimal interval found using Bergman's method are the same. They are both infinite, and the optimal maintenance policy for the KT-73 IMUs in the sample is to operate until failure.

Sensitivity Analysis

In Chapters I and III, a large portion of discussion was devoted to limitations regarding cost measurement and cost uncertainty. Cost estimation results in a degree of uncertainty, and Bergman's graphical method can be used to perform sensitivity analysis with respect to cost.

By constructing a range of values for cost, C , about the mean, new lines tangent to the failure curve can be drawn through these points and observations can be made to identify changes, if any, in the optimal replacement interval index, j_0 . In the last section, the mean value of 5.206 was used for C in finding the estimate of the optimal replacement index. The results of this study indicate that the replacement interval for the KT-73 IMU is infinite. Knowing this, it can be concluded at this point that the replacement

interval is totally insensitive to changes in cost, C. However, for the purpose of demonstrating the method, a sensitivity analysis was performed.

The degree of uncertainty of cost for this study is unknown, and the variability of cost in the sample may not reflect the true variability of the population of costs associated with the KT-73 IMU. The size of the sample of cost values (ten cases) preclude efficient analysis of the distribution of costs calculated in this study. Employing a rule from Chebyshev's theorem that applies to any sample of measurements, regardless of the shape of the frequency distribution, at least 75 percent of the observations are expected to fall within two standard deviations of the mean (13:149). Figure 4-11 shows the calculated standard deviation for the sample to be 1.783. Since the mean is 5.206, the two standard deviations from the mean are calculated as

$$\bar{X} \pm S = (3.42, 6.99)$$

$$\bar{X} \pm 2S = (1.64, 8.77)$$

These values (except 8.77) were plotted on the graph in Figure 4-13 and new lines drawn tangent to the failure curve. In the interest of conserving space, the point $(-8.77, 0)$, which represents two standard deviations above the mean, was not plotted. Also, since the point representing one standard deviation above the mean resulted in an

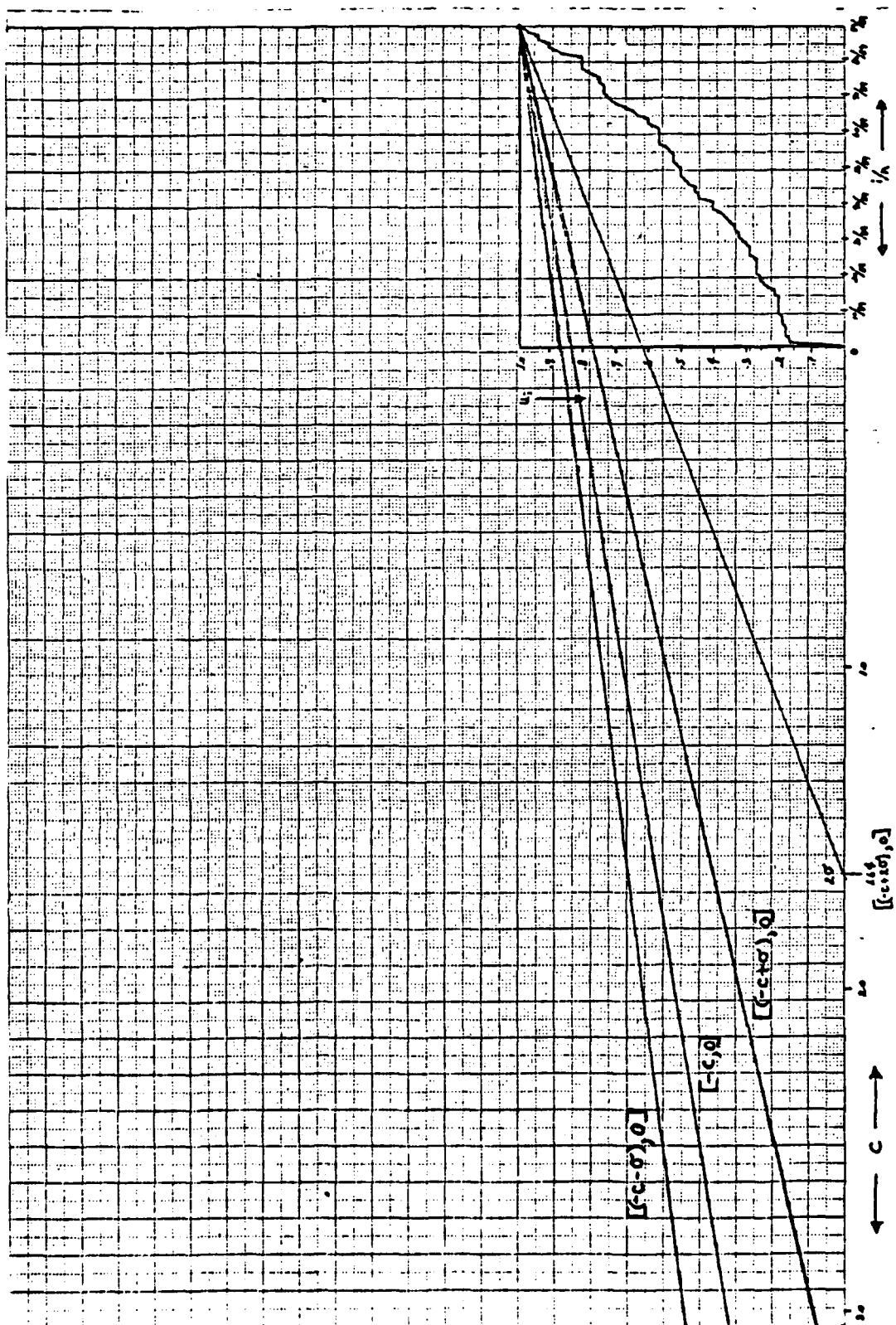


Fig. 4-13. Sensitivity Analysis

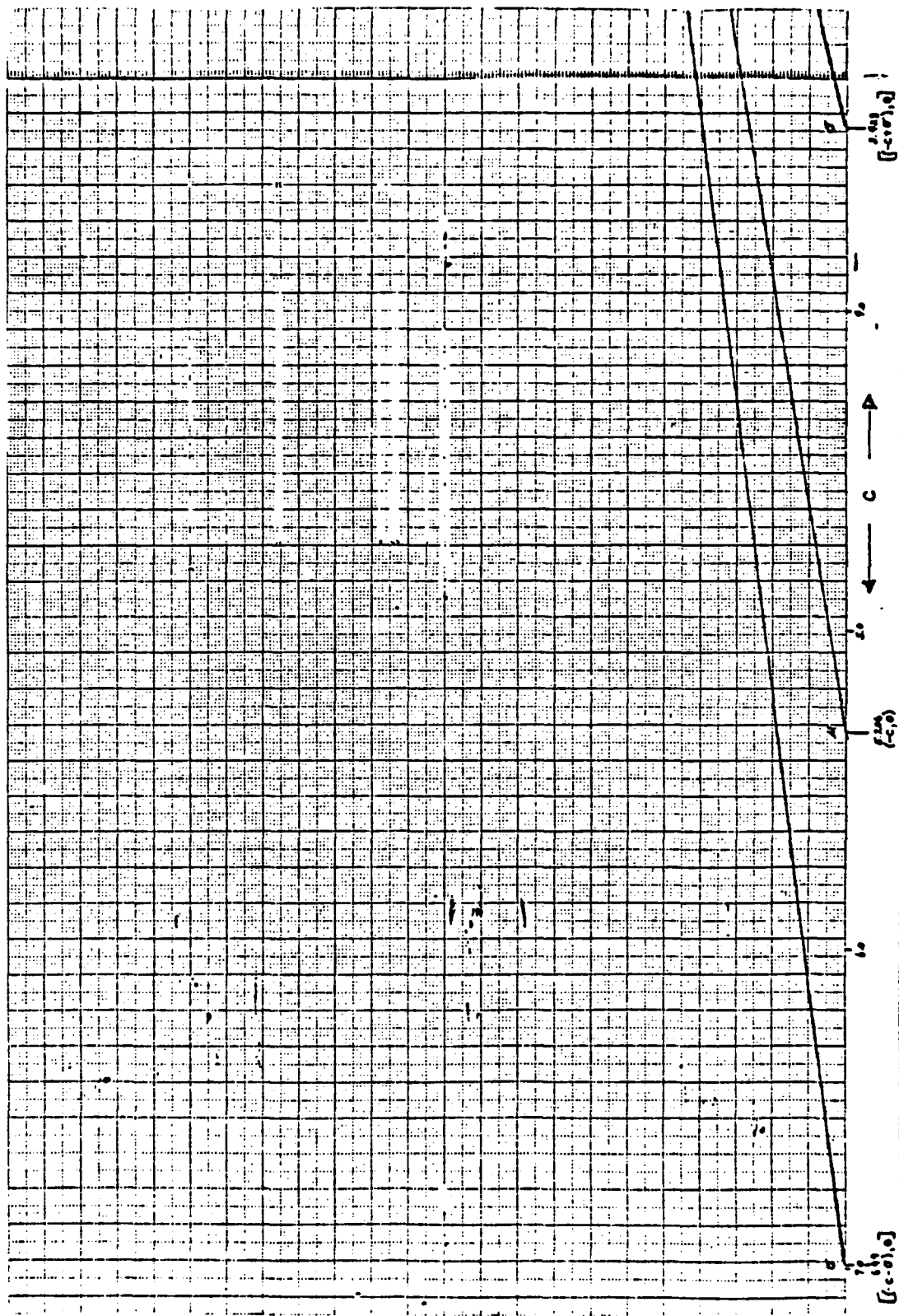


Fig. 4-13—Continued

infinite solution, it is known that any point beyond one standard deviation would produce an identical result given the failure curve for the units.

For this study, in each case in which a new line was drawn tangent to the failure curve from a new value for C , the solution was the same. In each case, the estimate of the optimal replacement interval was infinite resulting in a recommendation to operate the KT-73 IMU until failure. Hence, the optimal replacement interval is totally insensitive to changes in cost, C . Furthermore, it should be noted that all ten values for C contained in the sample fall within two standard deviations of the mean. This observation provides a "feel," as Bergman states it, for the confidence in the estimate of the optimal replacement interval.

Summary

The application and analysis of Bergman's method is summarized in light of the research question and the two secondary questions. In Chapter III, a set of criteria was established so that the degree to which the research answers these questions can be evaluated.

The research question asks if Bergman's method can be applied in determining an optimal maintenance task interval based on the objective of minimizing total long-run average cost per unit of time using actual field data. To answer the question, the cost of replacement, the cost of

failure and the time from renewal to failure (cycle) for all units in the sample, must first be known.

The cost of replacement, C_o , was defined as the sum of the cost to repair a unit at AGMC and the cost to transport a unit to and from the depot. Data was gathered from the AGMC Resources Division and the K051 MDC for the KT-73 IMU in the form of dollar amounts. The cost of failure, C_o+k , includes these costs plus the additional cost of trouble-shooting a failed unit. Data for trouble-shooting costs was also gathered from the K051 MDC for the KT-73 IMU in the form of dollar amounts. No attempt was made to quantify other cost factors, such as Not-Mission-Capable time or readiness. Adding these costs to the cost of failure would have resulted in a larger value for k and a smaller value for C . However, since the interval for the KT-73 IMU is totally insensitive to changes in cost, the results would have been the same if these additional costs had been added to k .

The times from renewal to failure were taken as Cycle 1 for all units in the sample. The data was gathered from the G078C reports by serial number and cycle number. Seven serial numbers in the original sample of ninety-six were said to have attrited and were removed from the sample without bias, leaving eighty-nine units for the study.

The second set of criteria which must be met to answer the research question is to have a large sample

(greater than 30). The sample of eighty-nine units meets this criterion.

The final set of criteria concerns procedures necessary to apply Bergman's method. If (1) the cost of replacement can be standardized to k units of dollars, (2) the observed life times can be scaled to Bergman's TTT-plot, (3) a graph of the scaled empirical life distribution can be constructed, (4) a tangent to the failure curve with the greatest slope passing through the point plotted for replacement cost can be drawn, and (5) the index for the optimal replacement interval can be identified using Bergman's graphical technique, then the research question can be answered in the affirmative.

Using a FORTRAN program, annual per unit averages for the cost of replacement and the additional cost of failure, k , were computed. The cost of replacement, C_0 , was then standardized to k units of dollars by dividing C_0 by k to arrive at values for C . The values for C were then analyzed for parameters and the mean value of 5.206 used to plot a point representing $(-c, 0)$. A line with the greatest slope passing through this point and tangent to the failure curve was drawn and the index for the optimal replacement interval identified as infinite. Accordingly, the recommendation based on this study is to operate the KT-73 IMU until failure.

Having met all of the criteria necessary, the research question is answered in the affirmative. As explained in Chapter III, having successfully applied Bergman's method for arriving at an optimal maintenance task interval, the reciprocal, $[C(T)]^{-1}$, of the objective function $C(T)$ is minimized. The resultant solution is an optimal maintenance task interval which balances the cost of replacement with the cost of failure, and results in a minimum total long-run average cost per unit time.

Secondary Research Question "a" asks how the optimal interval for the units tested compares with the current interval for the item. To answer this question, (1) the current interval must be known, (2) the distribution of observed failure data must be identified, (3) the index for the optimal interval must be identified using Bergman's graphical technique, (4) the current and optimal intervals must be compared, and (5) differences, if any, between the two intervals must be explained or reconciled.

The KT-73 IMU is replaced upon failure and so the current task interval is infinite. The empirical life distribution revealed by the TTT-plot using field data for the units was slightly DFR, and the index for the optimal replacement interval denoted an infinite interval. Thus, the current and optimal intervals are the same. Since all of the criteria for answering secondary Research Question

"a" were successfully met, the conclusion that the two intervals are identical can be asserted.

Secondary Research Question "b" asks how sensitive the calculated optimal interval is to the uncertainty of cost. To answer this question, (1) the mean and standard deviation for standardized cost values must be identified, (2) a range of values for C above and below the mean must be identified for use in performing the sensitivity analysis, (3) changes in the optimal index must be identified based on changes in C, and (4) conclusions about the sensitivity of the optimal interval to uncertainty in cost must be drawn from the analysis.

The ten values for cost of replacement, C, were subjected to analysis by the SPSS Condescriptive computer program to find values for the mean and standard deviation. Computing values for one and two standard deviations above and below the mean, new lines were drawn through these points and tangent to the failure curve. The index for the optimal replacement interval in each case denoted an infinite interval. Hence, it was concluded that the interval is totally insensitive to changes in cost, C.

Having successfully met all of the criteria, it was concluded that the optimal interval is totally insensitive to changes in cost.

CHAPTER V

CONCLUSIONS, IMPLICATIONS AND RECOMMENDATIONS

In this chapter, the authors endeavor to place in perspective the findings and observations gained through the demonstration of a simple graphical method for determining optimal maintenance task intervals using actual field data for equipment used in aircraft. The method is based on a control strategy which balances cost of replacement with the cost of failure resulting in a minimum total long-run average cost per unit time. The research conclusions, implications and recommendations are presented in the following sections.

Conclusions

The research objective was attained by answering the following research question and secondary questions:

Research Question

Can Bergman's graphical method be applied in determining an optimal maintenance task interval based on the objective of minimizing total long-run average cost per unit time using actual field data?

Bergman's method was successfully applied to a sample of KT-73 Inertial Measurement Units (IMUs) used in the Air Force A-7D aircraft. The study indicated that the component's

optimal replacement interval is an infinite one (operate until failure). The solution was found graphically. Bergman's method assigns an infinite task interval to any component displaying an exponential failure distribution or decreasing failure rate (DFR); therefore, by definition, the task interval could have been specified once the TTT-plot had been constructed and the distribution identified as DFR.

Secondary Research Question "a"

How does the calculated optimal interval for the units tested compare with the current interval for that item?

The units tested exhibited a DFR, thus, an infinite task interval was assigned. The current interval is also infinite. Comparison of the optimal and current intervals show that they are identical. Hence, the current interval is optimal.

Secondary Research Question "b"

How sensitive is the calculated optimal interval to the uncertainty of cost?

It was demonstrated in Chapter IV that a range of values for cost on the order of two standard deviations about the mean caused no change in the optimal replacement interval. Therefore, it was concluded that the optimal replacement interval is totally insensitive to changes in

cost. This conclusion could have been reached without performing the analysis since, by definition, a failure distribution which is DFR must yield an infinite interval.

The item chosen to demonstrate the graphical technique was not ideal for use in performing sensitivity analysis. The authors were unable to identify a unit of equipment that would display an increasing failure rate and that was traceable by serial number. This constraint severely limited demonstrating the usefulness of sensitivity analysis and the ease in which it can be accomplished using Bergman's method. However, the significant prospects that are offered for analyzing the uncertainty associated with cost through sensitivity analysis should not be overlooked.

Having answered the research questions, the researchers conclude that the application of Bergman's graphical technique to an IMU demonstrated a viable method for determining an optimal interval for an item in the Air Force inventory. It provides: (1) an easy way to give sensitivity analysis with respect to the uncertain relationship between cost of replacement and cost of failure, and (2) help in solving the problem of communication between the analyst and the decision maker (9:471) by presenting a visual means for analyzing failure data and by giving the analyst a "feel" for the uncertainties and relationships involved in arriving at the graphical solution.

Implications

Managerial Tool

Bergman's graphical method could provide the item manager with information to better manage the item. An empirical representation of the item's failure distribution would be known versus an assumed theoretical exponential failure distribution. The manager's planning could be influenced and enhanced significantly by better understanding the effects of changing cost on item intervals.

Opportunistic Maintenance Policy

This research was limited in scope in that it addresses optimal task intervals for individual components. To achieve an optimal maintenance policy for an end item, i.e., aircraft, the intervals of all components must be effectively incorporated into an optimal maintenance strategy for the end item. It is conceivable to combine optimal task intervals, achieved through Bergman's method, with the comprehensive maintenance strategy of an Opportunistic Maintenance Policy. Under such a policy, complex end items, i.e., aircraft, can be considered so that maintenance action taken on one part is made to depend on the state of the rest of the system. The use of such a maintenance policy in conjunction with optimal task intervals would result in some suboptimization of task intervals for the major end item; however, the final product would be a more effective maintenance strategy.

Smith conducted a Government-contracted study in 1980 in which he applied an opportunistic maintenance policy to the F100PW100 aircraft engine. The F100 engine is currently maintained under an on-condition policy, whereby the engine is removed and maintenance is performed to preclude failure of "driving" items only when required. Driving items are items whose failures are undesirable due to safety or economic consequences. Hence, this type of policy disallows scheduled maintenance for engine components on a hard time basis (27:3).

By applying an opportunistic policy, Smith reasons that maintenance actions not required at the time of engine removal (the opportunity) can be performed so as to avoid future costs (27:4). Using a total engine life-cycle cost formula, he balances the marginal cost to replace an item with the marginal cost of failure for the item and develops optimal Conditional Part Level (CPL) screens conditioned on engine status (27:22). A simulation of the engine's twenty-year life cycle indicated substantial savings, measured primarily by a reduction in engine removals. One of the major weaknesses in the analysis, according to Smith, regards assumptions in part failure distributions (27:39).

Since one of the keys to success of the model is the input of valid cost and failure data, Bergman's method could provide assistance in establishing an information storehouse

from which to feed the opportunistic maintenance screening process.

Within the context of the Reliability-Centered Maintenance Program, the use of an Opportunistic Maintenance Policy for major end items, based on individual analyses of components through Bergman's method, might better realize the objective of the program which is to develop a scheduled maintenance program that will realize the inherent reliability levels of complex equipment at minimum total cost.

Recommendations

It was found during the course of this research that some areas were worthy of further study:

General

There is much theory (see Chapter II) concerning optimal maintenance policies used to determine task intervals and typically based on the objective of finding the interval which minimizes cost. A need exists to begin closing the gap between theoretical and practical applications of methodology to determine maintenance task intervals.

The Air Force is dedicated to pursuing a means of improving the analytical process for determining scheduled maintenance task intervals; therefore, there is a need to restructure portions of the data collection system so it is responsive to the data needs of managers and, ultimately,

the analytical process brought about for determining task intervals.

Recommendations for Future Research

The amount of significant information obtainable through the use of Bergman's method is somewhat dependent on the failure distribution exhibited by the item under study. This is to say that sensitivity analyses and cost and interval relationships are better demonstrated by Bergman's method if the item displays an increasing failure rate versus an exponential failure distribution or decreasing failure rate. Therefore, it is suggested that further research be conducted with Bergman's graphical technique using an item which exhibits an increasing failure rate.

Any attempt to demonstrate the practical application of theoretical optimal maintenance models should be made within the context of an existing maintenance program. Only under this condition can the impact of the test be truly appreciated by an audience of potential benefactors. The attempt was made in this study to demonstrate Bergman's method within the context of the RCMP. However, in future research made within this context, a different approach is suggested. It is recommended that the item used for study be selected and characterized in accordance with the basic steps necessary to integrate items into the RCMP. Specifically, the item (1) should be identified as a significant item, (2) should have failure consequences (cost of failure)

identified through FMEA, (3) should have a specific type of maintenance task assigned to it, and (4) should have a maintenance task interval assigned to it.

Complying with these basic steps will accomplish the following: (1) it will be known that the item for study qualifies for RCM analysis because of its value in terms of safety and/or economics, (2) specific failure consequences can be identified and subsequent attempts made to quantify them for purposes of the study, (3) it will be known which type of maintenance task (hard time, on-condition, condition monitoring) has been assigned to the item so that an appropriate methodology for selecting the interval can be used, and (4) it will be known what task interval (finite or infinite) has been assigned to the item so that the optimality of the interval can be evaluated based on the results of the study. In this way, conclusions can be made about the applicability of the method under study as well as about the appropriateness of current intervals.

APPENDICES

APPENDIX A
FUNCTIONAL DESCRIPTION AND INSPECTION CHECKLIST--
KT-73 IMU

The purpose of this booklet is to familiarise the reader with the basic modes of operation of the A7 DMU. This information should be of value in determining and isolating malfunctions of the system.

It is recognized that this is not an in-depth analysis of system operation. This information will be supplemented by on-the-job training and technical assistance from the Logistics Support Engineering staff.

VERTICAL G.W.S.

The motor windings of the gyro have a / 0° and / 90° 20 volt peak to peak 480 cycle signal applied at all times after system turn on. This voltage is supplied by the Power Supply Board.

When the sequencing switch for Vertical G.W.S. is energized, a signal is applied to a relay driver on the Switching board. The relay K3 will couple an external supplied ground to the Vertical gyro which energizes the wheel.

CAGE MODE (A7 IMU)

The Cage Mode is for the purpose of aligning four gimbals to the attitude of the fixed frame of the platform. The various loops are standard servo loops employing direct current torquers.

The Azimuth pitch and outer roll synchros employ 26 vac. 400 Hz excitation from an external source while the Inner Roll pickoff excitation is a system supplied 19.2 KHZ at 8 vrms. This signal is supplied by the Power Supply Board.

OUTER ROLL LOOP - The stators of the outer roll Synchro are mechanically connected to the fixed Gimbal; while the rotor winding is essentially part of the outer roll Gimbal. The displacement angle of the rotor winding to the stator winding (S3) is indicated by a voltage. When this voltage is at a null with the proper phasing the mechanical position of the gimbal is zero degrees. The 400 cycle error is routed to the switching board to the O.R. Amp. The O.R. Amp. demodulates the A.C. to D.C. The D.C. signal is then coupled thru the gimbal board. The D.C. then is applied to the O.R. torquer (B9) which rotates the O.R. gimbal until it is positioned to point at which error signal is nulled. The remaining stator outputs are used to display O.R. position on the Roll P.A.I. at initiation of vertical isolation.

PITCH LOOP - The pitch Loop is similar to the O.R. channel in as the stators of (B6) Pitch CX are physically mounted on the O.R. gimbal and the rotor is on the Pitch Gimbal. The 400 cycle error signal is taken off of S3 and coupled through the switching board via relays to the Gimbal board. At the Gimbal board the 400 cycle signal is applied to a demodulator circuit which also receives a 400 cycle reference signal. The output is a positive or negative D.C. voltage depending on the phase of the error signal. The \pm D.C. is applied to a Power Amp. and coupled out to the torquer (B7) which drives the gimbal until the error is nulled. The remaining stator outputs are used to display Pitch angle on the P.A.T. during Vertical Isolation.

Inner Roll Loop - The I.R. Loop differs from the O.R. and Pitch only in the excitation used on the pick off which is 6 vrms. 19.2 kha. The pick off winding is mounted on the pitch gimbal and the rotor is positioned by the I.R. gimbal itself. The error signal from B4 is routed through the switching board and sent to the Gimbal board. The signal is then applied to demodulator which has a fixed reference signal of 19.2 kha. The \pm D.C. level is then amplified by the Power Amp. and applied to the I.R. torquer B5 which drives the I.R. gimbal until the error signal is nulled.

Asimuth Loop - The Asimuth Loop differs from the previously described loops in as it uses an external reference for its positioning. The Asimuth CX is positioned so that when the rotor and the stator (S1) are parallel to the X Axis of the frame of reference the output represent Zero degrees. The error signal from the stators of B2 is routed out of the IMI and applied to a synchronous transformer. In the test equipment the rotor of the C.T. is mechanically positioned to the desired Asimuth angle. The stator outputs represents this angle and is applied to the transformer. The output of the transformer is the difference of the two inputs. The error signal is then amplified and applied to the Asimuth channel on the Gimbal board. There the signal is demodulated and amplified. The \pm D.C. is applied to the Asimuth torquer B3. The Asimuth gimbal is driving until the error signal out of the test equipment is nulled. The stator outputs of B2 are also used to drive the Asimuth PAI.

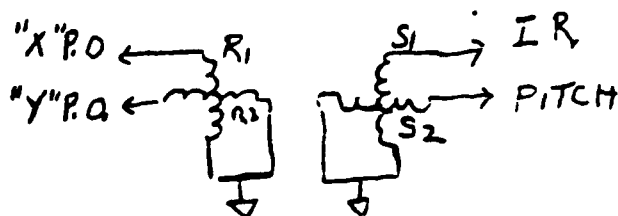
The various relays on the switching and Gimbal boards which are used for signal routing during the Cage Mode are energized by logic circuits on the switching board. The logic circuits are initiated by the sequencing switches on the test equipment.

VERTICAL ISOLATION

In this mode of operation there are actually two phases. The first being Low Gain and the second, Normal Gain. The only difference in the two phases is the input resistance to the demodulators in the Inner Roll and Pitch channels. These resistors are large during Low Gain and smaller during Normal Gain.

The purpose of Vertical Isolation is to cage the Inner Roll, Pitch and Outer Roll gimbals to the pick offs of the Vertical Gyro rather than to the synchros as in the Cage Mode. The circuit operation is as follows:

The outputs of the Vertical Gyro referred to as "X" axis pick off and "Y" axis pick off are amplified in the Gyro electronics board and applied to the rotor windings of the coordinate resolver (B1). The rotor of B1 is mechanically positioned at the function of the Azimuth gimbal. The stators position is fixed due to the fact that they are physically attached to the Inner Roll Cap in which the cluster is housed. The rotor windings R1 and R2 and stator windings S1 and S2 are displaced from each other by 90 degrees. Refer to the figure below.



When the Azimuth is positioned to zero degrees and the Platform is aligned along the X axis frame of reference the rotor R1 and the stator S1 are both aligned to zero degrees. At this time the "X" pick off is applied to R1 and induced into the S2 winding. If the Azimuth or the Platform is repositioned to an angle of 90 or 270 degrees the voltage applied to R1 would be induced in the S2 winding and any voltage on R2 would be coupled to S1.

The signal representing "X" axis pick off which is applied to R1 and induced into S1 is applied to the Inner Roll channel on the Gimbal board. The signal is demodulated, amplified and applied to the Inner Roll torquer.

At this time, the Outer Roll gimbal, which was caged to its own synchro output, is caged to the output of the Inner Roll pick off. The I.R. pick off signal is coupled to the Outer Roll Amp. on the Switching board. The reference input is switched from 400 HZ to 19.2 KHZ by circuits on the Switching board. The output from the O.R. Amp. is sent through the Gimbal board and applied to the Outer Roll torquer B9. The outputs of the O.R. CX (B8) are used to display position on the Roll P.A.I.

The "Y" pick off signal is applied to R2 of B1 coupled to S2 and applied to the Pitch channel on the Gimbal board. At this time the reference input to the demodulator is switched from 400 HZ to 19.2 KHZ by circuits on the Switching board. The signal is demodulated, amplified and applied to the Pitch torquer B7. The outputs of the Pitch CX (B6) are used to display position on the Pitch P.A.I.

The Azimuth loop remains as it was in Cage Mode. The various relays on the Gimbal and Switching boards are driven by inputs to the Switching board from the sequencing switches on the test console.

AZIMUTH G.W.S.

The operation of Azimuth G.W.S is identical to Vertical G.W.S. except that the switching of the ground is performed by relay KB.

See Vertical G.W.S. signal flow print.

AXIMUTH ISOLATION

This mode consists of two phases of operation. The first being, caging of the Azimuth gimbal to the Z Axis pick off of the Azimuth gyro. The "Z" pick off is applied to the Gyro EI-electronics board where it is amplified to a useful output level and then is sent to the Azimuth channel of the Gimbal board. The signal is coupled through a 1 megohm resistor by the action of relay K10 and through the contacts of K6 to the demodulator stage. The reference input is switched during this mode of operation from 400 HZ to 19.2 KHZ by the Switching board. The D.C output is applied to the amplifier section and applied to the Azimuth torquer (B3).

The second phase consists of two separate actions; switching to high gain in the azimuth channel and the caging of the Redundant loop to its own pick off.

High gain switching of the Azimuth channel is accomplished by the energizing of relay K10. The contacts of K10 will insert a 30K ohm resistor in place of the 1 megohm resistor thus increasing gain of the stage.

The output of the Redundant axis of the Azimuth Gyro is amplified, demodulated and amplified again and applied to the redundant torquer. The circuit is completed by the action of relay K2 on the Switching board which places the other side of the torquer to ground.

COURSE LEVEL

The purpose of this mode of operation is to level the double axis accelerometer so that the two axis are perpendicular to the gravity vector. Since both channels are effectively identical, only the "X" axis will be discussed.

Following the previously discussed modes of operations the accelerometers, particularly the double axis, will not be perfectly level to the earth and there will be an output representing this misalignment. The output signal which is 19.2 KHZ is amplified by pre-amps located on the D/A. The signal is then sent to the restoring amp. on the accelerometer Electronics board. The output is a \pm D.C. representing the amount of off level. The D.C. signal is applied through the torquer coil and routed to a junction point. Also tied to the junction point is a D.C. level which is used to null out the amount of error signal which is due to mass unbalance of the accelerometer. This voltage is supplied by the resistor network R32 and R33 on the Compensation Board.

The D.C. signal is applied to the Power Supply Board and through relay K2 to the "X" Coarse Level amp. The amplified signal is then sent to the Switching board. On this board the relay K10 serves a function of increasing or decreasing the gain of the signal. During Back-up level the 3.4K resistor is inserted into the circuit to lower the gain. In Coarse Level the relay is as above. The output of the Switching board is sent back to the Compensation board, through R18 and R19 and applied to the "Y" axis torquer of the Vertical Gyro. This signal will precess the gyro wheel causing an output on the "Y" pick off. The pick off signal is then amplified and applied to the rotor winding of the coordinate Resolver (S1). At this time if the Platform is aligned along the "X" axis and the heading is zero degrees, the signal will be coupled into the stator winding which feeds the Pitch channel of the Gimbal board. As the Pitch gimbal is rotated the output of the "X" axis accelerometer will diminish. The Pitch gimbal will continue to torque until the output of the accelerometer is nulled out.

The "Y" axis error signal will cause torque to be applied to the "X" axis of the Vertical Gyro whose output will cause the Inner Roll gimbal to be rotated until the error signal is nulled.

ALIGN NORMAL

In this mode of operation the Platform is free to drift with Earth Rate. At this present position of Latitude the drift rate about the X axis is 11.519 DEG/HR. and the drift rate about the X-Z axis is 9.672 DEG/HR. This drift will appear as movement on the Roll and Azimuth API's respectively.

There are certain corrections in respect to the Gyroflex that are taken into consideration at this time. All gyros exhibit drift characteristics and there are two classifications of drift. The first is referred to as "random drift" and is not acceptable for use in an IMU. The second is "fixed drift". The rate of drift is measurable and can be compensated for.

There are two other characteristics of the Gyroflex to be accounted and corrected for. They are both due to the actual construction of the wheel assembly of the gyro and will not be discussed in detail.

Both the X and Y axis of the Vertical Gyro and the Z axis of the Azimuth will have in their pick-off signal a voltage which is due to "in phase" error, also referred to as Spring Rates. Located on the Compensation Board are Amplified/Demodulator stages and "select during test" resistors which are used to null out the "In phase" error.

The other type of error is referred to as quadrature. Due to the "torque about - precess about" principle of gyros, this signal is applied to the axis 90 degrees displaced from where the error is detected. In other words, if the quadrature error is taken off the X axis pick-off it is applied to the Y axis torquer.

The fixed drift mentioned previously is compensated by applying a voltage to the X, Y and Z torquers, which will cause movement that is equal but opposite the drift, therefore, eliminating the affect of drift. This voltage is inserted into the circuit by R10, R11 and R12. The pots are also referred to as Restraints.

ALIGN NORMAL (FAST SLAVE)

In fast slave mode the Azimuth, Pitch and Roll gimbal position is determined by the angular displacement of their respective PAI's. As the PAI position is changed a signal is applied to the proper gyro torquer causing the gimbal to be repositioned.

The signal flow for Fast Slave is as follows:

AZIMUTH - A demodulated signal representing Azimuth PAI position is coupled across the contacts of relay K15 on the Switching Board and is applied through resistors R22 and R23 on the Compensation Board. This D.C. signal is applied to the Z torquer. The other side of the torquer is tied to ground via the Switching Board from an external source. The resultant Z pick off is amplified in the Gyro Electronics Board and applied to the Azimuth channel of the Gimbal Board. The output of the Gimbal Board is applied to the Azimuth Torquer which causes the Azimuth CS output to change. When the Azimuth CX position output is equal to the PAI's position the error signal applied to the Z torquer drops to zero and the Cluster stops driving.

The operation of the Pitch and Roll Gimbals during Fast Slave is identical except the error signals are applied directly from the PAI's to the X and Y gyro torquers.

ALIGN NORMAL (SLEW)

This mode of operation is identical to Fast Slave except the Azimuth, Pitch and Roll Gimbals are not repositioned by an error signal from the API's but rather by a ± 15 vdc signal from the Switching Board.

The selection of which Gimbal is slewed and in what direction is controlled by switches on the test equipment. Since the method of slewing all three of the Gimbals are somewhat ~~int~~ identical only the Pitch will be explained:

When Y Slew is selected relay K14 is de-energized by the signal applied to Z20 on the Switching Board. This ties the contacts of K14 to the Contacts of K12. Depending upon if K12 is energized or not a ± 15 vdc signal is applied to the Y torquer via the Compensation Board. The Y pick off signal is amplified and applied to the coordinate resolver and sent to the Pitch channel on the Gimbal board. The signal is applied to the Pitch Torquer Relay K12 determines direction of Slew.

The Azimuth Slew differs from Pitch and Roll to the extent that the Z torquer has a ± 15 vdc on one side and a $- 15$ vdc on the other. These polarities are reversed by the action of K9 when actuated by the polarity switch on the T/E.

DIGITAL LEVEL

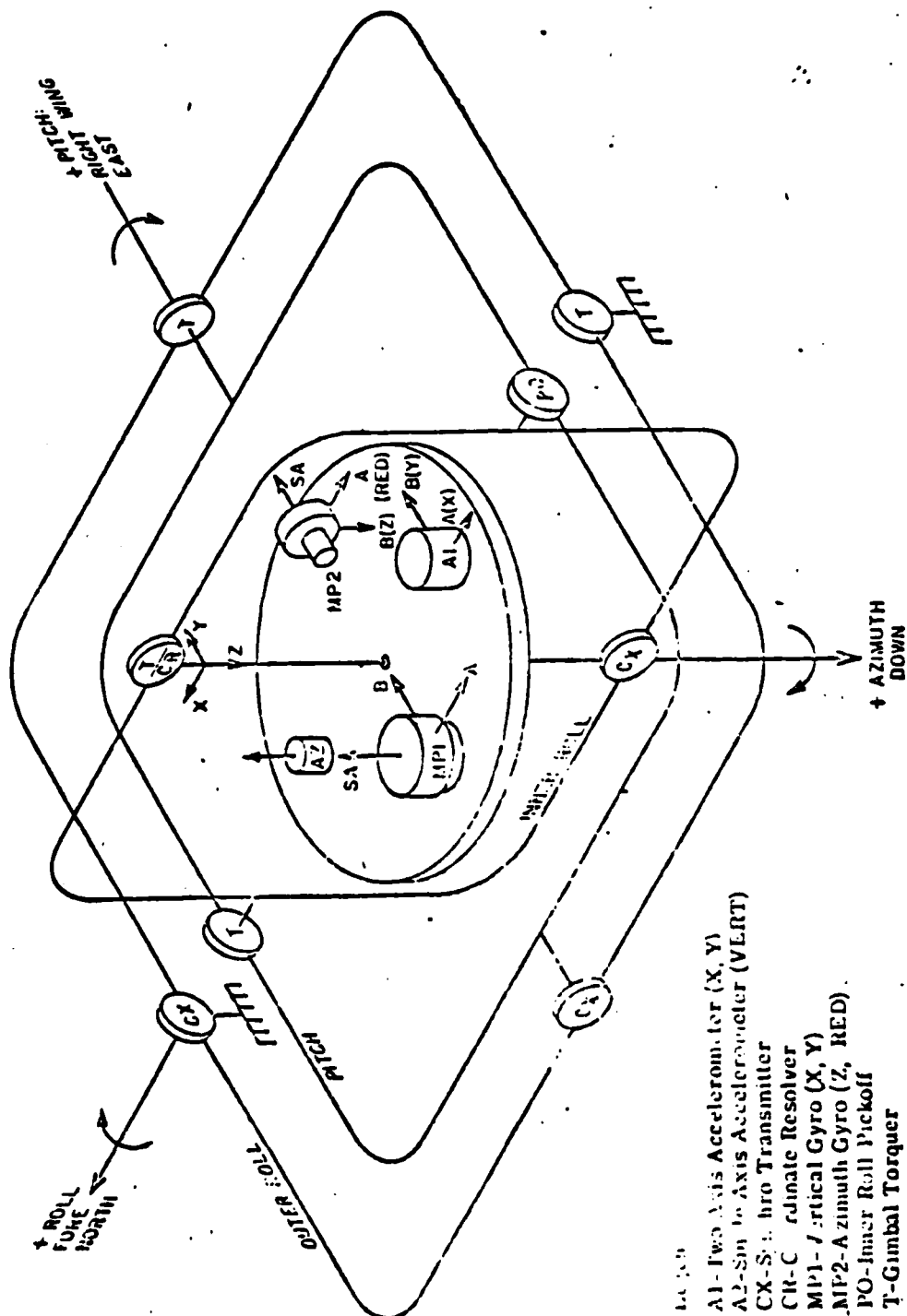
This is the mode of operation where the system is refined. That is to say that we want to perfectly level the system in respect to the earth's surface and insure that the system is pointed exactly north.

This is accomplished in the following manner. The X, Y and Z accelerometer signals are applied to the CAPRI Board where they are integrated into X, Y and Z velocity signals. These signals are displayed on the CAPRI counters. The X and Y CAPRI signals are also applied through the Digital Level Control Module to the Gyro Control Module. The X CAPRI signal is converted to pulses and is applied as Y Gyro pulses to the Switching Board. The Switching Board circuitry changes the one signal into two signals 180 apart. The two signals representing Y Gyro are applied to a push-pull circuit on the Gyro Electronics Board and the Y Bias torquer. This signal will null out any off level condition of the X accelerometer.

The X Gyro circuitry is identical to the Y Gyro except for the amount of pulses that the X Gyro puts out. As discussed previously, the X axis of the Vertical Gyro if not corrected would appear to drift with Earth's Rate. In Digital Level the output of the Y accelerometer is due to the Earth's Rate on the X axis Gyro. The false acceleration signal is integrated in the CAPRI Board and converted to pulses to be applied to the X bias torquer. The amount of pulses required to keep the Y axis of the D/A accelerometer perfectly level with the Earth's surface is the Earth's Rate correction signal for the X axis Gyro.

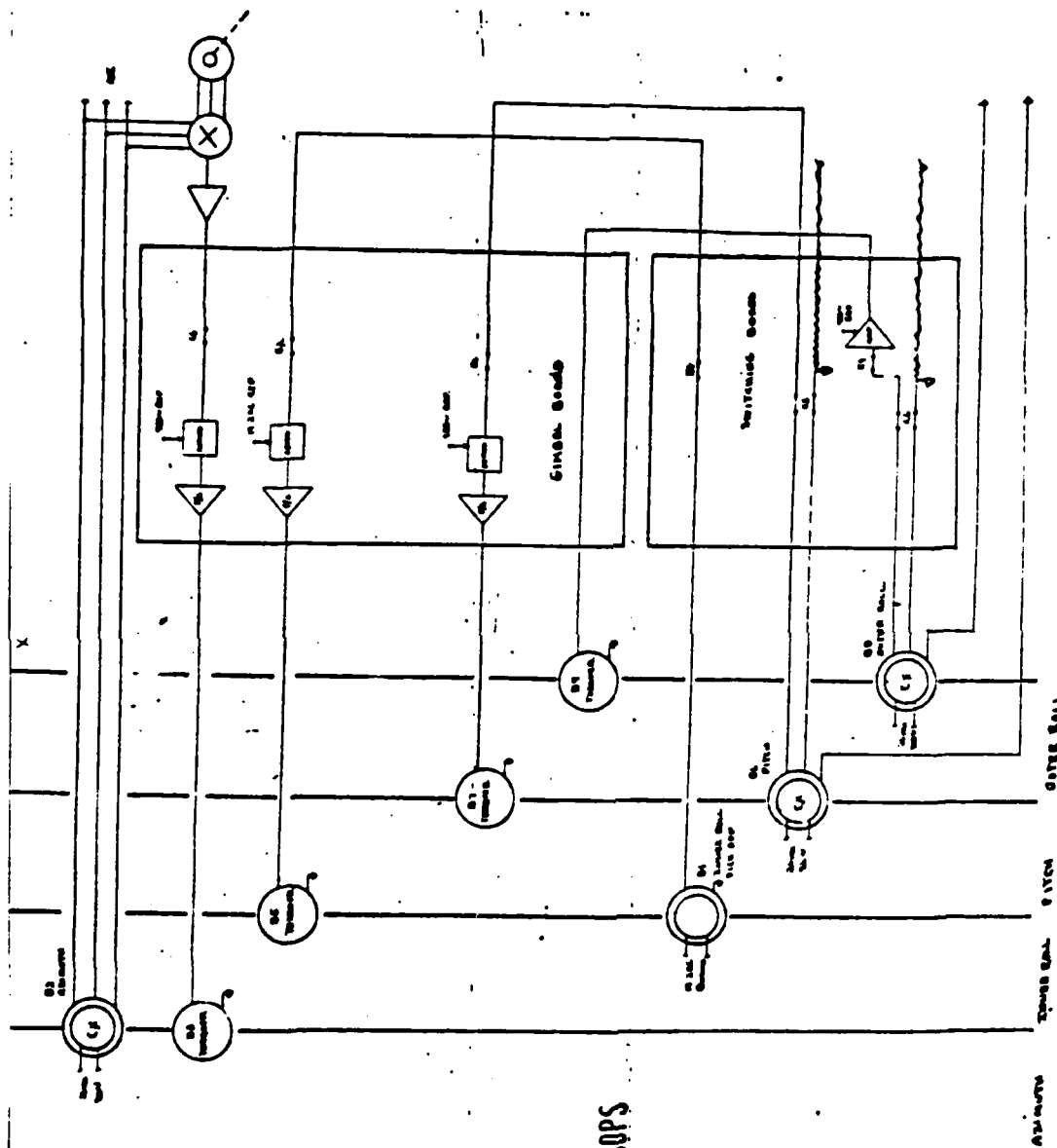
The Z Gyro circuit is used to null out the effect of Earth's Rate about the Z axis. To supply the correct signal for the Azimuth Gyro the output of the Azimuth CX is used. As the Z axis starts to drift, the Azimuth CX output changes to indicate this apparent precession. The signal is applied to the "Z" VCO Module where the 400 cps signal is converted into digital pulses. This signal is applied through the Test Equipment to the Z Gyro circuitry on the Switching Board and finally to the Z Bias torquer. The torquing signal is used to drive the Z axis of the Azimuth Gyro in a direction which is equal but opposite the drift rate..

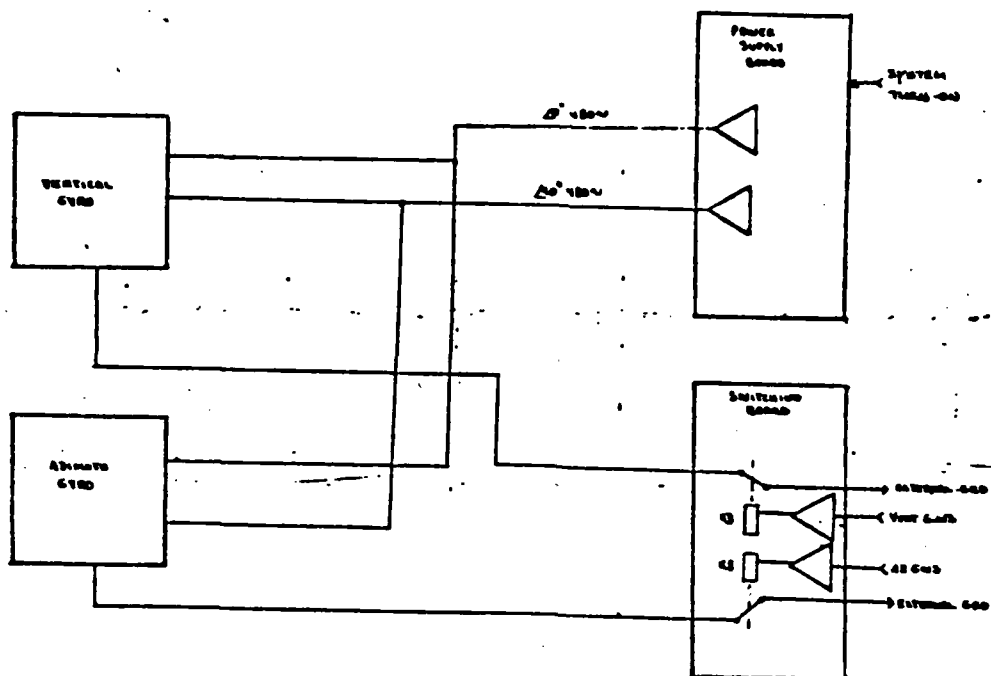
BASIC STABLE PLATFORM



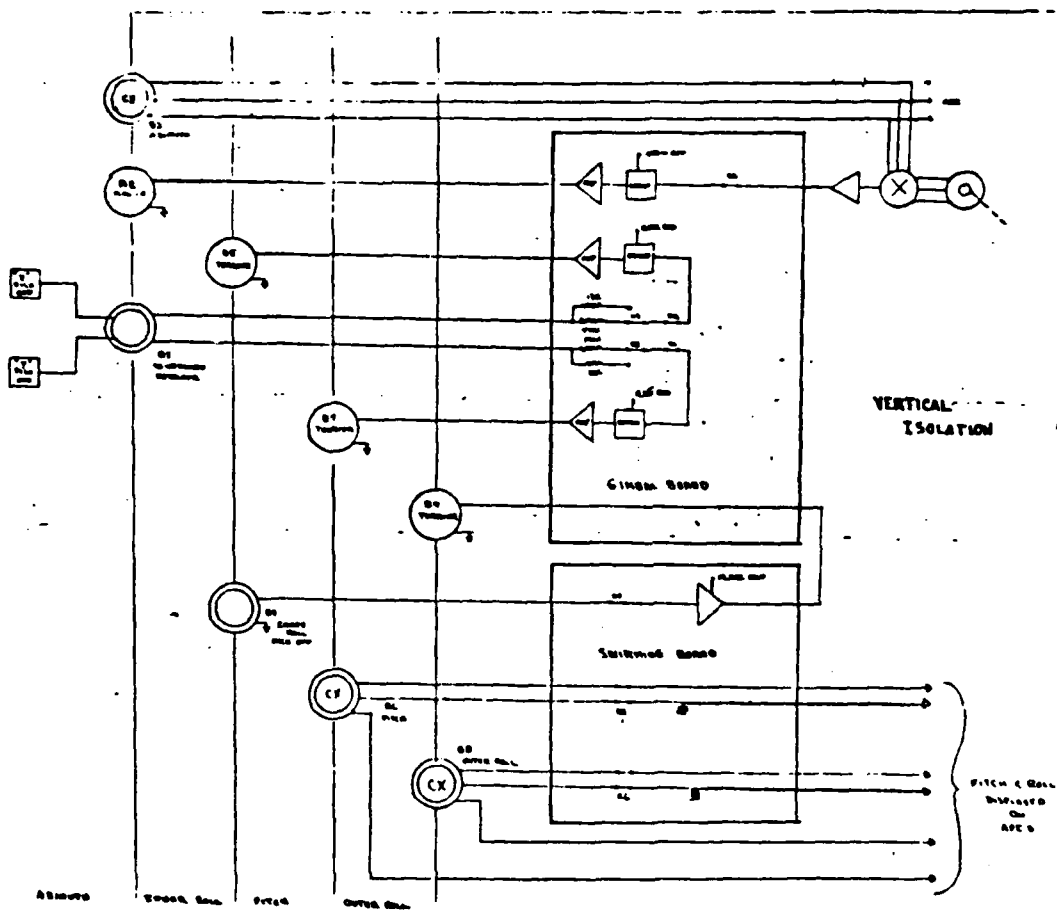
- A1 - Two Axis Accelerometer (X, Y)
- A2 - Six Axis Accelerometer (VLRT)
- CX - Roll Pickoff
- CY - Pitch Pickoff
- CZ - Yaw Pickoff
- MP1 - Vertical Gyro (Z, RED)
- MP2 - Azimuth Gyro (X, Y)
- PO - Inner Roll Pickoff
- T - Gimbal Torquer

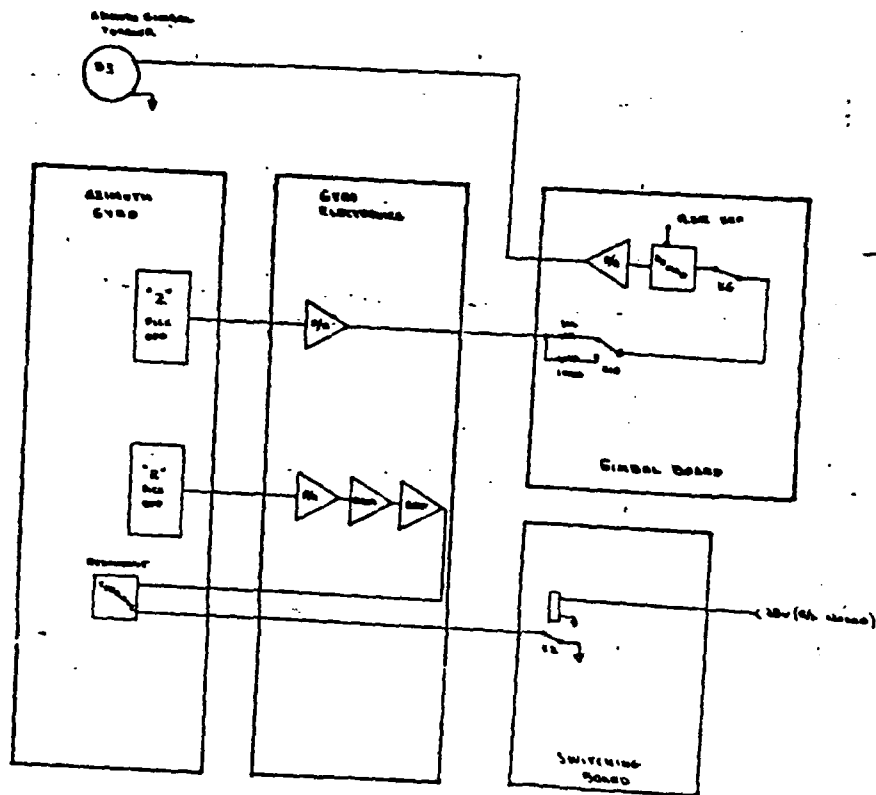




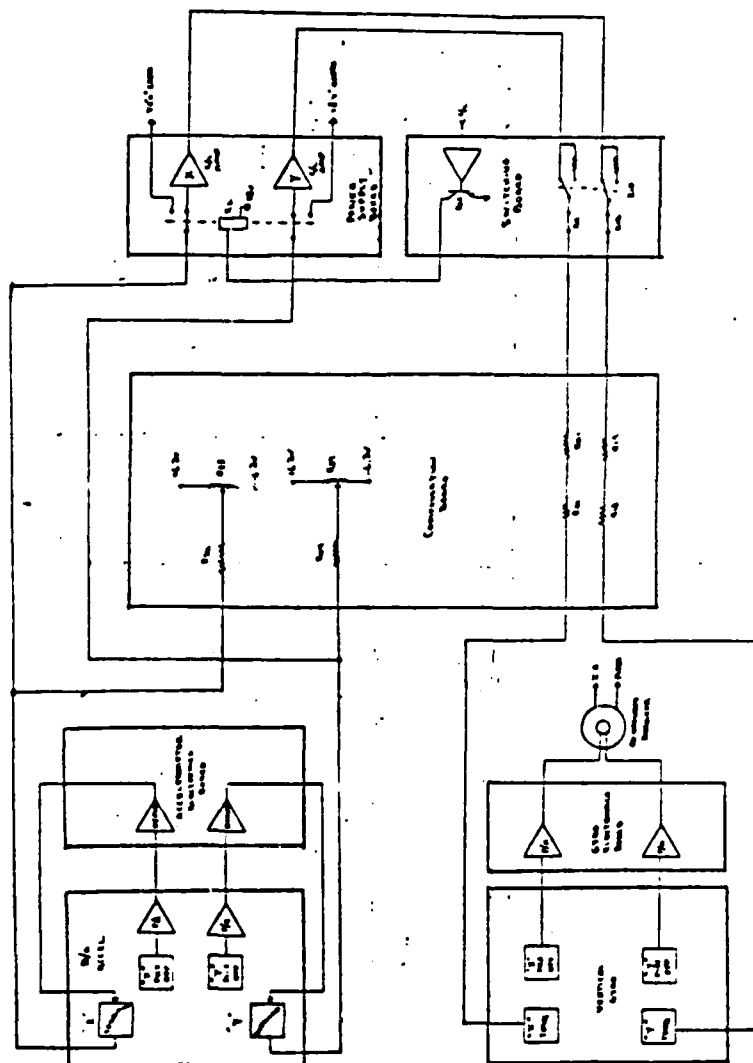


— VERTICAL GWS
 — AZIMUTH GWS

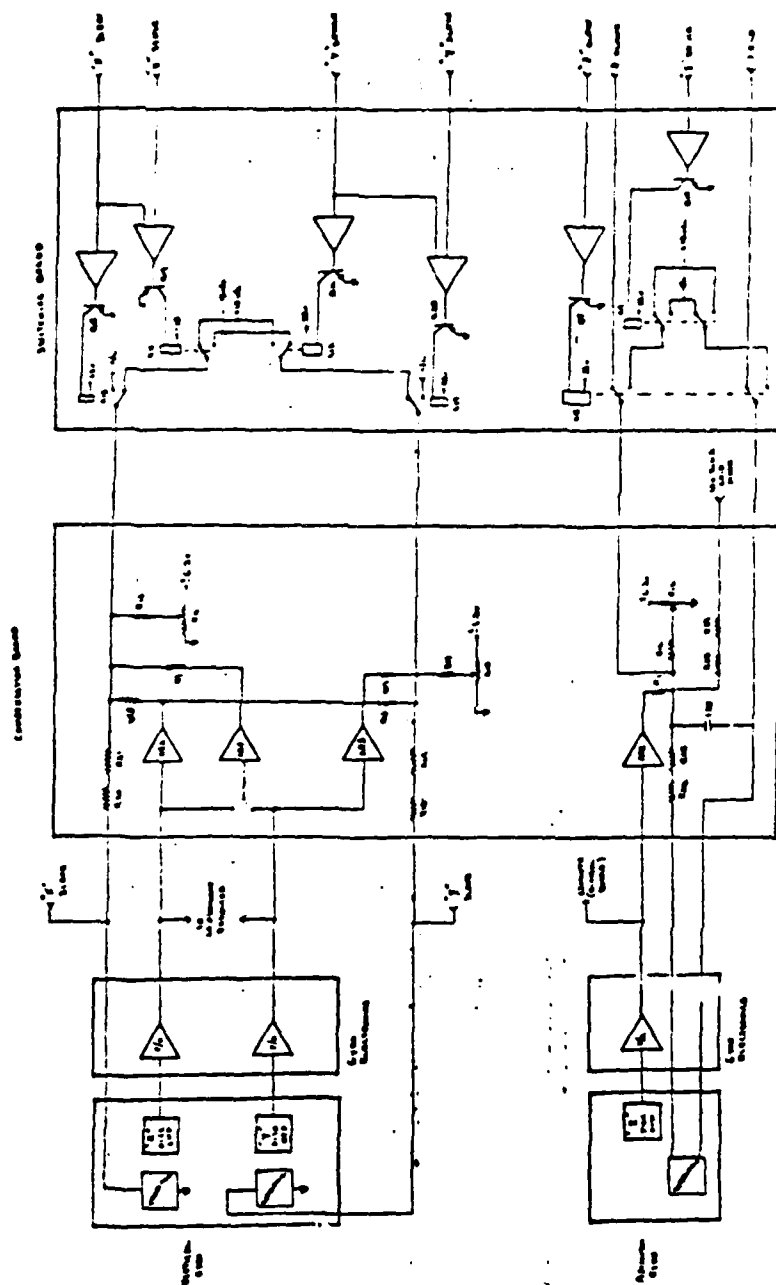




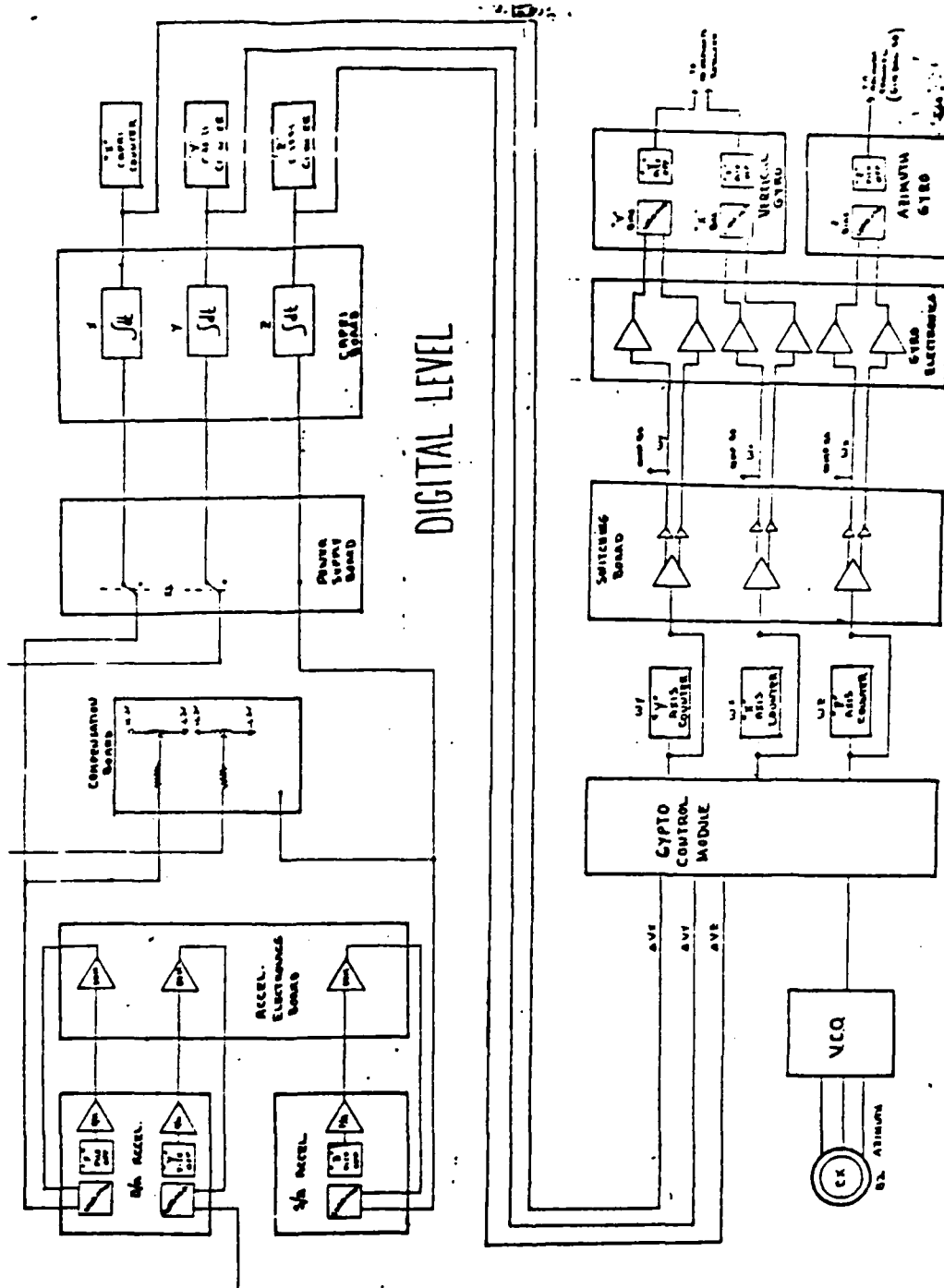
AZIMUTH ISOLATION



COARSE & BACK-UP LEVEL



ALIGN NORMAL
SLEW & SINE



VIEW OF A7 PLATFORM

P1, P10, J5, J6 CONNECTORS
WITH CORRESPONDING PIN LOCATIONS



VIEW OF P1 CONNECTOR
LOOKING TOWARDS
COMPENSATION BOARD



VIEW OF J5 CONNECTOR
LOOKING AT IMU HOUSING

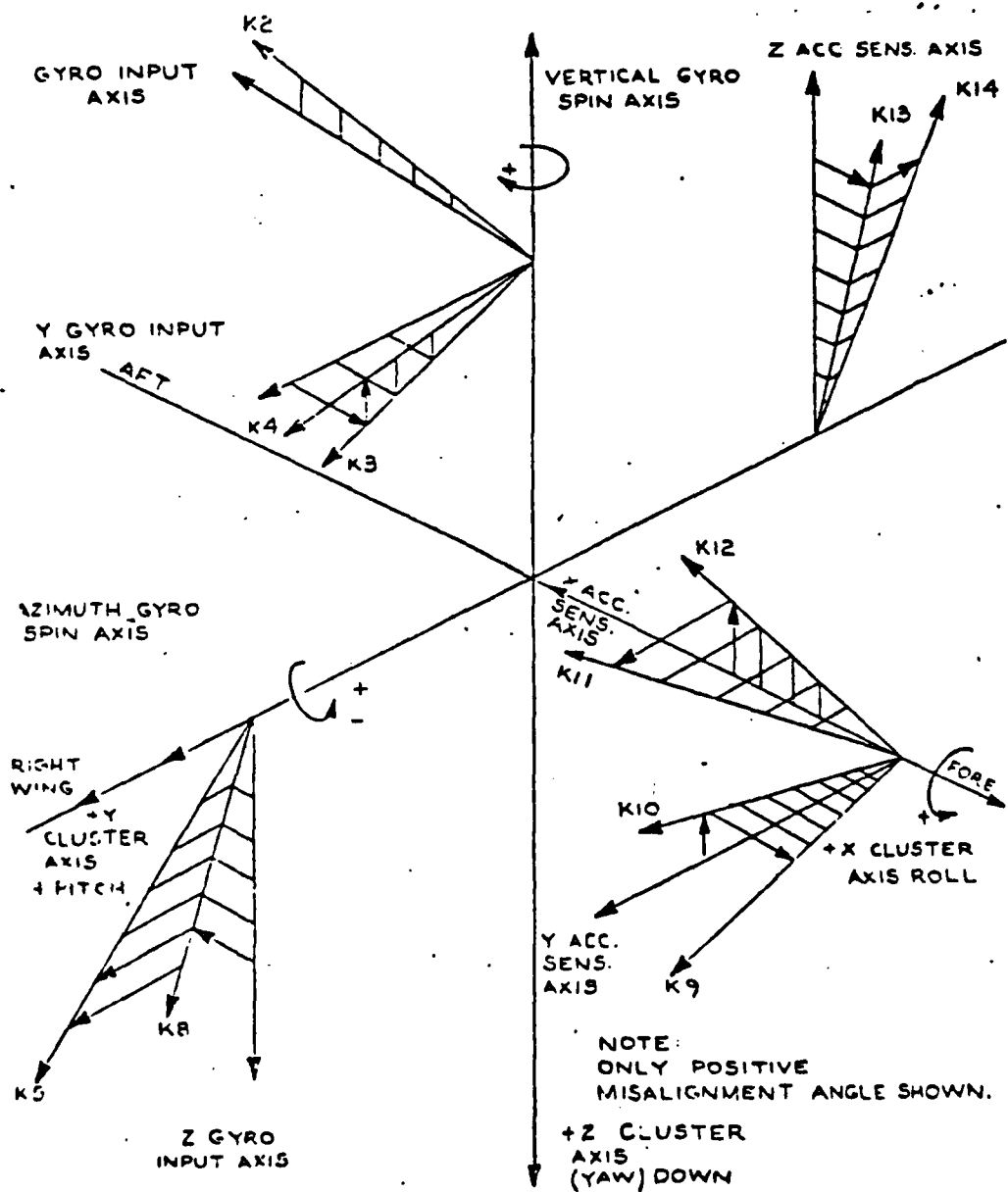


VIEW OF J6 CONNECTOR
LOOKING AT IMU HOUSING

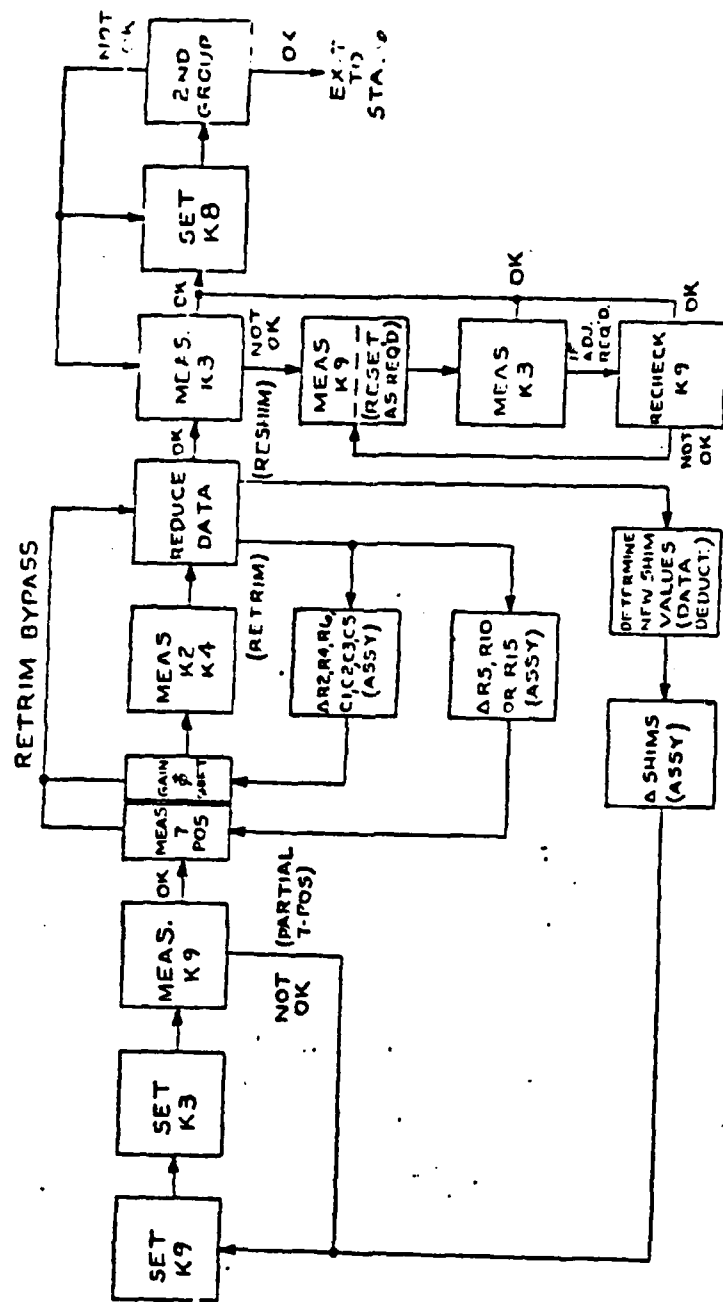


VIEW OF P10 CONNECTOR
LOOKING TOWARDS COMPENSATION
BOARD

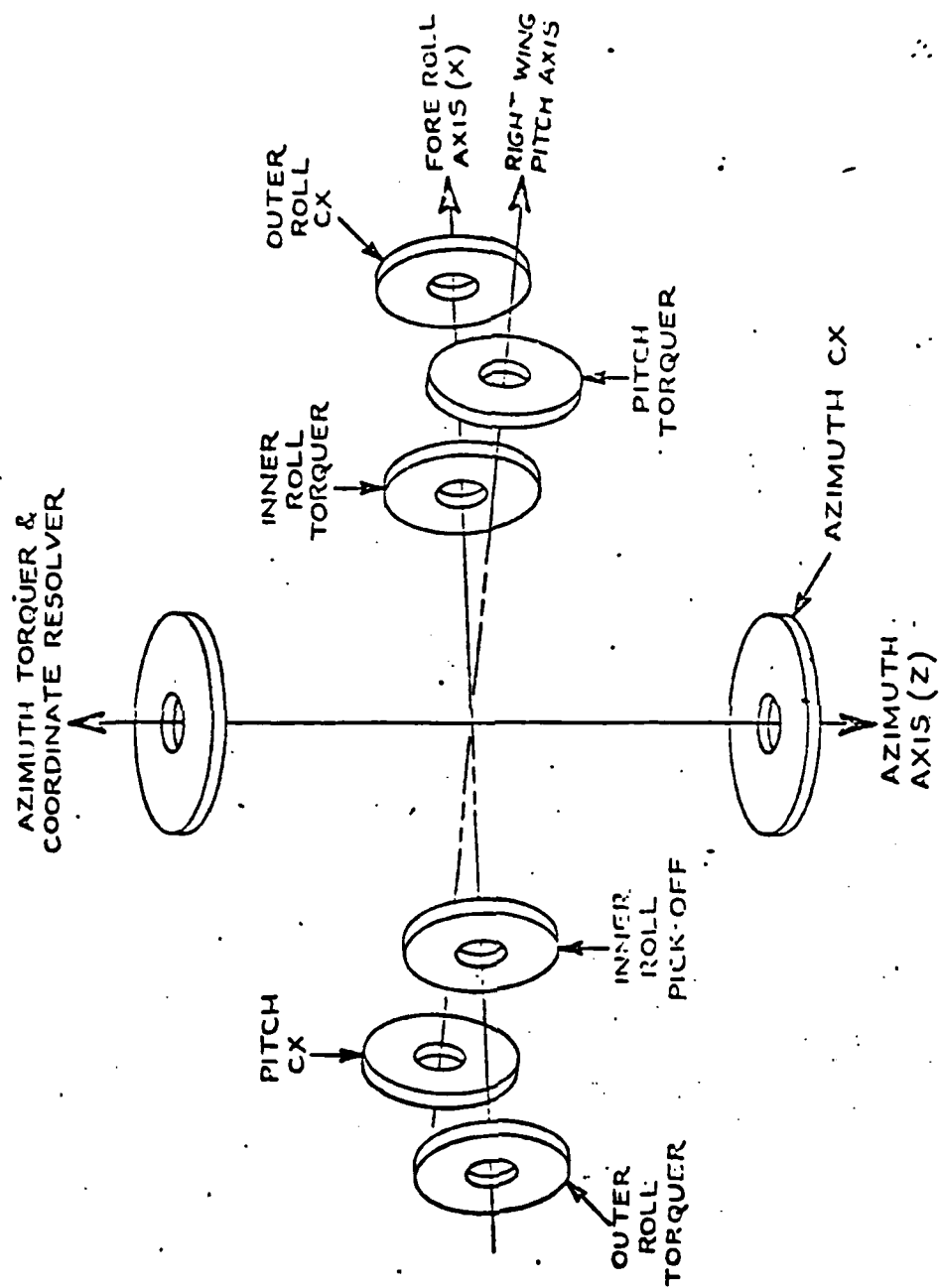
PLATFORM MISALIGNMENT ANGLE DEFINITION



SEQUENCE OF ALIGNMENT - A-7 CLUSTER



GIMBAL COMPONENT & AXES ORIENTATION



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ENGINEERING DEPARTMENT SPECIFICATION

TABLE XIII
AUTOMATIC IMS TESTING FAIL NUMBERS

BASIC TEST	FAIL NO.		INDICATED FAULT
	PRI*	SEC	
A	1		IMS failed and/or IMS System ready not indicated
B	2		IMS ground align mode not indicated
C	5		IMS self contained analog level incorrect
D	6		IMS self contained hdg loop initialization incorrect (Mag Var difference of 10° not indicated)
E			Accelerometer X and Y null bias & vertical accel. 1"G" bias not within prescribed limits:
	7		X accel/CAPRI high gain null bias out of tolerance
	8		Y accel/CAPRI high gain null bias out of tolerance
	9		X accel/CAPRI low gain null bias out of tolerance
	10		Y accel/CAPRI low gain null bias out of tolerance
	11		Z accel/CAPRI 1"G" bias out of tolerance
	27		X and/or Y accel/CAPRI low gain output saturated
F			Continuous platform slew condition:
	12		Continuous platform slew in X and/or Y axes
	13		Continuous platform slew in azimuth axis
G	17		IMS not under computer control:
		14	No response to positive X & Y slew commands (X & Y accel measurements)
		15	No response to positive Az slew commands (Az synchro measurement)
		16	No response to positive Az slew commands (mag hdg synchro measurements)
	3		Y slew sense malfunction (slews in one direction only)
	4		X slew sense malfunction (slews in one direction only)
	69		Continuous computer control
H			Azimuth slew function malfunctions and/or hdg synchro signals invalid:
		18	Positive Az slew malfunction
		19	No response to negative Az slew commands (Az synchro measurement)
		20	No response to negative Az slew commands (mag hdg synchro measurement)
		21	Negative Az slew malfunction
	22		Platform Az synchro invalid

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ENGINEERING DEPARTMENT SPECIFICATION

TABLE XIII (Continued)

BASIC TEST	FAIL NO.		INDICATED FAULT
	PRI*	SEC	
	23		Mag hdg synchro invalid
	24		No Az slew function
	25		Azimuth slew sense malfunction (slew in one direction only)
I	26		Malfunction of auto reversion to and/or operation of backup grid mode (plat hdg + mag hdg)
J	31		Fast magnetic heading update malfunction:
		24	Fast mag hdg update response rates not indicated (plat Az synchro measurement)
		40	Fast mag hdg update response rates not indicated (mag hdg synchro measurement)
K	34		Malfunction of auto reversion to and/or operation of backup mag slave mode (land only):
		32	Response rates not proper for mag slave mode (plat Az synchro measurement)
		33	Response rates not proper for mag slave mode (mag hdg synchro measurement)
L			Malfunction of X & Y slew functions and/or accel/CAPRI signals and/or roll & pitch attitude signals:
		45	Improper response to + X slew commands (roll synchro measurement)
		46	Improper response to + Y slew commands (pitch synchro measurement)
		47	Improper response to + Y slew commands (X low gain accelerometer measurement)
		38	Improper response to + X slew commands (Y low gain accelerometer measurement)
		39	Improper response to + Y slew commands (X high gain accelerometer measurement)
		40	Improper response to + X slew commands (Y high gain accelerometer measurement)
		41	Positive X slew malfunction
		42	Positive Y slew malfunction
		43	Improper response to -X slew commands (roll synchro measurement)
		44	Improper response to -Y slew commands (pitch synchro measurement)
		45	Improper response to -Y slew commands (X low gain accelerometer measurement)
		46	Improper response to -X slew commands (Y low gain accelerometer measurement)
		47	Improper response to -Y slew commands (X high gain accelerometer measurement)

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ENGINEERING DEPARTMENT SPECIFICATION

TABLE XIII (Continued)

BASIC TEST	FAIL NO.		INDICATED FAULT
	PRI*	SEC	
		48	Improper response to -X slew commands (Y high gain accelerometer measurement)
		49	Negative X slew malfunction
		50	Negative Y slew malfunction
	51		Positive Y accel/CAPRI malfunction
	52		Negative Y accel/CAPRI malfunction
	53		Y accel/CAPRI malfunction
	54		Negative X accel/CAPRI malfunction
	55		Positive X accel/CAPRI malfunction
	56		X accel/CAPRI malfunction
	57		Accelerometer scale factor change function malfunction
	58		Roll synchro invalid
	59		Pitch synchro invalid
	60		No X slew response
	61		No Y slew response
M			Gyro digital torquing function malfunctions:
	62		GYPTO clock line malfunction (open/short)
	63		Positive Y torque malfunction
	64		Negative X torque malfunction
	65		Negative Y torque malfunction
	66		Positive X torque malfunction
	67		Positive Az torque malfunction
	68		Negative Az torque malfunction
N	70		Vertical accel/CAPRI malfunction

*Primary fail numbers underlined are critical failures which discontinue testing.

APPENDIX B

G078C REPORTS - "AIRCRAFT LISTING"
AND "FIELD OPERATING HOURS (FOH) BY CYCLE - QUARTERLY"

Explanation. The appendix contains extracts from the "Aircraft Listing" and "Field Operating Hours (FOH) by Cycle - Quarterly" G078C reports. The listings are prepared by unit serial number (second column) and cycle number (first column). Failure data for units in the sample were taken by serial number for Cycle 1 (underlined entries). Actual times to failure (hours) were taken from the column labeled "ETI IN," the elapsed time indicator reading.

PREPARED BY MAY 20

MASTER LIST 81-73 (AF) PREPARED MAY 1982

CAN G 118

PL LY	PLAT-EN	DAIR RELU	MASS L K	(LTI) TH	DTI OUT	IRS	SHIPU AIL	W-U	350 M H	612 M H	612 A I	1AG	
-	01	AF00000	76117	MIL	0325	0077	76120	MIL	246	A	1500000119		
-	02	AF00001	71315	MIL	0399	0177	72033	MIL	799	B	1104508696		
-	03	AF00002	72062	MIL	0224	0260	72077	MIL					
-	04	AF00003	72109	MIL	0271	0342	72129	LAC					
-	05	AF00004	72200	MIL	0300	0423	72292	MIL					
-	06	AF00005	72327	MIL	0475	0502	72333	MIL					
-	07	AF00006	72410	MIL	1100	1139	72420	MIL	037	086	F	1701439773	
-	08	AF00007	74110	MIL	1352	1393	74142	MIL	051	G			
-	09	AF00008	76245	MIL	2471	2514	77009	EOL	654	FUA	F	2150431230	
-	10	AF00009	76003		2770	2832	78025		CAO	F	0999999999		
-	11	AF00010	72027	MIL	0229	0313	72108	MIL	799	B	0184921342		
-	12	AF00011	72341	MIL	0490	0534	73005	EOL					
-	13	AF00012	73072	EOL	0500	0603	73121	KUR	824	615	F	0611253259	
-	14	AF00013	74023	MIL	0705	1797	74330	ENG	242	00N	F	0172824459	
-	15	AF00014	75304	ENG	2155	2195	75315	MIL	0	255	677	A	2621251095
-	16	AF00015	72350	MIL	0515	0640	73064	ENG					
-	17	AF00016	74207	ENG	1307	1007	74208	ENG	656	246	A	2400463026	
-	18	AF00017	76243	ENG	1759	1802	77014	MIL	0	657	FBS	F	3351306583
-	19	AF00018	77110	MIL	1037	1077	77130	PIT	0	653	CAN	G	0750201756
-	20	AF00019	71320	MIL	0127	0182	71364	MIL					
-	21	AF00020	72112	MIL	0184	0295	72156	MIL					
-	22	AF00021	73020	MIL	0540	0595	73001	ENG	242	127	G	0052814406	

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PALPARLO 02 MAY 20

PLAT-34

02 AF00025 74199 MIL 0919 0962 0016 74225 KUR 607 246 A 1922823581
 03 AF00025 75015 KUR 1132 1177 0170 75022 ENG 799 0 3030817008
 04 AF00025 75104 ENG 1332 1391 0175 75237 ENG 0 655 AAO G 1750501256
 05 AF00025 76007 ENG 1403 1530 0092 76019 KIR 0 655 799 B 3541307550
 06 AF00025 72242 DMR 0104 0259 0000 72266 EDH 037 F
 07 AF00025 73144 MEL 0346 0394 0089 73220 ENG 070 F 0003183230
 08 AF00025 75115 KIR 0734 0773 0540 75204 DMN A 607 EBA F 0727500811
 09 AF00025 75239 DMN 0996 1049 0025 75266 MCE U 958 AAO G 2300548487
 10 AF00025 76307 MCE 1393 1444 0344 76234 TIN 0 653 246 A 2740231808
 11 AF00025 76276 ENG 1787 1818 0343 76331
 12 AF00025 72353 KJR 0308 0419 0000 73031 ENG
 13 AF00027 75324 ENG 1302 1408 0943 75335 PIT U 958 799 B 3091258944
 14 AF00027 77252 PIT 2081 2114 0673 77256 037 246 A 2284050061
 15 AF00027 78305 TIN 2322 2355 0208 78341
 16 AF00028 73170 MTL 0414 0468 0300 73236 KUR UNK 037 F 1431508554
 17 AF00028 73284 KJR 0470 0509 0002 73305 KUR 958 799 B 2552802161
 18 AF00028 74227 MIL 0332 0832 0323 74289 KJR 652 C8Q F 2242513518
 19 AF00028 75086 KUR 1043 1082 0211 75118 KUR 0 255 246 A 0670805005
 20 AF00028 76131 ENG 1375 1478 0293 76176 EGL 607 799 B NU 350 TAG
 21 AF00028 76203 EGL 1409 1566 0011 76236 ENG UNK 799 B NU 350 TAG
 22 AF00028 77019 LMG 1610 1672 0052 77035 HPI B 652 799 B 0101111235
 23 AF00028 77097 TIN 1693 1750 0021 77172 TIN 290 246 A NU 350 TAG

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PREPARED BY MAY 20

MASTER LIST K1-73 K-E-P-D-K-J (AF) PREPARED MAY 1982

AL	PLAT-SN	DAIL	REC'D	RAS	ETI	UUT	HK5	SHIPD	DAS	W-U	350	612	612	TAG
LY				E	IN			ATE	FSH		H	H	A	
09	AF00020	77215		11N	1794	1831	0044	77220			UNK	246	A	NU 350 TAG
10	AF00020	77200		MCE	1846	1870	0017	77301		Y	290	780	F	2351192312
01	AF00020	73021		KUR	0417	0463	0000	73009	NEL		457	160	G	3472043209
02	AF00029	73204		11N	0697	0737	0234	73319	EGL		UNK	246	A	0003309362
03	AF00029	74196		EGL	0745	0835	0008	74249	DMN		374	YBM	F	1220115983
04	AF00029	76267		DMN	1730	1783	0895	76301	ENG	0	958	799	B	2576512783
01	AF00030	72215		MIL	0103	0165	0000	72237	ENG					
02	AF00030	73096		ENG	0170	0195	0005	73136	ENG		255	799	B	0682406056
03	AF00030	74176		ENG	0649	0693	0454	74212	KUR		UNK	051	G	0004200731
04	AF00030	76512		ENG	1391	1474	1198	76512	ENG		354	246	A	3550402191
01	AF00031	73016		UNK	0334	0364	0000	73035	ENG		UNK	FBA	F	NU 350 TAG
02	AF00032	77144		MIL	1950	2018	1592	77166	MIL					
01	AF00033	72257		11N	0109	0143	0000	72272	MIL					
02	AF00033	72348		DMN	0158	0202	0615	73081	ENG		246	A	A	3140352422
03	AF00033	73211		ENG	0327	0382	0125	74077	KUR		255	FBA	F	1950467524
01	AF00034	72319		MIL	0123	0184	0000	72333	KUR		799	B	B	2494018910
02	AF00034	73016		KUR	0207	0232	0023	73034	KUR		901	799	B	3492996734
03	AF00034	73360		KUR	0701	0740	0469	74024	11N		242	246	A	3320910102
04	AF00034	74067		KIN	0742	0797	0002	74064	KUR		290	246	A	0241331781
05	AF00034	76315		MIL	1750	1789	0933	76355	EGL	U	290	LBD	F	3022014711
06	AF00034	77103		EGL	1710	1936	0121	77111	MCE		958	086	K	0905067897
07	AF00034	77200		MCE	1998	2008	0062	77209		A	255	AAQ	G	1750161562

CAN G 1)

MASTER LIST K-1-73 K-F-P-U-R-I
PREPARED 02 MAY 20 (AF) PREPARED MAY 1982

PREPARED 02 MAY 20

PLAT-SN	DATE RECD	BAS E K	LT IN	EST OUT	HRS	SHIP ATE	BAS EST 13	W-U H H	350 H H	612 H H	612 A T	TAG
06	AF00034	78016	MMH	2020	2093	0042	78033	U	657	LU2	F	3567503914
09	AF00034	78318	TIN	2261	2299	0168	78340					
10	AF00034	79043	SFS	2314		0015						
01	AF00035	72242	UMH	0163	0196	0000	72266	TIN				
02	AF00035	72326	UBG	0246	0312	0052	72347	KUR				
03	AF00035	73302	KUR	0890	0931	0578	73340	MIL	242	051	G	0760831326
04	AF00035	74199	MTL	1133	1192	0202	74226	KUR	657	051	G	3320910102
05	AF00035	75022	KUR	1365	1421	0173	75034	KIC	UNK	246	A	1842591590
06	AF00035	75135	KIC	1455	1517	0034	75181	TIN	290	CB2	F	0024001005
07	AF00035	76183	MCE	1907	1941	0390	76216	ENG	UNK	AAU	G	1227502136
08	AF00035	77123	ENG	2204	2340	0343	77137	KIR	UNK	AAU	G	NU 350 TAG
01	AF00036	72221	UMH	0093	0131	0000	72235	MIL	652	246	K	1121258016
02	AF00036	72324	REL	0168	0198	0037	72343	UMH				
03	AF00036	73037	KUR	0202	0283	0004	73089	ENG	UNK	246	A	3561501756
04	AF00036	75058	KIC	0929	0975	0646	75074	KIR	UNK	070	G	0000000302
01	AF00037	73144	UMH	0403	0517	0030	73193	UMH	656	246	A	1280537920
02	AF00037	73346	UBG	0565	0604	0048	74024	TIN				
03	AF00037	75107	UMH	0977	1017	0373	75132	UMH	958	P50	G	2234140632
04	AF00037	75163	UMH	1075	1141	0058	75181	TIN	UNK	799	B	0980461349
05	AF00037	76121	SUU	2353	2381	1212	76132					
01	AF00038	73113	UMH	0414	0516	0000	73192	KUR	UNK	246	F	0003152482
02	AF00038	73221	KUR	0539	0581	0023	73236	KUR	242	296	A	2070000598

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MASTER LIST K-73 (AF) PREPARED MAY 1982

PREPARED 02 MAY 20

AL
CY

PLAT-SN	DATE RECD	BAS L K	ELL IN	ELL OUT	HRS	SHIPD ATE	BAS L K	W-U	350 H M	612 H M	612 A	TAG
03 AF00038	73271	KUR	0592	0631	0011	73296	DMN		799	086	A	2530911314
04 AF00038	73324	DMN	0652	0697	0021	73353	MIL		654	070	G	3060550564
05 AF00038	74023	MIL	0698	0732	0001	74038	TIN		242	A50	G	0041549027
06 AF00038	74067	KIR	0736	0807	0006	74122	DMN			GBZ	F	
07 AF00038	74255	DMN	0842	0863	0035	74266	ENG		654	246	A	1400553375
08 AF00038	75164	ENG	1234	1262	0371	75202	MIL	U	658	086	A	1750564251
09 AF00038	76076	MIL	1352	1444	0130	76093	KIR	U	657	F80	F	0642810460
10 AF00038	76181	KIR	1537	1581	0093	76212	MIL	D	UNK	599	G	NU 350 TAG
11 AF00038	76253	MIL	1591	1631	0010	76300	EVL	U	958	NPC	G	2432803171
12 AF00038	77045	EGL	1554	1707	0028	77055	ENG	F	UNK	799	B	0201502395
13 AF00038	78328	TIN	2390	2418	0683	78340						
01 AF00039	72339	EGL	0421	0482	0000	73016	KUR		799	B		
02 AF00039	73165	MIL	0651	0681	0169	73212	TIN		037	246	A	1562512755
03 AF00039	75224	MIL	1254	0000	0573	75303	ENG	U	652	Y80	F	2172812600
04 AF00039	76349	ENG	0460	0519	0460	77006	EGL	A	657	AAQ	G	3421115905
05 AF00039	77260	EGL	0759	0840	0280	77300		U	958	NPT	G	2642013579
06 AF00039	78134	ENG	0872	0909	0032	78136						
01 AF00040	72245	ENG	0095	0136	0000	72269	EGL					
02 AF00040	72349	EGL	0105	0223	0049	73024	ENG		799	B		
03 AF00040	74126	LTV	0464	0513	0241	74190	KIR		UNK	246	A	0004165186
04 AF00040	75072	KIR	0767	0925	0254	75139	KIC	U	654	H88	F	0511028790
05 AF00040	75216	KIC	0785	1036	0060	75272	TIN	U	037	H80	F	1977501705

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CAN 2)

MASTER LIST K-1-73 (AF) PREPARED MAY 1982

PREPARED BY MAY 20

AF	PLAT-ON	DATE REC'D	AS R	LT IN	LT OUT	IRS	SHIPD ATE	AS IP	W-U	350 M	612 M	612 T	TAG
06	AF00040	76126	ENG	1164	1208	0126	76208	MCE	U	656	MBO	F	1171229229
07	AF00040	76358	MIL	1390	1494	0130	77039	MIL	U	654	GBQ	F	3080171842
08	AF00040	76173		2030		0536	78181						
09	AF00041	76293	MIL	2045	2095		76324	ENG	D	657	799	B	2822816054
02	AF00041	77025	ENG	2156	2192	0061	77033	DES	D	290	086	A	0201326333
03	AF00041	78174		2690		0498	78181						
01	AF00042	72346	DMN	0254	0470	0000	73172	DMN					
02	AF00042	75237	ENG	1343	1411	0867	75294	ENG	D	658	RBD	F	2440503264
03	AF00042	76139	ENG	1611	1654	0200	76163	DMN	Y	127	086	K	1323250468
04	AF00042	76012	DMN	2588	2703	0934	78030		B	958	799	B	0120000012
01	AF00043	72205	DMN	0141	0192	0000	72271	NEK					
02	AF00043	76169	ENG	2095	0005	1910	76223	PIT	U	958	799	B	1757152825
01	AF00044	73106	ENG	0285	0328	0000	73170	HDM		242	160	F	0880002626
02	AF00044	74282	KIR	0356	0447	0508	75077	ENG	U	654	FBA	F	2630028447
03	AF00044	76167	ENG	1365	1431	0918	76198	DMN	U	127	NSM	G	1591255701
04	AF00044	76224	DMN	1446	1488	0015	76254	ENG	U	958	AAS	G	2116557238
01	AF00045	73072	DMN	0426	0498	0000	73114	DMN		654	246	A	0540606369
02	AF00045	73169	DMN	0530	0585	0032	73219	KUR		242	242	F	1550666774
03	AF00045	73201	KUR	0616	0667	0031	74042	TIN		242	LBA	F	2442501094
04	AF00045	74121	MIL	0697	0740	0030	74151	KUR			086	A	0772814223
05	AF00045	76007	KUR	1461	1514	0741	76019	ENG	U	654	246	A	3420608009
06	AF00045	76115	ENG	2226	2270	0712	76135						

PREPARED 02 MAY 20
 MASIRK LIST K1-73 (AF) PREPARED MAY 1982

K-E-P-U-W-I

PLAT-SN	DALL	RECU	BAS	LT	IN	KII	DOJ	HKS	SHIPD	BAS	W-U	350	612	612	TAG
			E						ATL	ESH		H	H	A	
01	AF00045	76180			2307			0037	76195			UNK	070	A	00033064303
02	AF00046	73204	NIL	0490	0524	0000		0000	73312	MIL					
03	AF00047	74055	080	0526	0500	0004		0004	74114	KIR			246	A	0144112154
04	AF00048	75309	KIR	1209	1245	0643		0643	75330	MTL	0	654	FBA	F	2801027861
05	AF00049	72334	ENG	0180	0212	0000		0000	72362	KUR					1676493925
06	AF00050	74068	KUR	0983	1690	0771		0771	74351	KUR		UNK	FBA	F	0722812096
07	AF00051	75094	KUR	1726	1765	0030		0030	75121	KUR	0	654	246	A	0710807059
08	AF00052	76181	DMN	2204	2261	0439		0439	76216	KIR	0	958	246	A	1676493925
09	AF00053	77272	KIR	2676	2731	0417		0417	77300		0	958	FBA	F	2434011272
10	AF00054	78244		2909	2943	0178		0178	78260						
11	AF00055	73144	INN	0211	0247	0000		0000	73236	KUR		654	NVF	F	0101258722
12	AF00056	73332	KUR	0343	0378	0096		0096	73353	KUR		242	051	G	3102804165
13	AF00057	74052	KUR	0380	0438	0002		0002	74070	KUR		255	246	A	0044001547
14	AF00058	77254	MCE	1746	1764	1308		1308	77270			UNK	NPC	G	2341101099
15	AF00059	72242	EGU	0161	0202	0000		0000	72258	DMN					
16	AF00060	75189	DMN	1199	1243	0997		0997	75231	INN	0	653	A40	F	1820495730
17	AF00061	76153	ENG	1407	1525	0244		0244	76180	MCE	0	656	DUM	G	1421117839
18	AF00062	77165	MCE	1407	1494	0347		0347	77193			654	ADS	G	NU 350 TAG
19	AF00063	78344	DMN	0434	0466	0000		0000	78371			242	246	K	0580609313
20	AF00064	74102	KIR	0782	0824	0316		0316	74142	HPT			246	A	
21	AF00065	72264	INN	0120	0206	0000		0000	73009	KCK					
22	AF00066	73060	NLL	0232	0265	0026		0026	73136	MTL		290	246	A	0430617984

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MASTER LIST RT-73 (AF) PREPARED MAY 1982

PREPARED 62 MAY 20

AF CY	PLAT-SN	DATE REC'D	WAS R	ETI IN	ETI OUT	HKS	SHIPD ATE	WAS ESH	W-U	350 H	612 H	612 A	TAG
03	AF00052	76064	PIT	1166	1221	0701	76105	ENG	A	609	LHJ	F	0554001117
04	AF00052	76229	ENG	1367	1393	0146	76260	TIN	U	658	749	B	1421165028
05	AF00052	76356	TIN	1395	1451	0002	77024	MFL	S	242	HBA	F	2016300027
06	AF00052	77161	MFL	1650	1658	0179	77179	MFL	U	657	749	B	1535532225
07	AF00052	76054	SFS	1854	1999	0196	78135		U	127	MAN	F	0410266194
08	AF00052	78275		2074	2108	0075	78285						
01	AF00053	72234	LIV	0109	0151	0000	72243	LUL					
02	AF00053	73196	TIN	0192	0233	0041	73229	MPT		242	246	K	0301255962
03	AF00053	74142	MPT	0319	0355	0066	74150	BUC			070	A	
04	AF00053	76035	BUC	0906	0977	0551	76093	KIC	U	255	CDA	F	0150503202
05	AF00053	77259	KIC	1269	0010	0292	77271		U	037	599	G	2437505030
01	AF00054	75055	MFL	1001	1039		75065	KUR	U	949	877	A	0442804293
02	AF00054	76161	EGU	1543	1594	0504	76212	LUL	U	958	799	B	1677146874
03	AF00054	78124	LUL	2211	2242	0617	78136						
04	AF00054	76341	KIC	2360	3046	0118	76355						
01	AF00055	72319	MEL	0103	0227	0000	72325	UMN					
04	AF00056	75220	PIT	1123	1170	0396	75246	LUG	U	037	CAQ	G	3014831619
05	AF00056	76111	ENG	1401	1450	0231	76120	TIN		UNK	ZDM	G	2054006387
01	AF00057	72334	ENG	0217	0270	0000	73031	KUR			374	F	ND 350 TAG
02	AF00057	73071	KUR	9330	0367	0060	73109	UMN		624	246	K	0512994046
03	AF00057	75352	UMN	1275	1311	0708	76005	TIN	U	958	JSD	G	3436554008
01	AF00056	74607	ENG	0701	0742	0000	74123	MFL			246	A	0630468011

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CAN # 1

MASTER LIST K1-73 (AF) PREPARED MAY 1982

PREPARED 02 MAY 80

PL	PLAT-SN	DATE RECD	HAS E K	ETI IN	ETI OUT	IRS	SHIPD ATE	HAS E K	H-U	350 H M	612 H M	612 A T	TAG
04	AF000058	74200	MTL	0774	0610	0032	74275	KIK		242	246	A	1552853546
05	AF000058	75217	KIK	1056	1123	0246	75303	ENG	U	240	LBA	F	1651028280
04	AF000058	77109	ENG	1331	1360	0208	77116	DMN	U	652	ADL	C	1041301588
01	AF000059	73003	DMN	0240	0277	0000	73031	DMN		037	086	A	3240598888
02	AF000059	77226		1952	2024	1675	77243			UNK	070	A	ND 350 TAG
01	AF000060	72500	ENG	0164	0194	0000	72505	TIN					
02	AF000060	73000	ENG	0308	0444	0114	73115	UOU		654	246	K	05800491503
03	AF000060	73191	UOU	0359	0397	0015	73223	KER		UNK	070	A	0046910235
04	AF000060	73263	KER	0404	1213	0007	74080	KUM			FBA	F	0003323197
05	AF000060	74212	KUM	1214	1236	0001	74234	DMN		799	246	A	0984005689
06	AF000060	76224	DMN	1301	1343	0065	77286		U	958	FBA	F	2116551825
07	AF000060	76192		1660		0317	78208						
06	AF000060	75053	TIN	1821	1850	1821	79059						
01	AF000061	74227	DMN	0101	0140		74269	TIN		607	086	K	1940602651
01	AF000062	73561	DMN	0565	0596	0000	74058	TIN		958	DMN	F	3470402308
07	AF000062	74259	MTL	0720	0753	0132	74277	KUM		652	799	B	2382424176
03	AF000062	76246	ENG	1427	1475	0074	76270	ENG	U	656	799	B	2316001360
04	AF000062	77252		1877	1922	0402	77260			UNK	ADG	C	ND 350 TAG
05	AF000062	78305		2336	2368	0414	78307						
01	AF000063	72249	DMN	0126	0153	0000	72263	ENG					
02	AF000063	76004	ENG	0661	0622	0208	76116	EGL		UNK	F8F	F	ND 350 TAG
03	AF000063	76343	EGL	1023	1072	0201	77005	TIN		958	246	A	3341102295

CAN # 11055

MAY 1982
K-E-P-U-K-I
AFJ PREPARED
LIST RT-73

PREPARED 02 MAY 20

AF CY	PLAT-SN	DATE RECD	PLAS E	RTI IN	OUT	MKS	SHIPD ATE	BAS EOM IP	W-U H	350 H	612 H	612 A	TAG
01	AF00004	72314	NEL	0222	0276	0000	72350	TIN			374	K	2864750118
02	AF00004	73264	DMR	0335	0377	0063	73325	DMN		654	799	B	2700426906
03	AF00004	74114	DMN	0524	0574	0147	74158	TIN			246	A	0980461825
04	AF00004	74227	MTL	0575	0577	0001	74263	ENG		242	799	B	1971512967
05	AF00004	75237	ENG	0827	0875	0250	75254	BUC	U	652	051	G	2100511422
06	AF00005	72276	EGL	0122	0157	0000	72290	TIN			374	F	2452503359
07	AF00005	72327	TIN	0162	0184	0005	72333	KUR					
08	AF00005	73254	KUR	0777	0826	0593	73282	NEL		958	246	A	2262979872
09	AF00005	75079	BUC	1295	1333	0469	75114	MTL	U	037	799	B	0670505696
10	AF00005	75209	MTL	1351	1408	0018	75259	KIR	U	657	F8A	F	1702818707
11	AF00005	76261	TIN	1218	1259	0110	76303	MTL		UNK	NSE	G	NU 350 TAG
12	AF00005	73225	EGL	0299	0334	0000	74038	DMN		255	FUA	F	2171252690
13	AF00006	74092	DMN	0368	0409	0034	74112	TIN			CAN	G	0800553844
14	AF00007	73093	LIV	0212	0348	0000	73214	KUR			246	A	2331500406
15	AF00007	73254	KUR	0355	0378	0007	73283	KUR		UNK	246	A	2331500406
16	AF00007	73334	KUR	0405	0451	0007	74003	KUR			799	B	2920908496
17	AF00007	74077	KUR	0453	0499	0002	74091	KUR			246	A	0264105741
18	AF00007	74134	KUR	0507	0545	0018	74218	ENG		UNK	051	G	1150644495
19	AF00007	74357	LHG	0560	0606	0015	75027	ENG		607	C50	G	2490084243
20	AF00007	75065	ENG	0677	0706	0001	75090	MTL	Y	037	799	B	0492261462
21	AF00007	77064	DES	0618	0660	0512	77129	EOM	U	561	F80	F	0740006907
22	AF00007	77265	EOM	0776	0830	0116	77272		D	242	AAQ	G	2447518200

PCN N114607

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PREPARED 02 MAY 20

MASTER LIST 8-1-73 K-F-P-U-W-I
(AF) PREPARED MAY 1982

AF CU	PLAT-3N	DATE RECU	WAS E K	LT IN	FT OUT	MKS	SMPO ATE	WAS E K	W-U	350 H H	612 H H	612 A T	TAG
10	AF00007	78132	WLS	0931	1025	0101	78179				799	B	3354765285
11	AF00008	78230	WLS	0317	0506	0000	73071	MTL		655	XUM	G	3030825179
12	AF00009	78312	MTL	0615	0648	0213	74010	MTL		UNK	N5D	G	NL 350 TAG
13	AF00010	78216	PIT	0129	0106		76247	ENG		958	246	A	0047122364
14	AF00011	77020	ENG	0203	0250	0017	77028	SJU	F	290	246	A	1193361260
15	AF00012	77152	SJU	0206	0339	0036	77164	PIT	F	656	799	B	1984052904
16	AF00013	77236	PIT	0437	0450	0058	77243						
17	AF00014	78072	MTL	0638		0240	78081						
18	AF00015	78137		0745	0802	0745	78166						
19	AF00016	78332	TIN	0883		0081	78363						
20	AF00017	78053		0845					0	127	000	F	3537502279
21	AF00018	78092	ENG	0122	0156		78056	MTL	Y	169	599	G	0343250737
22	AF00019	78133	MTL	0251	0309	0095	78160	WLN	A	657	086	K	1242427287
23	AF00020	78287	MTL	0415	0437	0106	78321	KIK	U	657	799	B	2792459613
24	AF00021	78072	KIK	0396		0459	78145						
25	AF00022	78016	ENG	0704	0801		78031		U	255	799	B	3560027708
26	AF00023	78182	KIK	0292	0307		78243	KIC	U	958	060	F	NL 350 TAG
27	AF00024	78016	KIC	0707	0748	0340	78030		U	037	799	B	3567506123
28	AF00025	78201		0826		0078	78216						
29	AF00026	77066	PIT	0365	0485		77116	ENG	U	037	N60	F	0504025290
30	AF00027	77137	ENG	0496	0601	0011	77182		Y	799	N6A	F	1303315783
31	AF00028	77315	PIT	0881	0725	0080	77325		U	037	799	B	2944076012

PLN N114007

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CAN # 11E5

B-L-1-33 M-E-P-U-R-T
HASTIER LIST K-1-33 (AF) PREPARED MAY 1982

PREPARED BY MAY 20

AL	PLAT-SG	DAIL	RECD	BAS	LT	OUT	INRS	SHIPO	BAS	W-U	350	612	612	TAG
CL				E	IN			ATE	LP	H	H	M	A	
04	AF00000	76061		PIT	0742	0775	0017	78060		U	652	799	B	3132805761
01	AF00000	76344		MIL	0324	0307		76355	DMN	U				
01	AF00000	77029		MIL	0307	0307		77040		U	657	799	B	2492634745
01	AF00000	77044		MIL	0347	0309	0000	77074	MIL	U	656	246	A	0461350519
02	AF00000	77193		MIL	0516	0506	0129	77260		U	657	680	F	1762627595
03	AF00000	77325		ULS	0572	0597	0006	77330		U	654	680	F	1260027590
04	AF00000	78053			0012	0040	0015	78074		U	656	680	F	0117508872
01	AF00000	78116		ULS	0700	0700	0140	78127		U	UNK	AAQ	G	3002604323
01	AF00000	77340		ULS	0220	0259	0000	77341		B	070	246	A	2361007343
02	AF00000	76245		ENG	0332	0391		76271	MCE	U	654	799	B	2800041337
03	AF00000	76336		MCE	0409	0458	0010	76352	ULS	U				
03	AF00000	76132		ULS	1024		0566	76143						
01	AF00000	76542		ULS	0123	0114		76548	PIL		UNK	NPC	G	ND 350 TAG
01	AF00000	77100		ENG	0436	0430	0000	77123	ENG	U	654	NPT	F	0941312123
02	AF00000	77200		MIL	0546	0609	0066	77207		U	255	246	A	1862752927
01	AF00000	76210		DMN	0121	0183		76231	MIL	Y	799	200	G	1777707823
02	AF00000	76313		MIL	0244	0276	0061	76348	PIT	U	657	350	G	2527809260
03	AF00000	77130		PIT	0419	0459	0123	77145	KIR	U	654	086	A	1244051761
01	AF00000	76210		ENG	0124	0197		76244	KIC	U	958	799	B	1637164624
02	AF00000	76334		KIC	0273	0304	0076	76363	MIL	U	037	799	B	3157512377
03	AF00000	76219			0779		0675	76298						
01	AF00000	78310		TIN	1510									

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AF00000 81021
 AF00000 80037
 AF00000 80037

APPENDIX C

K051 LOGISTIC SUPPORT COST BREAKDOWN

Explanation. The appendix contains extracts from the K051 Logistic Support Cost Breakdown for the A-7D MDS and WUC 73FAO (first column). The cost data (presented in dollars) represent quarterly totals for the quarter indicated by the "as of" date in the top left corner of each page. The data for trouble-shooting costs were found by locating the WUC 73FAO in column 1, verified by the noun "Unit Inertial M" in column 2, and looking under the column labeled "Field Maint." Transportation costs were found in the same way under the column labeled "Pack-Ship Cost." The entries used are identified by an "X" in the left-hand margin of each page.

FTI WEAPON SYSTEM A0070 OALC
AFN 65-110/66-1 DATA AS OF 81 SEP
LOGISTIC SUPPORT COST RANKING
LSC BREAKDOWN
LOG-LOG(0)753
Q-K051-FM-10-102
DATE PROCESSED

LINE	NOUN	FIELD MAINT	QUARTERLY VALUES			CONSERVATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73ECP	ASSY ANALOG OUT	\$250	\$672	\$2	\$0	\$0
73ECP	ASSY ANALOG IN	\$67	\$532	\$3	\$0	\$0
73ECP	ASSY RATE-DEFL	\$67	\$240	\$1	\$0	\$0
73ECP	ASSY FUNCTION C	\$67	\$0	\$0	\$0	\$0
73ECP	ASSY CLOCK JUNK	\$701	\$672	\$3	\$0	\$0
73ECP	IN ELECT EQUIP	\$803	\$0	\$0	\$0	\$0
73ECP	ASSY FAN	\$805	\$0	\$0	\$0	\$0
73ECP	WIRING COMB PI	\$1,063	\$0	\$0	\$0	\$0
73ECP		\$132,213	\$42,650	\$1,459	\$430	
73F00	INERTIAL REURCH	\$50,021	\$0	\$0	\$0	\$0
73F00	INERTIAL M	\$101,357	\$239,626	\$2,041	P	\$0
73F00	INERTIAL M	\$54	\$0	\$0	\$0	\$0
73F00	CORD CARI	\$920	\$13,499	\$71	\$0	\$0
73F00	MODULE GINER L	\$172	\$3,072	\$11	\$0	\$0
73F00	MODULE RIR SUP	\$315	\$3,163	\$9	\$0	\$0
73F00	MODULE FUSE SH	\$220	\$1,715	\$3	\$0	\$0
73F00	ACCELERATOR K-Y	\$12	\$0	\$0	\$0	\$0
73F00	BACK FLEC EQUIP	\$1,356	\$0	\$0	\$0	\$0
73F00	CONTROLLER IHS	\$2,073	\$178	\$4	\$0	\$0
73F00	EC	\$20	\$0	\$0	\$0	\$0
73F00	ASSY RECON-MCAL	\$22	\$0	\$0	\$0	\$0
73F00	RIGHT PHEL	\$173	\$0	\$0	\$0	\$0
73F00	ALPHA PIR SP LS	\$56,216	\$30,670	\$675	\$0	\$0
73F00	PIR	\$56	\$0	\$0	\$0	\$0
73F00	CARD SEQUENCER	\$433	\$595	\$3	\$0	\$0
73F00	CARD SEQUENCER	\$114	\$296	\$3	\$0	\$0
73F00	MODULE R00 J2	\$106	\$21	\$2	\$0	\$0
73F00	MODULE HEAD REP	\$3,972	\$6,203	\$102	\$0	\$0
73F00	MODULE RELAY DR	\$5	\$0	\$0	\$0	\$0
73F00	CARD RELAY DRIV	\$153	\$500	\$3	\$0	\$0
73F00	CARD RELAY DRIV	\$261	\$72	\$0	\$0	\$0
73F00	MODULE ROL-PTIC	\$273	\$0	\$0	\$0	\$0
73F00	PRIMER ATTACHE	\$120	\$0	\$0	\$0	\$0
73F00	POWER SUPPLY	\$143	\$0	\$13	\$0	\$0
73F00	CARD PIR SUPPLY	\$2,052	\$1,166	\$8	\$0	\$0
73F00	CARD PIR SUPPLY	\$1,300	\$1,750	\$14	\$0	\$0
73F00	PIR PIR SUPPLY	\$57	\$0	\$0	\$0	\$0

WEAFCO SYSTEM: AFM70, CIALC
AFM 65-110/66-1 DATA AS OF 81 JUN

QUARTERLY VALUES-
PACK-SIZE
COST

HTT
 WEAPON SYSTEM A007D OALC
 AFM 65-110/66-1 DATA AS OF 81 MAR
 LOGISTIC SUPPORT COST RANKING
 LSC BREAKDOWN
 LOG-LO(0)7953
 a. P(0)51--PRG--LO-M/L
 DATE PROCESSED

QUARTERLY VALUES					
WUC	NOUN	FIELD	SPEC RETAIN	PACK-SHIP	CONDENSED COST
		MAINT	COST	COST	COST
736C1	ASSY CORE PLANE	\$140	\$171	\$1	\$0
736C2	ASSY ANALOG OUT	\$73	\$801	\$2	\$0
736C3	ASSY ANALOG IN	\$36	\$280	\$1	\$0
736C4	ASSY RATE-DEFL	\$70	\$0	\$0	\$0
736C5	ASSY FUNCTION C	\$56	\$223	\$1	\$0
736C6	ASSY CLOCK CHCK	\$138	\$444	\$1	\$0
736C7	ASSY PROGRAM C	\$73	\$270	\$1	\$0
736C8	PIR SUPPLY LOU	\$80	\$0	\$0	\$0
736C9	PIR SUPPLY EQUIP	\$143	\$0	\$0	\$0
736CA	ASSY FCR	\$709	\$0	\$0	\$0
736D0	HINDING COUS P1	\$1,114	\$0	\$0	\$0
736X		\$126,502	\$72,831	\$2,697	\$0
736D0	INERTIAL INSURIN	\$50,573	\$0	\$0	\$0
736A0	UNIT INERTIAL H	\$95,230	P \$161,777	\$1,951	P \$0
736F9	ROC	\$269	\$0	\$0	\$0
736F0	FORWARD CANN	\$1,016	\$11,099	\$9	\$0
736F1	MIDDLE GUN L	\$230	\$8,232	\$16	\$0
736F2	MIDDLE PIR SUP	\$50	\$1,424	\$5	\$0
736F3	MIDDLE CODE SW	\$276	\$2,861	\$5	\$0
736F4	BACK ELEC EQUIP	\$702	\$0	\$0	\$0
736F5	CONTROLLER INS	\$1,995	\$504	\$9	\$0
736F6	ROC	\$157	\$0	\$0	\$0
736F7	FRONT PANEL	\$201	\$0	\$0	\$0
736F8	FORWARD PIR SP LS	\$70,698	\$10,969	\$213	\$0
736F9	ROC	\$51	\$0	\$0	\$0
736D9	CARD SEQUENCER	\$342	\$919	\$6	\$0
736D0	CARD SEQUENCER	\$620	\$1,166	\$7	\$0
736D1	MODULE 800 NL	\$113	\$877	\$2	\$0
736D2	MODULE HEAD REP	\$2,597	\$843	\$16	\$0
736D3	MODULE RELAY DR	\$24	\$0	\$0	\$0
736D4	CARD RELAY DR	\$334	\$535	\$1	\$0
736D5	CARD RELAY RELV	\$77	\$744	\$2	\$0
736D6	MODULE ROL-PITC	\$409	\$0	\$0	\$0
736D7	RELIVER ATTACHE	\$194	\$0	\$0	\$0
736D8	POWER SUPPLY	\$41	\$178	\$7	\$0
736D9	CARD PIR SUPPLY	\$473	\$1,072	\$16	\$0
736E0	CARD PIR SUPPLY	\$424	\$445	\$7	\$0

LOGISTIC SUPPORT UNIT WORKING
USC REPAIR BATT
LOS ANGELES 94

NO	NAME	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUE		INFORMATION COST
				PACK-CHIP COST		
73E7	INS UNIT HEADSU	\$20,075	\$118,032	\$4,397		\$0
73E8	NOC	\$31	\$0	\$0		\$0
73E9	PHONE OPTICAL	\$61	\$0	\$0		\$0
73EA	ASSY COMBINER	\$19	\$0	\$0		\$0
73EB	ASSY CONTROL PA	\$274	\$0	\$0		\$0
73EC	ASSY TUBE UNIT	\$521	\$3,792	\$24		\$0
73ED	ASSY CATHODE RA	\$109	\$1,264	\$8		\$0
73EE	ASSY CRT MATCHI	\$17	\$115	\$0	P	\$0
73EF	FOR SUPPLY HIGH	\$782	\$1,080	\$20		\$5,500
73EG	AMPLIFIER DEFLEC	\$516	\$424	\$3		\$0
73EH	ASSY VIDEO	\$232	\$555	\$2		\$0
73EI	ASSY BITE	\$308	\$562	\$6		\$0
73EJ	PHR SUPPLY LOW V	\$7,429	\$0	\$0		\$0
73EK	PRINT CIR BRD IN	\$988	\$1,471	\$14		\$0
73EL	CIR BRD CR AMP/	\$373	\$1,086	\$4		\$0
73EM	CIR BRD OUTPUT R	\$760	\$1,200	\$16		\$0
73EN	ASSY ELECTRONIC	\$63	\$0	\$0		\$0
73EO	ASSY RECTIFIER B	\$281	\$252	\$0	P	\$0
73EP	SIGNAL DATA PRO	\$21,989	\$4,902	\$95		\$0
73EQ	ASSY DATA INPUT	\$128	\$140	\$1		\$0
73ER	ASSY ADDER/HOMO	\$97	\$0	\$0		\$0
73ES	ASSY PROCESSOR C	\$109	\$202	\$2		\$0
73ET	ASSY DISCRETE I	\$24	\$121	\$1		\$0
73EU	ASSY INSTRUCTION	\$48	\$0	\$0		\$0
73EV	ASSY STR CONT P	\$86	\$0	\$0	P	\$0
73EX		\$135,571	\$137,876	\$4,007		\$1,242
73EY	INERTIA MOUNTING	\$69,401	\$0	\$0		\$0
73EZ	UNIT INERTIAL M	\$124,926	\$256,431	\$2,848		\$0
73FA	NOC	\$12	\$0	\$0		\$0
73FB	BOARD CAPOT	\$307	\$1,482	\$1		\$0

K11
 WEAPON SYSTEM '007D OALC
 AFM 55-110/66-1 DATA AS OF 10 JUN
 LOGISTIC SUPPORT COST RANKING
 LSC BREAKDOWN
 LOG-LO(Q)7953
 0-1051-PH4-LQ-P
 DATE PROCESSED

WUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDEMNATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EDH	ASSY INSTRUCTION	\$12	\$0	\$0	\$0	\$0
73EDJ	ASSY STR CONT R	\$128	\$0	\$0	\$0	\$0
73EDK	ASSY DRIVE TRAN	\$82	\$181	P	\$1	\$0
73EDL	ASSY STORE CONT	\$72	\$256		\$1	\$0
73EDP	ASSY ANALOG OUT	\$104	\$1,764		\$5	\$0
73EDQ	ASSY ANALOG INP	\$36	\$252		\$1	\$0
73EDR	ASSY RATE-DEFL	\$61	\$0		\$0	\$0
73EDS	ASSY OVERFLOW R	\$41	\$146		\$0	\$0
73EDT	ASSY FUNCTION C	\$48	\$0		\$0	\$0
73EDU	ASSY CLOCK CHCK	\$456	\$360		\$1	\$0
73EDV	ASSY PARAMETR C	\$61	\$0		\$0	\$0
73EDZ	PWR SUPPLY LOU	\$92	\$0		\$0	\$0
73ECU	HI ELECT EQUIPM	\$1	\$0		\$0	\$0
73ECA	ASSY FAN	\$48	\$0		\$0	\$0
73ED0	WIRING CONNS PL	\$596	\$0		\$0	\$0
73EXX		\$148,829	\$127,349	\$3,608		\$8
73F00	INERTIAL MSURMN	\$84,573	\$0	\$0	\$0	\$0
73FA0	INIT INERTIAL M	\$132,477	\$273,409	\$3,134	\$0	\$0
73FA2	MOC	\$162	\$0	\$0	\$0	\$0
73FAD	BOARD CAPRI	\$624	\$888	\$1	\$0	\$0
73FAE	MODULE GICBAL L	\$293	\$4,263	\$9	\$0	\$0
73FAF	MODULE PWR SUP	\$279	\$1,340	\$5	\$0	\$0
73FAG	MODULE MODE SHI	\$291	\$2,259	\$0	\$0	\$0
73FEO	PACK ELEC EQUIP	\$1,273	\$0	\$0	\$0	\$0
73FEO	CONTROLLER IMS	\$3,171	\$1,630	\$20	\$0	\$0
73FEB	FRONT PANEL	\$424	\$0	\$0	\$0	\$0
73FEO	ADPTR PWR SP LS	\$92,867	\$28,477	\$491	\$0	\$0
73F02	MOC	\$259	\$0	\$0	\$0	\$0
73FDA	MODULE SEQUENCE	\$12	\$233	\$1	\$0	\$0
73F08	CARD SEQUENCER	\$257	\$749	\$5	\$0	\$0
73F0C	CARD SEQUENCER	\$505	\$913	\$6	\$0	\$0
73F06	MODULE PWD HZ	\$79	\$240	\$2	\$0	\$0
73FDE	MODULE HEAD REP	\$8,344	\$6,462	\$94	\$1,334	\$0
73F0F	MODULE RELAY CR	\$43	\$359	\$5	\$0	\$0
73F0J	CARD RELAY DRV	\$406	\$1,070	\$6	\$0	\$0
73F0H	CARD RELAY DRV	\$421	\$1,573	\$5	\$0	\$0
73F0I	DELIVER AMPLIFIE	\$91	\$0	\$0	\$0	\$0

WEAPON SYSTEM		AFM 65-110/66-1 DATA AS OF 80 MAR		LOGISTIC SUPPORT COST RANKING		Q-KG51.-P/11.-Q-KGZ	
A007D		OCALC		LSC BREAKDOWN		DATE PROCESSED	
73EXX		73EXX		LOG-LO(Q)7953			
NUC		NOUN		FIELD MAINT		QUARTERLY VALUES	
						PACK-SHIP COST	
						CONDENIATION COST	

DTI
 WEAPON SYSTEM A007D OALC
 APP 6-110766-1 DATA AS OF 79 DEC
 LOGISTIC SUPPORT COST RANKING
 LSC BREAKDOWN
 LOG-LO(Q)7953
 Q-K051--PN4-LQ-PQZ
 DATE PROCESSED

WUC	NOUN	QUARTERLY VALUES			CONDEMNATION COST
		FIELD MAINT	SPEC REPAIR COST	PACK-SHIP COST	
73EAV	CIR DRD ER AMP/	\$384	\$2,033	\$9	\$41
73EAM	CIR BRD OUTPT R	\$580	\$1,372	\$17	\$100
73EB0	SIGNAL DATA PRO	\$17,087	\$6,975	\$182	\$0
73EB9	NOC	\$33	\$0	\$0	\$0
73EBA	ASSY DATA INPUT	\$21	\$296	\$2	\$0
73EBB	ASSY ADDER/MEMO	\$172	\$0	\$0	\$0
73EBC	ASSY PROCESOR C	\$16	\$202	\$3	\$0
73EDE	ASSY DISCRETE I	\$16	\$121	\$2	\$0
73EBH	ASSY INSTRUCTION	\$181	\$525	\$3	\$0
73EDJ	ASSY STR CONT R	\$82	\$0	\$0	\$0
73EDL	ASSY STORE CONT	\$16	\$0	\$0	\$0
73EBP	ASSY ANALOG OUT	\$7	\$568	\$2	\$0
73EBQ	ASSY ANALOG INP	\$92	\$246	\$5	\$0
73EBR	ASSY RATE-DEFL	\$13	\$324	\$3	\$0
73EBS	ASSY OVERFLOW R	\$41	\$0	\$1	\$0
73EDT	ASSY FUNCTION C	\$33	\$134	\$1	\$0
73EDU	ASSY CLOCK CHEK	\$114	\$684	\$2	\$0
73EBV	ASSY PARAMETR C	\$8	\$135	\$1	\$0
73ECO	MT ELEC EQUIPM	\$866	\$0	\$0	\$0
73ECA	ASSY FAN	\$57	\$0	\$0	\$0
73ED0	WIRING CONNS PI	\$565	\$0	\$0	\$0
73EXX		\$109,909	\$172,860	\$6,785	\$1,264
73F00	INERTIAL MSURN	\$53,750	\$2,213	\$66	\$0
73FAD	UNIT INERTIAL M	\$65,264	\$154,714	\$2,822	\$0
73FAD	BOARD CAPRI	\$362	\$6,398	\$88	\$0
73FAE	MODULE GIBBAL L	\$238	\$2,006	\$9	\$0
73FAF	MODULE PWR SUP	\$662	\$4,560	\$17	\$0
73FAG	MODULE MODE SWI	\$431	\$2,325	\$7	\$0
73FAD	GYROSCOPE 2 AXIS	\$230	\$0	\$0	\$0
73FAU	AUX IMP CONT AM	\$13	\$0	\$0	\$0
73FAV	CLSTR CONT TMPT	\$16	\$0	\$0	\$0
73FBD	BACK ELEC EQUIP	\$701	\$0	\$0	\$0
73FCD	CONTROLLER IMS	\$1,123	\$331	\$6	\$0
73FCA	FRONT PANEL	\$453	\$0	\$0	\$0
73FBD	ADPTR PWR SP LS	\$61,505	\$27,287	\$541	\$0
73.09	NOC	\$41	\$0	\$0	\$0
73FDB	CARD SEQUENCER	\$110	\$530	\$5	\$0

WEAPON SYSTEM		ADDTD	OCALC	LOGISTIC SUPPORT COST RANVING		QUARTERLY VALUES		DATE PROCESSED	
AFM 45-110/66-1		DATA AS OF 79 SEP		LSC BREAKDOWN		PACK-SHIP COST			
MUC	NGUIN	FIELD MAINT	SPEC REPAIR COST	CONDENATION COST					
73EAS	ASSY RTE	\$369	\$4,157	\$0					
73EAT	PWR SUPPLY LOW V	\$4,016	\$1,120	\$158					\$28
73EAD	PRNT CIR BPD IN	\$317	\$842	\$12					\$114
73EAV	CIR BRD ER AMP/	\$305	\$1,418	\$7					\$44
73EAW	CIR BRD OUTPT R	\$190	\$980	\$11					\$142
73EAY	SENSOR AUTO BRI	\$66	\$0	\$0					\$0
73EBQ	SIGNAL DATA PRO	\$24,680	\$5,648	\$145					\$0
73EBT	CIRCUIT BOARD R	\$107	\$146	\$1					\$0
73EB4	ASSY RECTIFIER B	\$8	\$0	\$0	P				\$0
73EBA	ASSY DATA INPUT	\$45	\$151	\$0	P				\$0
73EBB	ASSY ADDER/MEMO	\$126	\$596	\$2	P				\$0
73EBC	ASSY PROCESOR C	\$54	\$404	\$6					\$0
73ECE	ASSY DISCRETE I	\$16	\$122	\$2					\$0
73EBH	ASSY INSTRUCTION	\$61	\$652	\$4					\$0
73EBJ	ASSY STR CONT R	\$172	\$127	\$1	P				\$0
73EBK	ASSY DRIVER TRAN	\$60	\$784	\$4					\$0
73EBL	ASSY STORE CONT	\$54	\$858	\$3					\$0
73EBM	ASSY CORE PLANE	\$24	\$117	\$1					\$0
73EBP	ASSY ANALOG OUT	\$414	\$2,556	\$10					\$517
73EBQ	ASSY ANALOG INP	\$163	\$2,765	\$3					\$0
73EBR	ASSY RATE-DEFL	\$567	\$2,716	\$4	P				\$0
73EBS	ASSY OVERFLOW R	\$76	\$669	\$3					\$0
73EBT	ASSY FUNCTION C	\$71	\$134	\$1					\$0
73EBU	ASSY CLOCK REF	\$26	\$518	\$3					\$0
73EBV	ASSY PARAMETR C	\$24	\$0	\$0					\$0
73ECO	MT ELECT EQUIPH	\$711	\$0	\$0					\$0
73ECA	ASSY FAN	\$117	\$0	\$0					\$0
73ECG	WIRING CONNS CI	\$325	\$2,157	\$44					\$0
73EYV		\$116,180	\$175,019	\$6,110					\$889
73ECC	INERTIAL MOUNTING	\$63,432	\$2,157	\$44	P				\$0
73EAD	UNIT INERTIAL M	\$97,117	\$286,560	\$5,129					\$0
73EAG	NOG	\$56	\$0	\$0					\$0
73EAF	BOARD CAPRI	\$287	\$5,355	\$5					\$0
73EAF	MODULE CTRBAT I	\$425	\$6,966	\$29					\$0
73EAF	MODULE PWR SUP	\$238	\$3,432	\$11					\$0
73EAG	MODULE MODE CUI	\$169	\$2,574	\$7					\$0
73EAF	ACCUMTER 2 AXIS	\$41	\$0	\$0					\$0

C11
 WEAPON SYSTEM A0070 OALC
 AFM 65-110766-1 DATA AS OF 79 JUN
 LOGISTIC SUPPORT COST RANKING
 CURRENT QUARTER COMPUTATION
 2-K051-PNC-LQ-M02
 DATE PROCESSED

MUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDEMNATION COST
			SPEC. REPAIR COST	PACK-SHIP COST		
73EBC	ASSY PROCESOR C	\$8	\$208	\$3	\$0	\$0
73EBE	ASSY DISCRETE I	\$10	\$93	\$2	\$122	\$0
73EBH	ASSY INSTRUCTION	\$94	\$360	\$2	\$0	\$0
73EBJ	ASSY STR COP R	\$304	\$128	\$1	\$0	\$0
73EBK	ASSY DRIVER TRAN	\$115	\$921	\$4	\$0	\$0
73EBL	ASSY STORE CONT	\$181	\$873	\$3	\$0	\$0
73EBM	ASSY CORE PLANE	\$149	\$329	\$3	\$1,714	\$0
73EBP	ASSY ANALOG OUT	\$312	\$2,166	\$7	\$0	\$0
73EBQ	ASSY ANALOG INP	\$140	\$528	\$2	\$0	\$0
73EBR	ASSY RATE-DEFL	\$25	\$666	\$2	\$0	\$0
73EBT	ASSY FUNCTION C	\$49	\$0	\$2	\$0	\$0
73EBU	ASSY CLOCK CHEK	\$115	\$378	\$2	\$0	\$0
73EBX	PHR SUPPLY 5 VOL	\$112	\$0	\$0	\$0	\$0
73EBZ	PHR SUPPLY LOW	\$8	\$242	\$5	\$0	\$0
73ECD	MT ELECT EQUIPM	\$1,450	\$0	\$0	\$0	\$0
73ECA	ASSY FAN	\$230	\$0	\$0	\$0	\$0
73EEO	WIPIG CONNS PI	\$1,832	\$0	\$0	\$0	\$0
73EXX		\$110,283	\$120,190	\$5,976	\$2,337	\$0
73F00	INERTIAL MSURMH	\$58,631	\$0	\$0	\$0	\$0
73F0A	UNIT INERTIAL M	\$69,190	\$184,295	\$3,505	\$0	\$0
73F09	NOC	\$54	\$0	\$0	\$0	\$0
73F0D	BOARD CAPRI	\$125	\$1,750	\$2	\$0	\$0
73F0E	MODULE GIMBAL L	\$218	\$2,113	\$10	\$0	\$0
73F0F	MODULE PNP SUP	\$22	\$666	\$6	\$0	\$0
73F0G	MODULE MODE SWI	\$74	\$1,492	\$4	\$0	\$0
73F0H	RACK ELEC EQUIP	\$796	\$0	\$0	\$0	\$0
73F0I	CONTROLLER IMS	\$2,639	\$812	\$13	\$0	\$0
73F0J	NOC	\$148	\$0	\$0	\$0	\$0
73F0B	FRONT PANEL	\$110	\$0	\$0	\$0	\$0
73F0N	ADPTR PWR SP LS	\$47,539	\$11,024	\$351	\$0	\$0
73F09	NOC	\$450	\$0	\$0	\$0	\$0
73F0B	CARD SEQUENCER	\$274	\$417	\$3	\$0	\$0
73F0C	CARD SEQUENCER	\$413	\$904	\$6	\$0	\$0
73F0D	MODULE 800 HZ	\$523	\$530	\$8	\$0	\$0
73F0E	MODULE HEAD REP	\$4,665	\$6,982	\$145	\$0	\$0
73F0G	CARD RELAY DRIV	\$53	\$372	\$1	\$0	\$0
73F0H	CARD RELAY DRIV	\$50	\$150	\$1	\$0	\$0
73F0I	POWER SUPPLY	\$82	\$0	\$0	\$0	\$0

C11
 WEAPON SYSTEM A007D OCALC K051.PN44
 AFM 65-110/66-1 DATA AS OF 78 DEC DATE PROCESSED

LOGISTIC SUPPORT COST RANKING
 CURRENT QUARTER COMPUTATION

HUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDENSATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EBL	ASSY STORE CONT	\$85	\$1,460	\$5	\$0	
73EBM	ASSY CORE PLANE	\$56	\$348	\$5	\$0	
73EDP	ASSY ANALOG GJT	\$280	\$2,504	\$9	\$2,720	
73EDQ	ASSY ANALOG INP	\$315	\$1,064	P	\$0	
73EDR	ASSY RATE-DEFL	\$300	\$1,998	P	\$0	
73EDS	ASSY OVERFLOW R	\$57	\$304	\$2	\$0	
73EBT	ASSY FUNCTION C	\$57	\$129	\$1	\$0	
73EDU	ASSY CLOCK CHEK	\$93	\$1,330	\$7	\$0	
73EBX	PUR SUPPLY 5 VOL	\$49	\$398	\$11	\$0	
73EBZ	PUR SUPPLY LON	\$66	\$244	\$5	\$0	
73ECO	MT ELEC EQUIPM	\$1,162	\$0	\$0	\$0	
73ECA	ASSY FAN	\$138	\$0	\$0	\$0	
73EEO	WIRING CONNS PI	\$120	\$0	\$0	\$0	
73EXX		\$137,712	\$210,294	\$5,725	\$16,019	
73FDO	INERTIAL MSURMN	\$52,836	\$0	\$0	\$0	
73FAO	UNIT INERTIAL M	\$94,732	\$206,724	\$3,932	\$0	
73FA9	NOC	\$155	\$0	\$0	\$0	
73FAD	BOARD CAPRI	\$134	\$4,542	\$0	\$0	
73FAE	MODULE GIMBAL L	\$216	\$3,598	\$21	\$0	
73FAF	MODULE PWR SUP	\$139	\$3,327	\$21	\$0	
73FAG	MODULE MODE SWI	\$121	\$1,605	\$5	\$0	
73FAP	GYROSCOPE X-Y AX	\$36	\$0	\$0	\$0	
73FBO	RACK ELEC EQUIP	\$889	\$1,047	\$44	\$0	
73FCO	CONTROLLER IMS	\$2,804	\$2,802	\$38	\$0	
73FC9	NOC	\$5	\$0	\$0	\$0	
73FCB	FRONT PANEL	\$131	\$0	\$0	\$0	
73FDO	ADPTR PWR SP LS	\$58,723	\$8,756	\$352	\$0	
73FD9	NOC	\$273	\$0	\$0	\$0	
73FDB	CARD SEQUENCER	\$115	\$1,088	\$9	\$0	
73FDC	CARD SEQUENCER	\$122	\$1,078	\$7	\$0	
73FDD	MODULE 800 HZ	\$118	\$395	\$4	\$0	
73FDE	MODULE HEAD REP	\$4,627	\$9,828	\$180	\$0	
73FDG	CARD RELAY DRIV	\$126	\$1,103	\$12	\$0	
73FDH	CARD RELAY DRIV	\$29	\$830	\$5	\$0	
73FDK	DRIVER AMPLIFIE	\$24	\$468	\$5	\$0	
73FDM	CARD PWR SUPPLY	\$133	\$4,836	\$36	\$0	
73FDN	CARD PWR SUPPLY	\$13	\$95	\$2	\$0	
73FDP	CARD PWR SUPPLY	\$31	\$270	\$9	\$0	

G11
WEAPON SYSTEM A007D OCALC
AFM 65-110/66-1 DATA AS OF 78 SEP

K051.PNLM
DATE PROCESSED

LOGISTIC SUPPORT COST RANKING
CURRENT QUARTER COMPUTATION

MUC	MOUN	FIELD MAINT	QUARTERLY VALUES			CONDENATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EBU	ASSY CLOCK CHEK	\$1,503	P	\$1,779	P	\$14
73EBV	ASSY PARAMETR C	\$22		\$146		\$0
73EDX	PHR SUPPLY 5 VOL	\$107		\$0		\$0
73EBZ	PHR SUPPLY LOW	\$16		\$0		\$0
73ECO	MT ELECT EQUIPM	\$1,184		\$0		\$0
73ECA	ASSY FAN	\$373		\$0		\$0
73EEO	WIRING CONNS PI	\$670		\$0		\$0
73EXX		\$146,171	\$141,953	\$4,635		\$6,704
73F00	INERTIAL MSURN	\$61,925		\$6,455		\$0
X 73FAO	UNIT INERTIAL M	\$98,908		\$280,665		\$0
73FA9	NOC	\$57		\$0		\$0
73FAD	BOARD CAPRI	\$306		\$3,414		\$0
73FAE	MODULE GIMBAL L	\$178		\$1,072		\$0
73FAF	MODULE PHR SUP	\$85		\$2,562		\$0
73FAG	MODULE MODE SHI	\$118		\$1,360		\$0
73FBO	RACK ELEC EQUIP	\$864		\$0		\$0
73FCO	CONTROLLER IMS	\$2,716		\$1,386		\$0
73FC9	NOC	\$123		\$0		\$0
73FCB	FRONT PANEL	\$159		\$0		\$0
73FDO	ADPTR PHR SP LS	\$63,985		\$19,726		\$0
73FD9	NOC	\$488		\$144		\$0
73FDB	CARD SEQUENCER	\$152		\$810		\$0
73FDC	CARD SEQUENCER	\$273	P	\$2,090	P	\$0
73FDD	MODULE 800 HZ	\$127		\$2,099		\$0
73FDE	MODULE HEAD REP	\$4,598	P	\$10,715	P	\$0
73FDF	MODULE RELAY DR	\$16	P	\$460	P	\$0
73FDG	CARD RELAY DRIV	\$196		\$1,322		\$0
73FDH	CARD RELAY DRIV	\$170		\$1,835		\$0
73FDJ	MODULE ROL-PTC	\$381		\$0		\$0
73FDK	DRIVER AMPLIFIE	\$105		\$0		\$0
73FDM	CARD PHR SUPPLY	\$282		\$2,016		\$0
73FDN	CARD PHR SUPPLY	\$57		\$312		\$0
73FDP	CARD PHR SUPPLY	\$65		\$222		\$0
73FDQ	CARD PHR SUPPLY	\$250		\$2,576		\$0
73FDR	CARD PHR SUPPLY	\$29		\$95		\$0
73FDT	FOOTER BOARD CL	\$16		\$65		\$0
73FDU	FOOTER BOARD MO	\$115		\$144		\$0
73FEO	MOUNT ADPT/PS	\$209		\$0		\$0
73FFO	BATTERY PACK IM	\$255		\$0		\$0

WEAPON SYSTEM A0070 OALC LOGISTIC SUPPORT COST RAKING K051.PM4M
 AFM 65-110/66-1 DATA AS OF 78 JUN CURRENT QUARTER COMPUTATION DATE PROCESSED

MUC	NOUN	FIELD MAINT	QUARTERLY VALUES			DEMATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73ED0	WIRING CONNS PI	\$245	\$0	\$0	\$0	\$0
73EXX		\$86,843	\$115,220	\$2,625		\$4,407
73F00	INERTIAL MSURMN	\$56,783	\$0	\$0		\$0
73FAD	UNIT INERTIAL M	\$72,248	\$271,526	\$3,096		\$0
73FAD	BOARD CAPRI	\$235	\$6,567	\$0		\$0
73FKE	MODULE GIBBAL L	\$175	\$2,065	\$11		\$0
73FAF	MODULE PNR SUP	\$258	\$2,659	\$13		\$0
73FAG	MODULE MODE SNI	\$18	\$222	\$1		\$0
73FAK	PLENUM	\$21	\$177	\$2		\$0
73FAR	ACCLMTR ELECTRM	\$14	\$0	\$0		\$0
73FAT	GMLE TNP CONT	\$18	\$0	\$0		\$0
73FNO	RACK ELEC EQUIP	\$923	\$0	\$0		\$0
73FC0	CONTROLLER IMS	\$1,700	\$796	\$10		\$0
73FC9	HOC	\$14	\$0	\$0		\$0
73FC0	FRONT PANEL	\$56	\$0	\$0		\$0
73FD0	ADPTR PNR SP LS	\$41,742	\$14,928	\$396	P	\$0
73FD9	MOC	\$179	\$0	\$0		\$0
73FDA	MODULE SEQUENCE	\$63	\$0	\$0		\$0
73FDD	CARD SEQUENCER	\$119	\$798	\$5		\$0
73FDC	CARD SEQUENCER	\$111	\$1,032	\$5		\$0
73FDB	MODULE 800 HZ	\$174	\$832	\$4		\$0
73FDE	MODULE HEAD REP	\$1,297	\$5,746	\$84		\$0
73FDF	MODULE RELAY DR	\$108	\$0	\$0		\$0
73FDG	CARD RELAY DRIV	\$329	\$1,373	\$10		\$0
73FDH	CARD RELAY DRIV	\$81	\$865	\$4		\$0
73FDL	POWER SUPPLY	\$29	\$804	\$1		\$0
73FDH	CARD PNR SUPPLY	\$102	\$1,099	\$17		\$0
73FDN	CARD PNR SUPPLY	\$27	\$333	\$5		\$0
73FDP	CARD PNR SUPPLY	\$28	\$137	\$3		\$0
73FDB	CARD PNR SUPPLY	\$111	\$1,261	\$16		\$0
73FDR	CARD PNR SUPPLY	\$14	\$97	\$2		\$0
73FDS	MODULE BITE	\$25	\$240	\$2		\$0
73FDO	MOTHER BOARD HO	\$28	\$0	\$0		\$0
73FEO	MOUNT ADPT/PS	\$67	\$0	\$0		\$0
73FFD	BATTERY PACK IM	\$126	\$0	\$0		\$0
73F60	WTR REMOTE COM	\$2,335	\$286	\$8		\$0
73FMO	WIRING CONNS PI	\$3,907	\$0	\$0		\$0

P 11
 WEAPON SYSTEM A007D OALC LOGISTIC SUPPORT COST BREAKDOWN KCS LOG-MMO(Q17213(3)) KCS1.PN4L
 AFM 65-110/66-1 DATA AS OF 78 MAR CURRENT QUARTER COMPUTATION DATE PROCESSED

WUC	HCJN	FIELD MAINT	QUARTERLY VALUES			COMPLETION
			SPEC REPAIR COST	PACK-SHIP COST		
73EAW	CIR BRD QUIPT R	\$337	\$2,777	\$20	\$0	\$0
73EAY	SENSOR AUTO BRI	\$14	\$0	\$0	\$0	\$0
73EAO	SIGNAL DATA PRO	\$24,238	\$16,293	\$164	\$3,055	\$0
73EO1	CIRCUIT BOARD R	\$7	\$0	\$0	\$0	\$0
73EO9	MOC	\$189	\$0	\$0	\$0	\$0
73EDA	ASSY DATA INPUT	\$112	\$137	\$1	\$0	\$0
73EDB	ASSY ADDR/DIEMO	\$62	\$146	P	\$0	\$0
73EDC	ASSY PROCESSOR C	\$84	\$104	\$5	\$0	\$0
73EDH	ASSY INSTRUCTION	\$175	\$342	\$2	\$0	\$0
73EDJ	ASSY SIR CONT R	\$197	\$133	P	\$0	\$0
73EDK	ASSY DRVR TRAN	\$221	\$170	\$1	\$0	\$0
73EDL	ASSY STORE CONT	\$68	\$508	\$2	\$0	\$0
73EDN	ASSY CORE PLANE	\$200	\$503	\$4	\$1,475	\$0
73EBP	ASSY ANALOG OUT	\$448	\$6,256	\$17	\$304	\$0
73EBQ	ASSY ANALOG INP	\$237	\$3,020	\$8	\$0	\$0
73EBR	ASSY RATE-DEEL	\$112	\$900	\$2	\$0	\$0
73EBS	ASSY OVERFLOW R	\$68	\$350	\$5	\$0	\$0
73EDT	ASSY FUNCTION C	\$14	\$117	\$1	\$0	\$0
73EDU	ASSY CLOCK CUEK	\$238	\$342	\$2	\$0	\$0
73EDV	ASSY PARAFETR C	\$28	\$101	\$1	\$0	\$0
73EDX	PUR SUPPLY S VOL	\$70	\$895	\$20	\$0	\$0
73ERY	ASSY TRANSF/MEA	\$7	\$179	\$1	\$0	\$0
73EBZ	PHR SUPPLY LOH	\$158	\$660	\$12	\$0	\$0
73ECO	MT ELECT EQUIPH	\$587	\$0	\$0	\$0	\$0
73EL9	MOC	\$15	\$0	\$0	\$0	\$0
73ECA	ASSY FAN	\$81	\$0	\$0	\$0	\$0
73EDO	WIRING CONNS PI	\$942	\$0	\$0	\$0	\$0
73EXX		\$101,048	\$161,401	\$4,655	\$5,402	\$0
73FDO	INERTIAL MSU2MM	\$45,990	\$0	\$0	\$0	\$0
73FAO	UNIT INERTIAL M	\$69,022	\$220,202	\$2,961	\$0	\$0
73FA9	MOC	\$161	\$0	\$0	\$0	\$0
73FAD	BOARD CAPRI	\$339	\$8,357	\$69	\$0	\$0
73FAE	MODULE GIMBAL L	\$112	\$2,184	\$13	\$0	\$0
73FAF	MODULE PHR SUP	\$128	\$3,064	\$13	\$0	\$0
73FAG	MODULE MODE SHI	\$154	\$216	\$13	\$0	\$0
73FED	RACK ELEC EQUIP	\$1,045	\$0	\$0	\$0	\$0
73FCO	CONTROLLER IHS	\$1,388	\$457	\$5	\$0	\$0
73FEO	MOC	\$24	\$0	\$0	\$0	\$0
73FEX		\$24	\$0	\$0	\$0	\$0

P 11
 WEAPON SYSTEM ANU70 OALC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-MMO(9)/213(3)
 AFM 65-110/AA-1 DATA AS OF 77 DEC. CURRENT QUARTER COMPUTATION
 KUST, PH4L
 DATE PROCESSED

WUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDEMNATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EBU	ASSY OVERFLOW R	\$4	\$0	\$0	\$0	\$0
73EBV	ASSY CLOCK, CHK	\$125	\$1,072	\$5	\$5	\$0
73EBW	ASSY PARAMETR C	\$56	\$0	\$0	\$0	\$0
73EBX	PWR SUPPLY 5 VUL	\$7	\$179	\$4	\$4	\$0
73EC0	MT ELECT EQUIPM	\$564	\$0	\$0	\$0	\$0
73ECA	ASSY FAN	\$151	\$0	\$0	\$0	\$0
73ED0	WIRING CONNS PT	\$56	\$0	\$0	\$0	\$0
73EXX		\$91,540	\$160,598	\$4,619		\$272
73F00	INERTIAL MSURMN	\$43,813	\$0	\$0	\$0	\$0
73FAU	UNIT INERTIAL M	\$63,424	\$166,811	\$2,546	\$0	\$0
73FA9	NOC	\$81	\$0	\$0	\$0	\$0
73FAD	BOARD CAPRI	\$196	\$3,000	\$4	\$4	\$0
73FAE	MODULE GIMBAL I	\$322	\$3,710	\$23	\$23	\$0
73FAF	MODULE PWR SUP	\$210	\$3,258	\$14	\$14	\$0
73FAG	MODULE MODE SWI	\$165	\$2,052	\$10	\$10	\$0
73FAS	GYROSCOPE ELECTR	\$1,085	\$0	\$0	\$0	\$0
73FBU	RACK ELEC EQUIP	\$1,179	\$0	\$0	\$0	\$0
73FBU	CONTROLLER IMS	\$2,043	\$1,308	\$14	\$14	\$0
73FCB	FRONT PANEL	\$78	\$0	\$0	\$0	\$0
73FDO	ADPTR PWR SP LS	\$38,209	\$10,619	\$231	\$0	\$0
73FD9	NOC	\$116	\$0	\$0	\$0	\$0
73FDB	CARD SEQUENCER	\$178	\$1,904	\$11	\$11	\$0
73FDC	CARD SEQUENCER	\$167	\$1,008	\$9	\$9	\$0
73FDD	MODULE 800 HZ	\$671	\$428	\$4	\$4	\$0
73FDE	MODULE HEAD REP	\$2,366	\$6,783	\$109	\$109	\$0
73FDE	MODULE RELAY DR	\$14	\$362	\$2	\$2	\$0
73FEG	CARD RELAY DRIV	\$354	\$1,988	\$11	\$11	\$0
73FDH	CARD RELAY DRIV	\$67	\$950	\$4	\$4	\$0
73FDL	POWER SUPPLY	\$14	\$102	\$4	\$4	\$0
73FDM	CARD PWR SUPPLY	\$97	\$1,971	\$22	\$22	\$0
73FDN	CARD PWR SUPPLY	\$46	\$438	\$5	\$5	\$0
73FDP	CARD PWR SUPPLY	\$35	\$456	\$10	\$10	\$0
73FDQ	CARD PWR SUPPLY	\$158	\$3,812	\$55	\$55	\$0
73FDP	CARD PWR SUPPLY	\$81	\$887	\$9	\$9	\$0
73FDS	MODULE EITE	\$7	\$123	\$1	\$1	\$0
73FDT	MOTHER BOARD CL	\$62	\$454	\$32	\$32	\$0
73FDT	MOTHER BOARD MO	\$7	\$91	\$0	\$0	\$0
73FDT	WTR REMOTE COM	\$806	\$444	\$12	\$12	\$0
73FDT	WIRING CONNS PT	\$56	\$0	\$0	\$0	\$0

C 11
 WEAPON SYSTEM A007D OALC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-MMO(Q)7213(3)
 AFM 65-110/66-1 DATA AS OF 77 SEP CURRENT QUARTER COMPUTATION K051.PN4L
 DATE PROCESSED

MUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDENNATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EAN	MODULE HIGH VOL	\$182	\$1,862	\$8	\$0	\$0
73EAP	PRINTED WIRE BD	\$25	\$1,794	\$2	\$0	\$0
73EAP	AMPLIFIER DEFLEC	\$98	\$1,640	\$8	\$0	\$0
73EAR	ASSY VIDEO	\$374	\$2,817	\$8	\$0	\$0
73EAS	ASSY BITE	\$372	\$2,555	\$13	\$0	\$0
73EAT	PWR SUPPLY LOW V	\$2,974	\$3,404	\$19	\$0	\$0
73EAU	PRINT CIR BRD IN	\$349	\$1,314	\$4	\$0	\$0
73EAV	CIR BRD CR AMP/	\$407	\$1,380	\$5	\$0	\$0
73EAW	CIR BRD OUTPT R	\$594	\$4,898	\$29	\$15	\$15
73EAX	ASSY RECTIFIER B	\$18	\$0	\$0	\$0	\$0
73EBO	SIGNAL DATA PRO	\$21,762	\$11,743	\$138	\$28	\$28
73EB3	CHASIS ELECTRMIC	\$14	\$0	\$0	\$131	\$131
73EB9	HOC	\$14	\$0	\$0	\$0	\$0
73EBA	ASSY DATA INPUT	\$63	\$264	\$2	\$0	\$0
73EBD	ASSY ADDER/MEMO	\$28	\$0	\$0	\$0	\$0
73EBC	ASSY PROCESOR C	\$24	\$460	\$6	\$0	\$0
73EBH	ASSY INSTRUCTION	\$120	\$1,026	\$5	\$0	\$0
73EBJ	ASSY STR CONT R	\$60	\$0	\$0	\$0	\$0
73EBK	ASSY DRIVER TRAN	\$59	\$473	\$3	\$0	\$0
73EBL	ASSY STORE CONT	\$70	\$0	\$0	\$0	\$0
73EBM	ASSY CORE PLANE	\$70	\$222	\$0	\$490	\$490
73EBP	ASSY ANALOG OUT	\$287	\$2,717	\$5	\$166	\$166
73EBQ	ASSY ANALOG INP	\$295	\$3,182	\$7	\$0	\$0
73EBR	ASSY RATE-DEFL	\$7	\$284	\$1	\$0	\$0
73EBT	ASSY FUNCTION C	\$74	\$204	\$2	\$0	\$0
73EBU	ASSY CLOCK CHEK	\$204	\$312	\$2	\$0	\$0
73EBV	ASSY PARAMETR C	\$21	\$101	\$1	\$0	\$0
73EBX	PWR SUPPLY 5 VOL	\$4	\$179	\$4	\$0	\$0
73EBZ	PWR SUPPLY LOW	\$42	\$220	\$4	\$0	\$0
73ECO	MT ELECT EQUIPM	\$2,297	\$141	\$6	\$16	\$16
73EDO	WIRING COUINS PI	\$32	\$0	\$0	\$0	\$0
73EXX		\$108,982	\$188,335	\$4,938	\$34,318	
73F00	INERTIAL MSURMN	\$69,275	\$0	\$0	\$0	\$0
73FA0	UNIT INERTIAL M	\$69,613	\$217,833	\$3,543	\$0	\$0
73FA9	HOC	\$196	\$0	\$0	\$0	\$0
73FAD	BOARD CAPRI	\$466	\$7,337	\$9	\$0	\$0
73FAE	MODULE GIRDAL L	\$573	\$6,600	\$40	\$0	\$0
73FAF	MODULE PWR SUP	\$266	\$2,148	\$13	\$0	\$0

F 11 WEAPON SYSTEM A0070 OALC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-MHO(Q)7213(3) K051.PN4L
AFM 65-110/66-1 DATA AS OF 77 JUN CURRENT QUARTER COMPUTATION DATE PROCESSED

QUARTERLY VALUES					
WUC	NOUN	FIELD MAINT	SPEC REPAIR COST	PACK-SHIP COST	CONDEMNATION COST
73EXX		\$113,882	\$129,306	\$2,971	\$1,551
73F00	INERTIAL MSURMN	\$58,282	\$0	\$0	\$0
73FA0	UNIT INERTIAL M	\$66,644	\$105,654	\$3,761	\$0
73FAD	BOARD CAPRI	\$375	\$11,172	\$134	\$0
73FAE	MODULE GIBBAL L	\$270	\$1,624	\$21	\$0
73FAF	MODULE PHR SUP	\$315	\$2,366	\$21	\$0
73FAG	MODULE MODE SWI	\$78	\$508	\$1	\$0
73FAM	ACCLMETER X-Y	\$0	\$0	\$0	\$0
73FAN	ACCLMETER Z AXIS	\$0	\$0	\$0	\$0
73FAP	GYROSCOPE X-Y AX	\$0	\$0	\$0	\$0
73FAQ	GYROSCOPE Z AXIS	\$0	\$0	\$0	\$0
73FAR	ACCLMTR ELECTRN	\$14	\$49	\$1	\$0
73FAS	GYROSCOPE ELECTR	\$0	\$0	\$0	\$100,068
73FAT	GIDLE THP CONT	\$0	\$0	\$0	\$0
73FAU	AUX THP CONT AM	\$0	\$0	\$0	\$0
73FAV	CLSTR CONT THPT	\$0	\$0	\$0	\$0
73FAM	COMPSATION BOAR	\$7	\$537	\$2	\$0
73FDO	RACK ELEC EQUIP	\$694	\$0	\$0	\$0
73FC0	CONTROLLER IMS	\$1,574	\$452	\$10	\$0
73FCB	FRONT PANEL	\$91	\$0	\$0	\$0
73FDO	ADPTR PHR SP LS	\$45,304	\$12,473	\$397	\$0
73FDA	MODULE SEQUENCE	\$45	\$155	\$3	\$0
73FDB	CARD SEQUENCER	\$170	\$637	\$10	\$0
73FDC	CARD SEQUENCER	\$127	\$620	\$8	\$0
73FDD	MODULE 800 HZ	\$245	\$720	\$10	\$0
73FDE	MODULE HEAD REP	\$2,741	\$8,316	\$174	\$0
73FDF	MODULE RELAY DR	\$112	\$0	\$0	\$0
73FDG	CARD RELAY DRIV	\$153	\$710	\$8	\$0
73FDH	CARD RELAY DRIV	\$165	\$656	\$6	\$0
73FDK	DRIVER AMPLIFIE	\$24	\$0	\$0	\$467
73FDL	POWER SUPPLY	\$28	\$161	\$4	\$0
73FDM	CARD PHR SUPPLY	\$273	\$1,887	\$41	\$0
73FDM	CARD PHR SUPPLY	\$112	\$721	\$11	\$0
73FDP	CARD PHR SUPPLY	\$6	\$73	\$3	\$0
73FDO	CARD PHR SUPPLY	\$154	\$2,561	\$31	\$0
73FDB	CARD PHR SUPPLY	\$115	\$760	\$14	\$0
73FDS	MODULE BITE	\$49	\$168	\$2	\$0
73FDT	MOTHER BOARD CL	\$112	\$0	\$0	\$0
73FDO	MOTHER BOARD MO	\$27	\$27	\$0	\$0
73FEO	MOUNT ADPT/PS	\$102	\$0	\$0	\$0
73FEO	BATTERY PACK IM	\$35	\$0	\$0	\$0

WEAPON SYSTEM A007D OALC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-HMO(Q)7213(3) K051.PN4L
 AFM 65-110/66-1 DATA AS OF 77 MAR CURRENT QUARTER COMPUTATION DATE PROCESSED

MUC	MOUN	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUES		CONDEMNATION COST
				PACK-SHIP COST		
73EBA	ASSY DATA INPUT	\$57	\$110	\$1	\$0	
73EBB	ASSY ADDR/MEMO	\$31	\$119	\$1	\$0	
73EBC	ASSY PROCESOR C	\$95	\$148	\$2	\$0	
73EBE	ASSY DISCRETE I	\$136	\$324	\$5	\$14	
73EDH	ASSY INSTRUCTION	\$71	\$513	\$2	\$0	
73EDL	ASSY STR CONT R	\$164	\$928	\$3	\$0	
73EDK	ASSY DRIVER TRAN	\$77	\$861	\$5	\$0	
73EDL	ASSY STORE CONT	\$65	\$711	\$4	\$18	
73EDH	ASSY CORE PLANE	\$150	\$1,391	\$9	\$2,022	
73EDP	ASSY ANALOG OUT	\$343	\$8,658	\$12	\$208	
73EDQ	ASSY ANALOG IMP	\$112	\$2,590	\$4	\$0	
73EDS	ASSY OVERFLOW R	\$4	\$0	\$0	\$0	
73EDT	ASSY FUNCTION C	\$51	\$194	\$2	\$0	
73EDU	ASSY CLOCK CHECK	\$134	\$584	\$3	\$0	
73EDX	PHR SUPPLY 5 VOL	\$39	\$143	\$4	\$0	
73EDY	ASSY TRANSF/MEA	\$14	\$0	\$0	\$0	
73EDZ	PHR SUPPLY LOW	\$35	\$354	\$8	\$0	
73EC0	MT ELECT EQUIPM	\$557	\$139	\$6	\$16	
73EC9	HOC	\$17	\$0	\$0	\$0	
73ECA	ASSY FAN	\$280	\$0	\$0	\$0	
73ED0	WIRING CONNS PI	\$141	\$0	\$0	\$0	
73EXX		\$127,948	\$184,153	\$6,001	\$3,163	
73F00	INERTIAL MSURMN	\$62,069	\$0	\$0	\$0	
73FA0	UNIT INERTIAL M	\$66,932	\$117,998	\$2,304	\$0	
73FAD	BOARD CAPRI	\$235	\$3,840	\$6	\$0	
73FAE	MODULE GINBAL L	\$465	\$1,677	\$23	\$0	
73FAF	MODULE PHR SUP	\$447	\$1,690	\$16	\$0	
73FAG	MODULE MODE S/H	\$182	\$1,143	\$7	\$0	
73FAH	ACCLORMETER X-Y	\$0	\$0	\$0	\$0	
73FAN	ACCLMTR 2 AXIS	\$0	\$0	\$0	\$0	
73FAP	GYROSCPE X-Y AX	\$0	\$0	\$0	\$0	
73FAQ	GYROSCPE Z AXIS	\$0	\$0	\$0	\$0	
73FAR	ACCLMTR ELECTRM	\$0	\$0	\$0	\$0	
73FAS	GYROSCPE ELECTR	\$0	\$0	\$0	\$108,150	
73FAT	GHBLE TMP CONT	\$0	\$0	\$0	\$100,068	
73FAU	AUX TMP CONT AM	\$0	\$0	\$0	\$0	
73FAV	CLSTR CONT THPT	\$0	\$0	\$0	\$0	
73FAW	COMPASATION BOAR	\$0	\$0	\$0	\$0	
73F00	RACK ELEC EQUIP	\$2,005	\$0	\$0	\$0	
73F00	CONTROLLER INS	\$2,764	\$2,484	\$2	\$0	

D 11
 WEAPON SYSTEM A007D OALC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-MMO(0)7213(3)
 AFM 65-110/66-1 DATA AS OF 76 DEC CURRENT QUARTER COMPUTATION K011.PN4L
 DATE PROCESSED

WUC	NOUN	FIELD MAINT	QUARTERLY VALUES		CONDEMNATION COST
			SPEC REPAIR COST	PACK-SHIP COST	
73F00	INERTIAL NSURMN	\$63,981	\$0	\$0	\$0
73FA0	UNIT INERTIAL M	\$64,854	\$156,114	\$3,154	P
73FA9	ROC	\$528	\$0	\$0	\$0
73FAD	DRARD CAPAI	\$486	\$4,320	\$7	P
73FAE	MODULE GIMBAL L	\$281	\$1,972	\$27	P
73FAF	MODULE PHR SUP	\$199	\$1,859	\$18	P
73FAG	MODULE MODE SWI	\$224	\$0	\$6	P
73FAM	ACCLORHETER X-Y	\$0	\$0	\$0	\$0
73FAN	ACCLTHER 2 AXIS	\$0	\$0	\$0	\$0
73FAP	GYROSCOPE X-Y AX	\$0	\$0	\$0	\$0
73FAQ	GYROSCOPE 2 AXIS	\$0	\$0	\$0	\$0
73FAR	ACCLTHER ELECTRH	\$10	\$452	\$2	P
73FAS	GYROSCOPE ELECTRA	\$0	\$0	\$0	\$54,075
73FAT	GIMBLE TNP CONT	\$10	\$0	\$0	\$50,034
73FAU	AUX TNP CONT AM	\$0	\$0	\$0	\$0
73FAV	CLSTR CONT TMT	\$0	\$0	\$0	\$0
73FAM	COMPASATION BOMR	\$0	\$0	\$0	\$0
73FDC	RACK ELEC EQUIP	\$1,172	\$0	\$0	\$0
73FC0	CONTROLLER IMS	\$1,528	\$678	\$74	P
73FC9	ROC	\$406	\$0	\$0	\$0
73FCD	FRONT PANEL	\$71	\$0	\$0	\$0
73FDD	ADPTR PHR SP LS	\$50,200	\$11,920	\$431	P
73FDB	CARD SEQUENCER	\$137	\$441	\$7	P
73FDC	CARD SEQUENCER	\$93	\$354	\$5	P
73FDD	MODULE 800 M2	\$92	\$382	\$5	P
73FDE	MODULE HEAD REP	\$2,975	\$6,160	\$129	P
73FDG	CARD RELAY DRIV	\$152	\$710	\$8	P
73FDH	CARD RELAY DRIV	\$190	\$902	\$9	P
73FDJ	MODULE PNL-PITC	\$108	\$0	\$0	\$0
73FDK	DRIVER AMPLIFIE	\$18	\$0	\$0	\$0
73FDL	POWER SUPPLY	\$118	\$0	\$0	\$0
73FDH	CARD PHR SUPPLY	\$199	\$1,534	\$34	P
73FDM	CARD PHR SUPPLY	\$164	\$721	\$11	P
73FDP	CARD PHR SUPPLY	\$193	\$219	\$10	P
73FDQ	CARD PHR SUPPLY	\$182	\$1,970	\$24	P
73FDR	CARD PHR SUPPLY	\$52	\$380	\$6	P
73FDS	MODULE BITE	\$7	\$56	\$1	P
73FDT	MOTHER BOARD CL	\$4	\$0	\$0	\$0
73FED	MOUNT ADPT/PS	\$216	\$0	\$0	\$0
73FEO	MOUNT REMOTE COM	\$1,145	\$365	\$4	P
73FEO	MOUNT REMOTE COM	\$2,147	\$0	\$0	\$0

F 11
 WEAPON SYSTEM AFM 65-110/66-1 A007D OALC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-MMO(0)7213(3) K051.PN4L
 DATE PROCESSED

AFM 65-110/66-1 DATA AS OF 76 SEP
 CURRENT QUARTER COMPUTATION

MUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDENMATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EAE	ASSY TUBE UNIT	\$517	\$11,492	\$82	P	\$0
73EAF	ASSY CATHODE RA	\$419	\$9,464	\$68	P	\$0
73EAG	ASSY CRT MATCHI	\$141	\$1	\$1	P	\$0
73EAM	PWR SUPPLY HIGH	\$776	\$2,898	\$28	P	\$0
73EAP	MODULE HIGH VOL	\$7	\$0	\$0	P	\$0
73EAP	PRINTED WIRE BD	\$152	\$1,166	\$2	P	\$0
73EAQ	AMPLIFIER DEF'EC	\$131	\$1,216	\$6	P	\$0
73EAR	ASSY VIDEO	\$250	\$15,934	\$26	P	\$0
73EAS	ASSY BITE	\$771	\$3,407	\$21	P	\$543
73EAT	PWR SUPPLY LOW V	\$3,017	\$1,500	\$15	P	\$195
73EAV	PRINT CIR BRD IN	\$222	\$2,067	\$20	P	\$0
73EAV	CIR BRD ER AMP/	\$450	\$1,694	\$15	P	\$0
73EAW	CIR BRD OUTPT R	\$426	\$7,338	\$21	P	\$0
73EAX	ASSY RECTIFIER B	\$7	\$0	\$0	P	\$0
73EBO	SIGNAL DATA PRO	\$42,522	\$7,916	\$111	P	\$218
73EB9	NOC	\$354	\$0	\$0	P	\$109
73EBA	DATA INPUT	\$120	\$880	\$6	P	\$0
73EBB	ASSY ADDER/MEMO	\$148	\$3	\$2	P	\$0
73EBB	ASSY PROCESOR C	\$95	\$554	\$0	P	\$0
73EBE	ASSY DISCRETE I	\$66	\$357	\$5	P	\$0
73EBH	ASSY INSTRUCTION	\$64	\$681	\$3	P	\$0
73EBJ	ASSY STR CONT R	\$119	\$696	\$2	P	\$0
73EBK	ASSY DRIVER TRAH	\$118	\$504	\$3	P	\$0
73EBL	ASSY STORE CONT	\$262	\$2,746	\$15	P	\$0
73EBM	ASSY CORE PLANE	\$143	\$822	\$5	P	\$0
73EBP	ASSY ANALOG OUT	\$519	\$21,564	\$31	P	\$0
73EBQ	ASSY ANALOG INP	\$228	\$9,984	\$16	P	\$855
73EBR	ASSY RATE-DEFL	\$67	\$1,547	\$6	P	\$0
73EBT	ASSY FUNCTION C	\$71	\$1,222	\$1	P	\$0
73EBU	ASSY CLOCK CHEK	\$276	\$2,788	\$23	P	\$0
73EBV	ASSY PARAMETR C	\$14	\$0	\$0	P	\$0
73EDX	PWR SUPPLY 5 VOL	\$28	\$286	\$8	P	\$0
73EBZ	PWR SUPPLY LOW	\$53	\$354	\$8	P	\$0
73ECO	MT ELECT EQUIPM	\$515	\$0	\$0	P	\$0
73ECA	ASSY FAN	\$102	\$0	\$0	P	\$0
73EDD	WIRING CONNS PI	\$321	\$0	\$0	P	\$0
73EXX		\$168,406	\$248,212	\$6,929		\$1,920
73F00	INERTIAL MSURMM	\$75,870	\$0	\$0		\$0
73FAD	UNIT INERTIAL M	\$88,377	\$215,606	\$4,313	P	\$0
73FAD	CDC	\$66	\$0	\$0	P	\$0
73FAD	GUARD CAPRI	\$231	\$2,212	\$4	P	\$0
73FAD		\$231	\$2,212	\$39	P	\$0

U 10
WEAPON SYSTEM A0070 G4LC LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-MMG(6)7213(3) K051.PN4L
AFM 65-110/66-1 DATA AS OF 76 JUN CURRENT QUARTER COMPUTATION DATE PROCESSED

MUC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDEMNATION COST
			SPEC REPAIR COST	PACK-SHIP COST		
73EBU	ASSY CLOCK CHEK	\$298	P \$3,416	\$18	P	\$0
73EBV	ASSY PARAMETR C	\$35	\$0	\$0		\$0
73EBX	PHR SUPPLY 5 VOL	\$10	\$0	\$0		\$0
73FBZ	PHR SUPPLY LOW	\$42	P \$372	\$8	P	\$0
73ECU	MT ELECT EQUIPM	\$1,475	\$0	\$0		\$0
73ECA	ASSY FAN	\$15	\$0	\$0		\$0
73EDD	WIRING CONNS PI	\$172	\$0	\$0		\$0
73EXX		\$130,497	\$140,172	\$5,487		\$2,161
73F00	INERTIAL MSURMH	\$76,487	\$0	\$0		\$0
73FA0	UNIT INERTIAL M	\$78,458	\$41,832	\$5,402		\$0
73FA9	NOC	\$35	\$0	\$0		\$0
73FAD	BOARD CAPRI	\$256	\$1,506	\$5		\$0
73FAE	MODULE GIMBAL L	\$379	\$1,616	\$28		\$0
73FAF	MODULE PHR SUP	\$343	\$1,452	\$18		\$0
73FAG	MODULE MODE SWI	\$169	\$724	\$8		\$0
73FAM	ACCLROMETER X-Y	\$0	\$0	\$0		\$0
73FAN	ACCLMTR 2 AXIS	\$0	\$0	\$0		\$0
73FAP	GYROSCOPE X-Y AX	\$0	\$0	\$0		\$0
73FAQ	GYROSCOPE Z AXIS	\$0	\$0	\$0		\$0
73FAR	ACCLMTR ELECTRN	\$0	\$0	\$0		\$0
73FAS	GYROSCOPE ELECT R	\$0	\$0	\$0		\$0
73FAT	GMBLE TMP CONT	\$0	\$0	\$0		\$0
73FAU	AUX TMP CONT AM	\$0	\$0	\$0		\$0
73FAV	CLSTR CONT TMPT	\$0	\$0	\$0		\$0
73FAM	COMPASATION BOAR	\$0	\$0	\$0		\$0
73FBO	RACK ELEC EQUIP	\$2,592	P \$0	\$4	P	\$1,113
73FC0	CONTROLLER IMS	\$1,935	\$1,888	\$39		\$0
73FC9	FRONT PANEL	\$41	\$0	\$0		\$0
73FD0	ADPTR PHR SP LS	\$55,652	\$2,925	\$99		\$0
73FD9	NOC	\$214	\$0	\$0		\$0
73FDB	CARD SEQUENCER	\$269	\$1,770	\$12		\$0
73FDC	CARD SEQUENCER	\$291	\$1,050	\$8		\$0
73FDD	MODULE 800 HZ	\$279	\$745	\$12		\$0
73FDE	MODULE HEAD REP	\$2,397	\$9,867	\$212		\$0
73FDF	MODULE RELAY DR	\$3	\$0	\$0		\$0
73FDG	CARD RELAY DRIV	\$172	P \$489	\$5	P	\$0
73FDH	CARD RELAY DRIV	\$43	\$216	\$3		\$0
73FDL	POWER SUPPLY	\$45	\$86	\$8	P	\$0
73FDM	PHR PHR SUPPLY	\$234	\$2,226	\$34		\$0

US JN40
DATE RELEASED

WREATH SYSTEM AUGUST 1964 LOGISTICS SUPPORT LOST BREAKDOWN RCS LOG-MMO(1)7211(3)
AUG 65-110/66-1 DATA AS OF 76 MAR CURRENT QUARTER COMPUTATION

ML	NOUN	FIELD MAINT	QUARTERLY VALUES			CONCERNATION LOST
			SPEC REPAIR LOST	PAID-SHIP LOST		
73EAK	ASSY CRT MATING	\$45	\$80	\$1		\$0
73EAM	PWR SUPPLY HIGH	\$497	\$294	\$12		\$0
73EAN	MODULE HIGH VOL	\$21	\$131	\$4		\$883
73EAP	PRINTED WIRE BD	\$75	\$999	\$5		\$0
73EAP	AMPLIFIER DEFEC	\$197	\$700	\$4		\$0
73EAP	ASSY VIDEO	\$481	\$3,483	\$21		\$0
73EAS	ASSY BITE	\$430	\$1,610	\$23		\$407
73EAT	PWR SUPPLY LOW V	\$3,685	\$0	\$0		\$0
73EAU	PANT CIR BRD IN	\$270	\$392	\$17		\$0
73EAV	CIR PRD ER AMF	\$227	\$2,248	\$10		\$0
73EAW	CIR BRD OUTPT K	\$453	\$2,664	\$32		\$0
73EAX	ASSY ELECTRONIC	\$59	\$0	\$0		\$0
73EAX	ASSY RECTIFIER B	\$64	\$264	\$2		\$0
73EBO	SIGNAL DATA PRD	\$31,272	\$2,810	\$139		\$0
73EB3	CHASSIS ELECTRONIC	\$81	\$0	\$0		\$0
73EB5	MOD	\$155	\$0	\$2		\$137
73EBA	ASSY DATA INPUT	\$14	\$333	\$1		\$0
73EBB	ASSY ADDER/MEMO	\$144	\$1	\$1		\$0
73EBL	ASSY PROCESSOR C	\$17	\$182	\$5		\$0
73EBE	ASSY DISCRETE I	\$21	\$1	\$2		\$0
73EBH	ASSY INSTRUCTION	\$19	\$666	\$2		\$0
73EBJ	ASSY STR CONT K	\$56	\$0	\$0		\$0
73EBK	ASSY DRIVE TRAN	\$82	\$660	\$4		\$0
73EBL	ASSY STORE CONT	\$24	\$0	\$0		\$0
73EBM	ASSY CORE PLANE	\$100	\$976	\$6		\$0
73ESF	ASSY ANALOG OUT	\$466	\$2,394	\$17		\$0
73EBY	ASSY ANALOG IMP	\$241	\$1,313	\$10		\$513
73EBW	ASSY RATE-DEFL	\$46	\$3	\$2		\$0
73EBU	ASSY CLOCK CHIF	\$194	\$1,743	\$13		\$0
73EEX	PWR SUPPLY 5 VOL	\$35	\$533	\$4		\$0
73EBZ	PWR SUPPLY LOW	\$67	\$744	\$16		\$0
73ELU	MT ELECT EQUIPM	\$789	\$0	\$0		\$0
73ELA	ASSY FAN	\$165	\$0	\$0		\$0
73EUD	WIRING CONNG FI	\$409	\$0	\$0		\$0
73EXA		\$141,502	\$176,104	\$7,291		\$1,940
73F00	INERTIAL MEASRMN	\$77,998	\$0	\$0		\$0
73F00	UNIT INERTIAL M	\$75,966	\$166,012	\$2,877		\$0
73F09	MOD	\$203	\$0	\$0		\$0
73F0A	P-220 CASET	\$319	\$6,510	\$74		\$0

WEAPON SYSTEM AX170
AFM 65-110/66-1 DATA AS OF 75 DEC

LOGISTIC SUPPORT COST BREAKDOWN RCS LOG-PMO(0)7213(3)
CURRENT QUARTER COMPUTATION

POST PLAN
DATE PROCESSED

MOC	NOUN	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUES			BASE MATERIAL COST
				PACK-SHIP COST	CONDEMNATION COST	COST	
73EAK	ASSY CRT MATCH	332	\$0	\$1	\$0	\$0	COST
73EAT	PR SUPPLY HIGH	\$417	\$294	\$12	\$0	\$0	COST
73EAD	MODULE HIGH VCA	\$18	\$0	\$4	\$0	\$0	COST
73EAP	PRINTED WIRE BO	\$32	\$333	\$1	\$0	\$0	COST
73EAG	AMPLIFIER DEFLEC	\$228	\$1,820	\$10	\$0	\$0	COST
73EAR	ASSY VIDEO	\$659	\$2,979	\$19	\$0	\$0	COST
73EAS	ASSY BITE	\$591	\$1,932	\$25	\$475	\$0	COST
73EAT	PR SUPPLY LOW V	\$1,510	\$616	\$1	\$0	\$0	COST
73EAD	PRNT CIR BRG IN	\$119	\$5	\$9	\$0	\$0	COST
73EAT	CIR BRG ER AMP	\$236	\$1,881	\$16	\$0	\$0	COST
73EAM	CIR BRG OUTFT R	\$93	\$396	\$6	\$493	\$0	COST
73EAT	ASSY RECTIFIER B	\$28	\$0	\$1	\$0	\$0	COST
73EAD	SIGNAL DATA FRQ	\$20,623	\$8,430	\$41	\$0	\$0	COST
73EB9	MOC	\$71	\$0	\$0	\$0	\$0	COST
73EBA	ASSY DATA INFT	\$32	\$666	\$2	\$0	\$0	COST
73EBB	ASSY ADDER/MEMO	\$150	\$4	\$4	\$0	\$0	COST
73EBF	ASSY DISCRETE I	\$28	\$2	\$3	\$0	\$0	COST
73EBH	ASSY INSTRUCTION	\$28	\$999	\$2	\$0	\$0	COST
73EBX	ASSY DRIVER TRAN	\$52	\$0	\$2	\$0	\$0	COST
73EBL	ASSY STORE CONT	\$133	\$976	\$7	\$0	\$0	COST
73EBM	ASSY CORE PLANE	\$52	\$488	\$3	\$0	\$0	COST
73EBP	ASSY ANALOG OUT	\$189	\$1,824	\$15	\$0	\$0	COST
73EGV	ASSY ANALOG INP	\$304	\$1,860	\$14	\$472	\$0	COST
73EBR	ASSY RATE-DEFL	\$119	\$8	\$36	\$0	\$0	COST
73EBI	ASSY FUNCTION C	\$25	\$891	\$0	\$0	\$0	COST
73EBU	ASSY CLUTCH MEK	\$134	\$186	\$7	\$0	\$0	COST
73EBZ	PR SUPPLY LOW	\$10	\$0	\$0	\$0	\$0	COST
73EC0	MT ELEFT EQUIPM	\$489	\$0	\$0	\$0	\$0	COST
73EC9	MOC	\$3	\$0	\$0	\$0	\$0	COST
73ECA	ASSY FAN	\$28	\$0	\$0	\$0	\$0	COST
73EEO	VIRING CONNS P1	\$28	\$0	\$0	\$0	\$0	COST
73EEX		\$103,804	\$184,186	\$5,533	\$1,445	\$0	COST
73EFA	INERTIAL MEASRM	\$61,266	\$3,498	\$34	\$0	\$0	COST
73EAD	UNIT INERTIAL M	\$57,697	\$165,393	\$2,970	\$0	\$0	COST
73EAG	MOC	\$17	\$0	\$0	\$0	\$0	COST
73EAB	ROUND CAPMT	\$612	\$1,757	\$4	\$0	\$0	COST
73EAC		\$33	\$0	\$0	\$0	\$0	COST

AD-A123 025

A STUDY TO DEMONSTRATE THE APPLICATION OF A GRAPHICAL
METHOD TO DETERMINE..(U) AIR FORCE INST OF TECH
WRIGHT-PATTERSON AFB OH SCHOOL OF SYST..

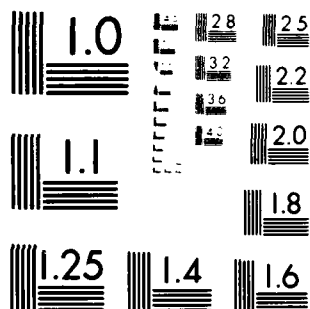
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MICROCOPY RESOLUTION TEST CHART
NATIONAL BUREAU OF STANDARDS-1963-A

4 11 WEAPON SYSTEM AC070 OCALC LOGISTIC SUPPORT COST BREAKDOWN FCS LOG-MMO(0)7213(3) K051.PM44
AFM AS-110/66-1 DATA AS OF 75 SEP CURRENT QUARTER COMPUTATION DATE PROCESSED

WUC	NOUN	FIELD PAINT	SPEC. REPAIR COST	QUARTERLY VALUES			BASE MATERIAL COST
				PACK-SHIP COST	CONDEMNATION COST		
73EXX		\$120,710	\$158,975	\$4,656	\$606	COST	
73FOU	INERTIAL MSURPM	\$69,212	\$0	\$0	\$0	COST	
X 73FAO	UNIT INERTIAL M	\$75,126	P \$191,786	\$3,942	\$0	COST	
73FA9	HOC	\$38	\$0	\$0	\$0	COST	
73FAD	BOARD CAPRI	\$544	\$5,282	\$15	\$0	COST	
73FAE	MODULE GIMBAL L	\$681	\$4,675	\$53	\$0	COST	
73FAF	MODULE PWR SUP	\$291	\$3,828	\$34	\$0	COST	
73FAG	MODULE MODE SWI	\$312	\$3,017	\$6	\$0	COST	
73FAM	ACCELEROMETER X-Y	\$0	\$0	\$0	\$0	COST	
73FAN	ACCLMTER 2 AXIS	\$7	\$0	\$0	\$0	COST	
73FAP	GYROSCOPE X-Y AX	\$0	\$0	\$0	\$0	COST	
73FAQ	GYROSCOPE 2 AXIS	\$0	\$0	\$0	\$0	COST	
73FAR	ACCLMTR ELECTPN	\$0	\$0	\$0	\$0	COST	
73FAS	GYROSCOPE ELECTA	\$0	\$0	\$0	\$0	COST	
73FAT	GBLE TYP CONT	\$0	\$0	\$0	\$0	COST	
73FAU	AUX TYP CONT AM	\$0	\$0	\$0	\$0	COST	
73FAV	CLSTR CONT TMPT	\$0	\$0	\$0	\$0	COST	
73FAM	COMPASSION BOAR	\$1,011	\$0	\$0	\$0	COST	
73FBO	RACK ELEC EQUIP	\$1,578	\$0	\$0	\$0	COST	
73FCO	CONTROLLER IMS		\$824	\$19	\$0	COST	
73FC9	NOC	\$64	\$0	\$0	\$0	COST	
73FCB	FRONT PANEL	\$45	\$0	\$0	\$0	COST	
73FDO	ADPTR PWR SP LS	\$50,685	\$0	\$0	\$0	COST	
73FD9	NOC	\$441	\$0	\$0	\$0	COST	
73FDB	CARD SEQUENCER	\$204	\$380	\$8	\$0	COST	
73FDC	CARD SEQUENCER	\$164	\$385	\$4	\$0	COST	
73FDD	MODULE 600 HZ	\$28	\$54	\$2	\$0	COST	
73FDE	MODULE HEAD REP	\$1,257	\$2,912	\$103	\$0	COST	
73FDF	MODULE RELAY DR	\$4	\$0	\$0	\$0	COST	
73FDG	CARD RELAY DRIV	\$176	\$448	\$6	\$0	COST	
73FDH	CARD RELAY DRIV	\$15	\$720	\$7	\$0	COST	
73FDL	POWER SUPPLY	\$00	\$280	\$16	\$0	COST	
73FDN	CARD PWR SUPPLY	\$494	\$4,216	\$75	\$0	COST	
73FDN	CARD PWR SUPPLY	\$91	\$440	\$13	\$0	COST	
73FDP	CARD PWR SUPPLY	\$50	\$650	\$16	\$0	COST	
73FDQ	CARD PWR SUPPLY	\$276	\$2,800	\$39	\$0	COST	
73FDD	PWR SUP CLIP V	\$82	\$147	\$5	\$0	COST	

Q 111
 WEAPON SYSTEM A0070 OALC LOGISTIC SUPPORT COST BREAKDOWN RCS:LOG-M40(0)7213(3) K051.PN6L
 APM 65-110/66-1 DATA AS OF 75 JUN CURRENT QUARTER COMPUTATION DATE PROCESSED

NRC	NO/M	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUES			BASE MATERIAL COST
				PACK/SHIP COST	CONDENATION COST		
73EBZ	PHR SUPPLY LOW	\$15	\$372	\$8	\$0	\$0	\$0
73EB0	SIGNAL DATA PRO	\$34,933	\$5,620	\$277	\$0	\$0	\$0
73EB9	MOC	\$227	\$0	\$0	P	\$484	\$0
73ETA	ASSY FAN	\$346	\$0	\$0	\$0	\$0	\$0
73ECU	MT ELEC EQ/1PM	\$556	\$0	\$0	\$0	\$0	\$0
73ED0	DIS SYS HEADSUP	\$10,766	\$0	\$0	\$0	\$0	\$0
73EXX		\$133,278	\$161,788	\$5,048	\$1,090	\$0	\$0
73FAP	BOARD CAPRI	\$553	\$876	\$10	\$0	\$0	\$0
73FAE	MODULE GIMBAL L	\$707	\$1,972	\$55	\$0	\$0	\$0
73FAF	MODULE PHR SUP	\$446	\$1,375	\$42	P	\$0	\$0
73FAG	MODULE MOUE SWI	\$270	\$531	\$9	P	\$0	\$0
73FAM	ACCLORIMETER X-Y	\$0	\$0	\$0	\$0	\$0	\$0
73FAN	ACCLIMETER Z AXIS	\$0	\$0	\$0	\$0	\$0	\$0
73FAP	GYROSCOPE X-Y AX	\$0	\$0	\$0	\$0	\$0	\$0
73FAQ	GYROSCOPE Z AXIS	\$28	\$0	\$0	\$0	\$0	\$0
73FAT	GYBLE TMP CONT	\$0	\$0	\$0	\$0	\$0	\$0
73FAU	AUX TMP CONT AM	\$0	\$0	\$0	\$0	\$0	\$0
73FAH	COMPASITION BOAR	\$11	\$0	\$0	\$0	\$0	\$0
73FAO	UNIT INERTIAL M	\$79,169	\$119,377	\$5,926	\$0	\$0	\$0
73FBD	RACK ELEC EQUIP	\$942	\$0	\$0	\$0	\$0	\$0
73FCB	FRONT PANEL	\$66	\$0	\$0	\$0	\$0	\$0
73FCD	CONTROLLER IMS	\$1,783	\$370	\$12	\$0	\$0	\$0
73FCE	MOC	\$45	\$0	\$0	\$0	\$0	\$0
73FDB	CARD SEQUENCER	\$171	\$1,330	\$11	\$0	\$0	\$0
73FDC	CARD SEQUENCER	\$143	\$814	\$9	\$0	\$0	\$0
73FDD	MODULE 800 MZ	\$119	\$606	\$9	\$0	\$0	\$0
73FDE	MODULE HEAD REP	\$1,656	\$1,560	\$167	\$0	\$0	\$0
73FDG	CARD RELAY DRIV	\$35	\$0	\$0	\$0	\$0	\$0
73FDH	CARD RELAY DRIV	\$111	\$410	\$8	\$0	\$0	\$0
73FDK	DRIVER AMPLIFIE	\$43	\$153	\$2	P	\$0	\$0
73FDL	POWER SUPPLY	\$76	\$0	\$6	\$0	\$0	\$0
73FDM	CARD PHR SUPPLY	\$7	\$0	\$0	\$0	\$0	\$0
73FDN	CARD PHR SUPPLY	\$478	\$2,100	\$72	\$0	\$0	\$0
73FDN	CARD PHR SUPPLY	\$220	\$980	\$23	\$0	\$0	\$0
73FDN	CARD PHR SUPPLY	\$211	\$660	\$35	\$0	\$0	\$0
73FDQ	CARD PHR SUPPLY	\$783	\$2,380	\$82	\$0	\$0	\$0
73FDQ	CARD PHR SUPPLY	\$181	\$2,272	\$18	\$0	\$0	\$0

A 10
 WEAPON SYSTEM A0070 OALC LOGISTIC SUPPORT COST BREAKDOWN 765:LOG-WO(0)7213(3)
 APR 65-110/66-1 DATA AS OF 75 MAR CURRENT QUARTER COMPUTATION K031.PW21
 DATE PROCESSED

JAC	MODL	FIELD MOUNT	QUARTERLY VALUES			CONDEMNATION COST	BASE MATERIAL COST
			SPEC REPAIR COST	PACK/SHIP COST			
735A0	AMPLIFIER DEFLEC	\$155	\$420	\$2		\$0	\$0
735A1	ASSY VIDEO	\$167	\$1,719	\$10		\$0	\$0
735A2	ASSY OITE	\$354	\$752	\$11		\$0	\$0
735A3	FOR SUPPLY LOW V	\$2,284	\$924	\$14		\$0	\$0
735A4	FOR CIR DRD IN	\$178	\$3	\$3		\$0	\$0
735A5	CIR DRD ER NP/	\$232	\$1,463	\$3		\$0	\$0
735A6	CIR DRD OUTPT R	\$273	\$393	\$12	P	\$0	\$0
735A7	ASSY ELECTRONIC	\$14	\$0	\$0		\$0	\$0
735A8	ASSY RECTIFIER O	\$43	\$0	\$0		\$0	\$0
735A9	DIS UNIT HEADSU	\$80,262	\$193,461	\$0		\$0	\$0
735A1	ASSY TESTUAL O	\$28	\$0	\$0		\$0	\$0
735A2	SETTOR AUTO BRI	\$3	\$0	\$0		\$0	\$0
735A3	FOR	\$522	\$0	\$0		\$0	\$0
735A4	ASSY DATA INPUT	\$141	\$333	\$1		\$0	\$0
735A5	ASSY ADDER/7220	\$357	\$1	\$1	P	\$0	\$0
735A6	ASSY PROCESSOR C	\$119	\$515	\$4		\$0	\$0
735A7	ASSY DISCRETE I	\$30	\$0	\$0		\$0	\$0
735A8	ASSY INSTRUCTION	\$32	\$445	\$2		\$0	\$0
735A9	ASSY STR CONT R	\$43	\$111	\$1		\$0	\$0
735A1	ASSY CPU/2 TON	\$31	\$331	\$2		\$0	\$0
735A2	ASSY STORE CONT	\$30	\$241	\$2		\$0	\$0
735A3	ASSY CORE PLATE	\$339	\$1,223	\$2		\$0	\$0
735A4	ASSY ANALOG OUT	\$477	\$3,153	\$2		\$0	\$0
735A5						\$1,320	\$0
735B0	DRD FACOL	\$150,180	\$215,372	\$7,040		\$0	\$0
735B1	MEASUREMENT L	\$303	\$376	\$10		\$0	\$0
735B2	MEASUREMENT CUP	\$303	\$1,160	\$12		\$0	\$0
735B3	MEASUREMENT F/A	\$303	\$1,160	\$13	P	\$0	\$0
735B4	UNIT INITIAL R	\$87,078	\$205,451	\$3,733		\$0	\$0
735B5	MEASUREMENT F/A	\$920	\$0	\$0		\$0	\$0
735B6	FRONT PANEL	\$7	\$0	\$0		\$0	\$0

LOGS, PM-L
DATE PROCESSED

LOGISTIC SUPPORT COST BREAKDOWN RCS:LOG-WMD-0-7813-3
CURRENT QUARTER COMPUTATION

WEAPON SYSTEM A0070 DCALC
07N 08-110/08-1 DATA AS OF 74 DEC

NAVC	NOUN	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUES			CONDEMNATION COST	BASE MATERIAL COST
					PACK/SHIP COST			
73EBA	ASSY DATA INPUT	956	90		90		90	90
73EBB	ASSY ADDR/MEMO	9131	90		90		90	90
73EBC	ASSY PROCEDURE C	929	9182	P	95	P	90	90
73EBD	ASSY DISCRETE I	9112	92		93		90	90
73EBE	ASSY INSTRUCTION	914	9333		91		90	90
73EBF	ASSY DRIVER TRAM	950	90		92		90	90
73EBG	ASSY STORE CONT	947	9398	P	93		90	90
73EBH	ASSY CORE PLANE	9241	91,268		910		90	90
73EBI	ASSY ANALOG OUT	9833	95,130	P	964	P	90	90
73EBJ	ASSY ANALOG INP	980	9458		93		90	90
73EBK	ASSY RATE-DEFL	9120	97		96		90	90
73EBL	ASSY FUNCTION C	921	9122		91		90	90
73EBM	ASSY CLOCK CHCK	971	9372		92		90	90
73EBN	ASSY PARAMETER C	935	90	P	91		90	90
73EBP	SIGNAL DATA PRD	940,023	92,810		9137		90	90
73EBQ	CHAMIS ELECTRIC	924	920	P	92	P	90	90
73EBR	NOC	9119	90	P	95	P	90	90
73ECA	ASSY FAN	9189	90		90		90	90
73ECO	MT ELECT EQUIPM	9117	90		90		90	90
73EC9	NOC	915	90		90		90	90
73E00	D18 SYS HEADSUP	98,382	90		90		90	90
73EXX		9125,333	9187,625		96,035		9108	90
73FA0	BOARD CAPRI	9245	9730		98		90	90
73FAE	MODULE GIMBAL L	9274	9838		918		90	90
73FAF	MODULE PAR SUP	9198	9550		916		90	90
73FAG	MODULE MODE SWI	9102	9472		96		90	90
73FA0	UNIT INERTIAL M	959,528	9123,444		93,476		90	90
73FAS	NOC	9118	90		90		90	90
73FBO	RACK ELEC EQUIP	9916	90		90		90	90
73FCB	FRONT PANEL	9129	90		90		90	90
73FC0	CONTROLLER INS	92,238	9381		97		90	90
73FC9	NOC	980	90		90		90	90
73FDB	CARD SEQUENCER	9108	9780		96		90	90
73FDC	CARD SEQUENCER	9140	91,143		97		90	90
73FDD	MODULE 800 M2	9293	9507		97		90	90
73FDF	MODULE 800 M2	91,482	92,990		9181		90	90

WEAPON SYSTEM 40070 DCALC LOGISTIC SUPPORT COST BREAKDOWN ACS-LOG-REQ-0-7813-3- 10001, PM-4
 07M 00-110000-1 DATA AS OF 74 SEP CURRENT QUARTER COMPUTATION DATE PROCESSED

NA'S	MODM	FIELD MAINT	QUANTITATIVE VALUES			BASE MATERIAL COST
			SPEC REPAIR COST	PACK/SHIP COST	COORDINATION COST	
7200A	ASSY DRIVER TRM	000	00	04	00	00
7200B	ASSY STONE CONT	000	0122	01	00	00
7200C	ASSY CORE PLANE	0100	0244	02	00	00
7200D	ASSY ANALOG OUT	0140	02,000	020	00	00
7200E	ASSY ANALOG IMP	0144	01,000	07	00	00
7200F	ASSY RATE-DEFL	0374	01	01	00	00
7200G	ASSY ENVELOPE R	000	0333	01	00	00
7200H	ASSY FUNCTION C	002	0122	01	00	00
7200I	ASSY CLOCK OVER	0110	0100	02	00	00
7200J	ASSY PARAMETER C	07	00	01	00	00
7200K	PUR SUPPLY B VOL	000	0333	04	00	00
7200L	PUR SUPPLY LOW	0119	0100	04	00	00
7200M	SIGNAL DATA PRO	042,000	00,100	0305	00	00
7200N	MAGNETIC ASSY	020	00	00	00	00
7200O	CHASSIS ELECTRONIC	07	00	00	00	00
7200P	NOX	004	00	00	00	00
7200Q	ASSY FAN	000	00	00	00	00
7200R	MT ELECT EQUIPM	0030	00	00	00	00
7200S	D18 SYS HEADUP	00,700	00	00	00	00
7200T		0130,393	0149,101	04,000	0310	00
7200U	BOMB CAPRI	0005	03,524	070	00	00
7200V	MODULE GIMBAL L	0070	02,370	000	00	00
7200W	MODULE PAR SUP	0044	01,705	050	00	00
7200X	MODULE MODE SWI	0391	01,100	010	00	00
7200Y	FAN	07	00	00	00	00
7200Z	UNIT INERTIAL M	070,344	0130,453	03,000	00	00
7201A	NOX	035	00	00	00	00
7201B	PACK ELEC EQUIP	0410	00	00	00	00
7201C	FRONT PANEL	021	00	00	00	00
7201D	CONTROLLER INS	01,400	0500	010	00	00
7201E	MODULE SEQUENCE	001	00	00	00	00
7201F	CARD SEQUENCER	0175	0700	00	00	00
7201G	CARD SEQUENCER	0190	01,397	03	00	00
7201H	MODULE 000 ME	0343	0037	010	00	00
7201I	MODULE HEAD REP	0071	01,024	0103	00	00

WEAPON SYSTEM 40070 DEALC LOGISTIC SUPPORT COST BREAKDOWN MCS, LOG-MOD-9-7213-3- KOSI, PM-4
 47M 08-110/08-1 DATA AS OF 74 JUN CURRENT QUARTER COMPUTATION DATE PROCESSED

MUC	MDM	FIELD MAINT	QUARTERLY VALUES			BASE MATERIAL COST
			SPEC REPAIR COST	PACK/SHIP COST	CONDEMNATION COST	
752H		903,243	9129,110	92,725	91,954	90
752A	BOARD CAPRI	983	9057	95	90	90
752E	MODULE CIRCUL L	9538	91,180	923	90	90
752F	MODULE PUR SUP	9374	91,155	924	90	90
752G	MODULE MODE SWI	9213	91,003	910	90	90
752P	GYROSCOPE X-Y AX	937	90	90	90	90
752A	UNIT INERTIAL M	955,594	9281,415	93,858	90	90
752A	NOC	92	90	90	90	90
752B	RACK ELEC EQUIP	9567	90	90	90	90
752C	FRONT PANEL	962	90	90	90	90
752C	CONTROLLER IMB	91,677	9404	97	90	90
752C	NOC	92	90	90	90	90
752D	MODULE SEQUENCE	95	90	90	90	90
752D	CARD SEQUENCER	9137	9725	98	90	90
752D	CARD SEQUENCER	9108	9908	95	90	90
752D	MODULE 800 M2	9384	9456	98	90	90
752E	MODULE HEAD REP	91,343	92,180	9112	90	90
752F	MODULE RELAY DR	954	90	90	90	90
752G	CARD RELAY DRIV	9120	9561	98	90	90
752H	CARD RELAY DRIV	961	9295	93	90	90
752H	DRIVER AMPLIFIE	95	90	90	90	90
752H	CARD PUR SUPPLY	9398	91,808	942	90	90
752H	CARD PUR SUPPLY	9132	9784	99	90	90
752P	CARD PUR SUPPLY	9103	9201	97	90	90
752A	CARD PUR SUPPLY	9380	91,800	942	90	90
752H	CARD PUR SUPPLY	9128	9488	910	90	90
752B	MODULE SITE	958	9370	93	90	90
752B	MOTHER BOARD MD	954	90	90	90	90
752B	ADPTR PUR SP LS	942,393	92,004	972	90	90
752B	NOC	9225	90	90	90	90
752B	ADPTR ADPT/PS	9188	90	90	90	90
752A	BATTERY CHARGER	9283	90	90	9105	90
752B	CHARGER PC BD	95	90	90	90	90
752C	BATTERY MTER ADPT	93,215	923	9101	90	90
752B	BATTERY PACK IM	92,837	93,200	928	90	90
752B	NOC	948	90	90	90	90
752B	INTRA REMOTE CON	9274	90	90	90	90
752B	INERTIAL MEASUREMENT	948,952	90	90	90	90

WEAPON SYSTEM A0070 DCAMA
AFN 05-110/05-1 DATA AS OF 74 MAR

LOGISTIC SUPPORT COST BREAKDOWN RCS:LOG-MMO-0-7213-3-
CURRENT QUARTER COMPUTATION

KOSI, NA
DATE PROCESS

WUC	NOUN	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUES			BASE MATERIAL COST
				PACK/SHIP COST	CONDEMNATION COST		
73E00	DIS SYS HEADSUP	95,537	90	90	90	90	
73E1X		972,233	9125,950	92,971	91,643	90	
73FA0	BOARD CAPRI	9195	9360	93		90	
73FAE	MODULE GIMBAL L	9355	9754	915		90	
73FAF	MODULE PUR SUP	9269	9324	97		90	
73FAG	MODULE MODE SWI	977	9408	94		90	
73FAM	ACCELEROMETER X-Y	938	90	90		90	
73FAN	ACCLMTR ELECTRON	921	90	90		90	
73FAO	UNIT INERTIAL M	943,003	9192,489	92,711		90	
73FA9	NOC	94	90	90		90	
73F90	RACK ELEC EQUIP	9278	90	90		90	
73F9B	FRONT PANEL	9104	90	90		90	
73FC0	CONTROLLER INS	9736	90	90		90	
73F08	CARD SEQUENCER	9108	9385	93		90	
73FDC	CARD SEQUENCER	9103	9400	92		90	
73F00	MODULE 800 MZ	959	9211	93		90	
73FDE	MODULE HEAD REP	9728	91,068	921		90	
73FDF	MODULE RELAY DR	928	950	91		90	
73FDG	CARD RELAY DRIV	949	9150	92		90	
73F0M	CARD RELAY DRIV	983	9232	92		90	
73FDJ	MODULE MOL-PTTC	998	90	90		90	
73F0K	DRIVER AMPLIFIE	97	90	91		90	
73F0N	CARD PUR SUPPLY	9115	9098	93		90	
73F0P	CARD PUR SUPPLY	989	9388	95		90	
73FDP	CARD PUR SUPPLY	947	9198	97		90	
73FDG	CARD PUR SUPPLY	9160	9518	912		90	
73FDR	CARD PUR SUPPLY	989	9156	94		90	
73FDS	MODULE SITE	918	974	91		90	
73F0U	MOTHER BOARD MD	95	90	90		90	
73F00	ADPTR PUR SP LS	928,594	90	90		90	
73FD9	NOC	9784	90	90		90	
73FEO	MOJMT ADPT/PS	9277	90	90		90	
73FFA	BATTERY CHARGER	9345	90	94		90	
73FFC	BATRY MTR ASSY	95,457	919	988		90	
73FFO	BATTERY PACK IM	92,298	9800	97		90	
73FCO	MTR REMOTE COM	9898	90	90		90	

WEAPON SYSTEM A007D DCANA LOGISTIC SUPPORT COST BREAKDOWN RCS,LOG-MNO-Q-7213-3-
 AFM 00-110/00-1 DATA AS OF 73 DEC

NO51.FM44
 DATE PROCESSED

LOGISTIC SUPPORT COST BREAKDOWN
 CURRENT QUARTER COMPUTATION

MAC	NOUN	FIELD MAINT	QUARTERLY VALUES			CONDENSATION COST	BASE MATERIAL COST
			SPEC REPAIR COST	PACK/SHIP COST			
72E8K	ASSY DRIVE TRAN	918	90	90		90	90
72E8L	ASSY STORE CONT	915	P	90		90	90
72E8M	ASSY CORE PLANE	930	P	95		90	90
72E8P	ASSY ANALOG OUT	9114	P	97		90	90
72E8R	ASSY RATE-DEFL	9127	P	916		90	90
72E8S	ASSY RATE-DEFL	918	92	93		90	90
72E8T	ASSY OVERFLOW R	93	90	90		90	90
72E8U	ASSY FUNCTION C	95	P	91		90	90
72E8V	ASSY CLOCK CHCK	929	P	92		90	90
72E8W	ASSY PARAMETER C	95	90	90		90	90
72E8X	PUR SUPPLY LOW	93	P	93		90	90
72E8Y	SIGNAL DATA PRO	914,577	P	920		90	90
72E8Z	CIRCUIT BOARD R	97	90	90		90	90
72E9A	CHARGE ELECTRONIC	932	P	92		9239	90
72E9B	ASSY RECTIFIER B	97				90	90
72E9C	ASSY FAN	9134	90	90		90	90
72E9D	MT ELECT EQUIPM	900	90	90		90	90
72E9E	MT ELECT EQUIPM	9157	90	90		90	90
72E9F	DIS SYS MEASUR	90,481	90	90		90	90
72E9G		988,380	97	92,599		9239	90
72F8D	BOARD CAPR	9303	93,848	95		90	90
72F8E	MODULE GINER L	9288	92,338	918		90	90
72F8F	MODULE PUR SUP	9203	91,520	912		90	90
72F8G	MODULE MODS SWI	9384	92,040	95		90	90
72F8H	UNIT INERTIAL M	940,731	9150,398	92,659		90	90
72F8I	PACK ELEC EQUIP	9780	90	90		90	90
72F8J	ASSY MECHANICAL	93	90	90		90	90
72F8K	FRONT PANEL	977	90	90		90	90
72F8L	CONTROLLER INS	91,231	9400	97		90	90
72F8M	MOD	98	90	90		90	90
72F8N	CARD SEQUENCER	972	9398	93		90	90
72F8P	CARD SEQUENCER	988	9400	92		90	90
72F8Q	MODULE 900 M2	988	9211	93		90	90
72F8R	MODULE HEAD REP	91,003	91,299	927		90	90
72F8S	MODULE RELAY DR	99	90	90		90	90
72F8T	CARD RELAY DRIV	932	9100	91		90	90

WEAPON SYSTEM A0070 DCAMA
AFN 08-110/08-1 DATA AS OF 73 SEP

LOGISTIC SUPPORT COST BREAKDOWN PCB, LOG-MOD-0-7213.3.
CURRENT QUARTER COMPUTATION

K051, PA4
DATE PROCESSED

		QUARTERLY VALUES				BASE MATERIAL COST
		FIELD MAINT	SPEC REPAIR COST	PACK/SHIP COST	CONSERVATION COST	
AAC	NOUN					
72BT	ASSY FUNCTION C	940	P 90	91	P 90	90
72BU	ASSY CLOCK CHCK	9121	P 90	95	P 90	90
72BV	ASSY PARAMETR C	95	90	90	90	90
72BN	PUR SUPPLY S VOL	913	90	90	90	90
72BE	PUR SUPPLY LOW	93	P 90	93	90	90
72BS	SIGNAL DATA PRO	928, 936	P 90	9280	90	90
72BS	CHASSIS ELECTRONIC	9127	90	90	960	90
72BS	NOC	9242	90	90	90	90
72CA	ASSY FAN	9294	90	90	90	90
72CO	MT ELECT EQUIPM	9249	90	90	90	90
72EO	DIB SYS HEADSUP	913, 448	90	90	90	90
72EX		9103, 238	924	93, 634	94, 166	90
73AD	BOARD CAPRI	9262	91, 872	92	90	90
73AE	MODULE GINGAL L	9375	9568	P 90	90	90
73AF	MODULE PUR SUP	9182	P 93, 428	P 97	90	90
73AG	MODULE MODE SWI	9127	91, 080	92	90	90
73AH	ACCELEROMETER X-Y	92	90	90	90	90
73AI	UNIT INERTIAL M	944, 250	9215, 084	93, 173	90	90
73AO	RACK ELEC EQUIP	9101	90	90	90	90
73CB	FRONT/PANEL	925	90	90	90	90
73CO	CONTROLLER INS	91, 197	9300	95	90	90
73CS	NOC	919	90	90	90	90
73DA	MODULE SEQUENCE	93	90	90	90	90
73DB	CARD SEQUENCER	9171	9184	91	90	90
73DC	CARD SEQUENCER	9127	9100	91	90	90
73DO	MODULE 800 HZ	928	9118	91	90	90
73DE	MODULE HEAD REP	9831	91, 248	924	90	90
73DF	MODULE RELAY DR	93	90	90	90	90
73DG	CARD RELAY DRIV	979	9150	92	90	90
73DH	CARD RELAY DRIV	959	9174	92	90	90
73DJ	MODULE ROL-PITC	918	90	90	90	90
73DM	CARD PUR SUPPLY	9290	91, 378	919	90	90
73DN	CARD PUR SUPPLY	979	9291	94	90	90
73DP	CARD PUR SUPPLY	9110	9138	97	90	90
73DQ	CARD PUR SUPPLY	9201	9808	918	90	90
73DR	CARD PUR SUPPLY	987	9104	91	90	90
73DS	MODULE F SITE	988	9000	--	90	90

LEAPON SYSTEM A0070 OCAMA LOGISTIC SUPPORT COST BREAKDOWN RCS,LOG-MNO-0-7213-3- K051.PWAL
 07M 00-110/00-1 DATA AS OF 73 JUN CURRENT QUARTER COMPUTATION DATE PROCESSED

WAC	NOUN	FIELD MAINT	QUARTERLY VALUES			BASE MATERIAL COST
			SPEC REPAIR COST	PACK/SHIP COST	CONDENATION COST	
73ECA	AGSY PAN	071	00	00	00	00
73ECO	MT ELEC EQUIPM	0345	00	00	00	00
73E00	D18 SYS HEADSUP	010,501	00	00	00	00
73EXX		0120,363	019	02,281	00	00
73FA0	BOMBO CAPRI	0143	071	01	00	00
73FAE	MODULE GIMBAL L	0307	067	00	00	00
73FAF	MODULE PAR SUP	0269	0424	00	00	00
73FAG	MODULE MODE SWI	0136	0342	03	00	00
73FAS	GYROSCOPE ELECTRA	028	00	00	00	00
73FA0	UNIT INERTIAL M	051,740	0321,000	03,424	00	00
73FAS	NOC	05	00	00	00	00
73FBO	RACK ELEC EQUIP	0140	00	00	00	00
73FCB	FRONT PANEL	02	00	00	00	00
73FCO	CONTROLLER IMB	01,362	0158	03	00	00
73FC9	NOC	021	00	00	00	00
73FDB	CARD SEQUENCER	0121	0300	02	00	00
73FDC	CARD SEQUENCER	0108	038	01	00	00
73FDD	MODULE 800 MZ	0106	00	00	00	00
73FDE	MODULE HEAD REP	0049	01,011	022	00	00
73FDG	CARD RELAY DRIV	0197	0158	03	00	00
73FDH	CARD RELAY DRIV	0111	0228	02	00	00
73FDK	DRIVER AMPLIFIE	015	00	00	00	00
73FDL	POWER SUPPLY	074	00	00	00	00
73FDN	CARD FOR SUPPLY	0143	0588	08	00	00
73FDN	CARD FOR SUPPLY	032	00	00	00	00
73FDP	CARD FOR SUPPLY	0150	0132	07	00	00
73FDE	CARD FOR SUPPLY	0165	0504	012	00	00
73FDR	CARD FOR SUPPLY	045	0100	01	00	00
73FDS	MODULE SITE	028	0144	01	00	00
73FDU	MOTHER BOARD HQ	028	00	00	00	00
73FDO	ADPTR PART SP LB	030,970	00	028	00	00
73FDS	NOC	010	00	00	00	00
73FES	HEUNT ADPT/PS	078	00	00	00	00
73FFA	BATTERY CHARGER	0015	00	00	00	00
73FFB	CHARGER PC 80	058	00	00	00	00
73FFC	BATTERY MTER AGSY	05,205	019	008	00	00

WEAPON SYSTEM A0070 02A000
AFM 85-110/88-1 DATA AS OF 73 MAR

DATE PROCESSED
K051.PN4L
CURRENT QUARTER COMPUTATION

73E84 PUR SUPPLY 5 VOL
73E82 PUR SUPPLY LOW
73E80 SIGNAL DATA PRO
73E83 CHASIS ELECTRIC
73E80 MT ELECT EQUIPM
73E80 CIS SYS HEADSUP
73E84

WUC	NOUN	FIELD MAINT	REP/REPAIR COST	STARTER VALUES PACK SHIP COST	CONCENTRATION COST	BASE MATERIAL COST
73E84	PUR SUPPLY 5 VOL	822	\$0	\$0	\$0	\$0
73E82	PUR SUPPLY LOW	828	\$0	\$0	\$0	\$0
73E80	SIGNAL DATA PRO	\$27,230	\$0	\$278	\$0	\$0
73E83	CHASIS ELECTRIC	83	\$0	\$0	\$0	\$0
73E80	MT ELECT EQUIPM	\$263	\$0	\$0	\$0	\$0
73E80	CIS SYS HEADSUP	\$20,229	\$0	\$0	\$0	\$0
73E84		\$103,452	\$10	\$3,313	\$6,856	\$0
73E80	BOARD CAPRI	8341	\$284	\$2	\$0	\$0
73E80	MODULE GIMBAL L	845	\$237	\$0	\$0	\$0
73E80	MODULE PUR SUP	8453	\$216	\$5	\$0	\$0
73E80	MODULE MODE SWI	\$124	\$54	\$1	\$0	\$0
73E80	ACCUPTER ELECTRIC	8	\$0	\$0	\$0	\$0
73E80	UNIT INERTIAL M	\$47,143	\$143,452	\$1,380	\$0	\$0
73E80	NOE	837	\$0	\$0	\$0	\$0
73E80	RACK ELEC EQUIP	840	\$0	\$0	\$0	\$0
73E80	FRONT PANEL	824	\$0	\$0	\$0	\$0
73E80	CONTROLLER IMV	\$1,622	\$10	\$3	\$0	\$0
73E80	MODULE SEQUENCE	813	\$0	\$0	\$0	\$0
73E80	CAPC SEQUENCEP	844	\$15	\$1	\$0	\$0
73E80	CAPC SEQUENCEP	845	\$0	\$0	\$0	\$0
73E80	MODULE 900 MZ	8200	\$0	\$1	\$0	\$0
73E80	MODULE HEAD REP	\$1,271	\$116	\$24	\$0	\$0
73E80	CAPC RELAY DPT	842	\$15	\$1	\$0	\$0
73E80	CAPC RELAY DPT	813	\$14	\$1	\$0	\$0
73E80	MODULE REL DPT	851	\$0	\$0	\$0	\$0
73E80	CAPC PUR SUPPLY	\$171	\$1,204	\$16	\$0	\$0
73E80	CAPC PUR SUPPLY	837	\$300	\$4	\$0	\$0
73E80	CAPC PUR SUPPLY	837	\$130	\$1	\$0	\$0
73E80	CAPC PUR SUPPLY	8232	\$114	\$21	\$0	\$0
73E80	CAPC PUR SUPPLY	8237	\$364	\$4	\$0	\$0
73E80	ACCUPTER PUR SUP	\$32,554	\$72	\$10	\$0	\$0
73E80	NOE	824	\$0	\$0	\$0	\$0
73E80	MODULE ACCT PR	\$132	\$0	\$0	\$0	\$0
73E80	WATERPUMP SHIP	\$1,271	\$0	\$0	\$0	\$0
73E80	WATERPUMP SHIP	824	\$0	\$0	\$0	\$0
73E80	WATERPUMP SHIP	\$1,271	\$23	\$14	\$0	\$0
73E80	WATERPUMP SHIP	\$3,071	\$0	\$1	\$0	\$0

WEAPON SYSTEM A007D OCAMA
AFM 65-110/66-1 DATA 'S OF 72 DEC

LOGISTIC REPORT COST BREAKDOWN
CURRENT QUARTER INFORMATION

WAC	NOUN	FIELD MAINT	SPEC REPAIR COST	QUARTERLY VALUES		QUANTITY
				PAC-SHIP	COST	
73EA9	NOC	\$200	\$0	\$0	\$0	1
73EBA	ASSY DATA INPUT	\$9	\$0	\$0	\$0	1
73EBB	ASSY ADDER/MEMO	\$130	\$0	\$0	\$0	1
73EBC	ASSY PROCESSOR C	\$28	\$0	\$0	\$0	1
73EBE	ASSY DISCRETE I	\$6	\$0	\$0	\$0	1
73EBH	ASSY INSTRUCTION	\$39	\$0	\$0	\$0	1
73EBJ	ASSY STR CONT R	\$73	\$0	\$0	\$0	1
73EBK	ASSY DRIVER TRAN	\$19	\$0	\$0	\$0	1
73EBL	ASSY STORE CONT	\$41	\$0	\$0	\$0	1
73EBM	ASSY CORE PLANE	\$45	\$0	\$0	\$0	1
73EBP	ASSY ANALOG OUT	\$392	\$0	\$0	\$0	1
73EBQ	ASSY ANALOG INP	\$108	\$0	\$0	\$0	1
73EBR	ASSY RATE-DEFL	\$22	\$0	\$0	\$0	1
73EBB	ASSY OVERFLOW R	\$25	\$0	\$0	\$0	1
73EBT	ASSY FUNCTION C	\$37	\$0	\$0	\$0	1
73EBU	ASSY CLOCK CHEK	\$113	\$0	\$0	\$0	1
73EBV	ASSY PARAMETR C	\$5	\$0	\$0	\$0	1
73EBX	PWR SUPPLY 5 VOL	\$6	\$0	\$0	\$0	1
73EB0	SIGNAL DATA PRO	\$29,703	\$0	\$197	\$0	1
73EB2	MAGNETIC ASSY	\$11	\$0	\$0	\$0	1
73EB3	CHASSIS ELECTRONIC	\$21	\$0	\$0	\$0	1
73ECA	ASSY FAN	\$85	\$0	\$0	\$0	1
73ECO	MT ELECT EQUIPM	\$87	\$0	\$0	\$0	1
73E00	DIB SYS HEADSUP	\$19,399	\$0	\$0	\$0	1
73EXX		\$93,674	\$12	\$2,773	\$1,515	1
73FA0	BOARD CAPRI	\$215	\$210	\$0	\$0	1
73FAE	MODULE GIMBAL L	\$298	\$188	\$0	\$0	1
73FAF	MODULE PWR SUP	\$401	\$53	\$0	\$0	1
73FAG	MODULE MODE SWI	\$124	\$0	\$0	\$0	1
X 73FA0	UNIT INERTIAL M	\$39,361	\$30,928	\$1,770	\$0	1
73FB0	RACK ELEC EQUIP	\$458	\$0	\$0	\$0	1
73FC0	CONTROLLER IMS	\$548	\$101	\$0	\$0	1
73FDA	MODULE SEQUENCE	\$14	\$0	\$0	\$0	1

K051, PM4L
DATE PROCESSED

LOGISTIC SUPPORT COST BREAKDOWN
CURRENT QUARTER COMPUTATION

WEAPON SYSTEM A0070 OCAMA
AFM 05-110/00-1 DATA AS OF 72 SEP

MAC	MODL	FIELD MAINT	QUARTERLY VALUES			BASE MATERIAL COST
			SPEC REPAIR COST	PACK/SHIP COST	CONCERNATION COST	
73EC0	MT ELECT EQUIPM	9158	90	90	90	90
73EC9	NOC	920	90	90	90	90
73E00	D18 SYS HEADSUP	910,003	90	90	90	90
73E1X		930,913	98	93,482	91,510	90
73FAD	BOARD CAPRI	987	970	91	90	90
73FAE	MODULE C1M1AL L	9146	958	90	90	90
73FAF	MODULE PUR SUP	952	90	90	90	90
73FAG	MODULE MODE SHI	963	9112	91	90	90
73FAD	UNIT INERTIAL M	941,243	9104,392	92,249	90	90
73FBO	RACK ELEC EQUIP	9562	90	90	90	90
73FC0	CONTROLLER INS	9760	9505	90	90	90
73FC9	NOC	924	90	90	90	90
73FDB	CARD SEQUENCER	943	90	90	90	90
73FDC	CARD SEQUENCER	920	90	90	90	90
73FDB	MODULE HEAD REP	92,368	9690	935	90	90
73FDB	CARD RELAY D11V	937	90	90	90	90
73FDB	MODULE REL-P1TC	93	90	90	90	90
73FDB	CARD PUR SUPPLY	9178	9525	98	90	90
73FDB	CARD PUR SUPPLY	918	9158	92	90	90
73FDB	CARD PUR SUPPLY	9188	9320	912	90	90
73FDB	CARD PUR SUPPLY	984	9313	910	90	90
73FDB	CARD PUR SUPPLY	924	9102	91	90	90
73FDB	MODULE SITE	96	974	91	90	90
73FDB	ADPTR PUR SP LS	930,648	93,337	928	90	90
73FDB	NOC	9282	90	90	90	90
73FDB	MODULE ADPT/PS	9122	90	90	90	90
73FDB	BATTERY CHARGER	91,717	90	90	90	90
73FDB	CHARGER PC 80	949	90	90	90	90
73FDB	BATTERY MTER ASBY	93,015	922	934	91,112	90
73FDB	BATTERY PACK IN	94,585	90	90	90	90
73FDB	INTR REMOTE COM	9791	90	90	90	90
73FDB	INERTIAL MEASUR	933,120	90	90	90	90
73FDB		9120,279	9111,508	92,493	91,112	90

NAIC	NAUN	FIELD NAME	SPEC REPAIR UNIT	QTY	UNIT PRICE	TOTAL PRICE	QTY	UNIT PRICE	TOTAL PRICE
73EAS	ASSY VIDEO	\$8	\$0	1	\$8	\$8	1	\$8	\$8
73EAS	ASSY BITE	\$45	\$0	1	\$45	\$45	1	\$45	\$45
73EAT	PWR SUPPLY LOW V	\$811	\$0	1	\$811	\$811	1	\$811	\$811
73EAV	PRINT CIR BRD IM	\$28	\$0	1	\$28	\$28	1	\$28	\$28
73EAV	CIR BRD ER AMP	\$183	\$0	1	\$183	\$183	1	\$183	\$183
73EAV	CIR BRD OUTPT R	\$67	\$0	1	\$67	\$67	1	\$67	\$67
73EAS	ASSY RECTIFIER B	\$186	\$0	1	\$186	\$186	1	\$186	\$186
73EAO	DIS UNIT HEADCU	\$26,221	\$0	1	\$26,221	\$26,221	1	\$26,221	\$26,221
73EAS	NOC	\$213	\$0	1	\$213	\$213	1	\$213	\$213
73EAS	ASSY DATA INPUT	\$22	\$0	1	\$22	\$22	1	\$22	\$22
73EAS	ASSY ADPR-MEMO	\$96	\$0	1	\$96	\$96	1	\$96	\$96
73EHC	ASSY PROCESOR C	\$34	\$0	1	\$34	\$34	1	\$34	\$34
73EHC	ASSY DISCRETE I	\$13	\$0	1	\$13	\$13	1	\$13	\$13
73EHC	ASSY INSTRUCTION	\$16	\$0	1	\$16	\$16	1	\$16	\$16
73EHC	ASSY STR CONT R	\$40	\$0	1	\$40	\$40	1	\$40	\$40
73EHC	ASSY DRIVE TRAN	\$44	\$0	1	\$44	\$44	1	\$44	\$44
73EHC	ASSY STORE CONT	\$69	\$0	1	\$69	\$69	1	\$69	\$69
73EHC	ASSY CORE PLANE	\$76	\$1	1	\$76	\$76	1	\$76	\$76
73EHC	ASSY ANALOG OUT	\$130	\$0	1	\$130	\$130	1	\$130	\$130
73EHC	ASSY ANALOG IMP	\$40	\$0	1	\$40	\$40	1	\$40	\$40
73EHC	ASSY RATE-DEFI	\$49	\$3	1	\$49	\$49	1	\$49	\$49
73EHC	ASSY ORN-FLW R	\$21	\$0	1	\$21	\$21	1	\$21	\$21
73EHC	ASSY CLOCK CHCK	\$66	\$0	1	\$66	\$66	1	\$66	\$66
73EHC	ASSY PARAPETR C	\$74	\$0	1	\$74	\$74	1	\$74	\$74
73EHC	PWR SUPPLY 5 VOL	\$21	\$0	1	\$21	\$21	1	\$21	\$21
73EHC	PWR SUPPLY LOW	\$20	\$0	1	\$20	\$20	1	\$20	\$20
73EHC	SIGNAL DATA PRD	\$54	\$0	1	\$54	\$54	1	\$54	\$54
73EHC	NOC	\$19,761	\$0	1	\$19,761	\$19,761	1	\$19,761	\$19,761
73EHC	ASSY FAH	\$16	\$0	1	\$16	\$16	1	\$16	\$16
73EHC	MT ELECT GUNW	\$71	\$0	1	\$71	\$71	1	\$71	\$71
73EHC	DIS CIR MND JP	\$412	\$0	1	\$412	\$412	1	\$412	\$412
73EHC	DIS CIR MND JP	\$9,533	\$0	1	\$9,533	\$9,533	1	\$9,533	\$9,533
73EHC		\$58,027	\$10	1	\$58,027	\$58,027	1	\$58,027	\$58,027
73EHC	ROUND CAPRI	\$296	\$0	1	\$296	\$296	1	\$296	\$296
73EHC	MODULE GIMBAL L	\$145	\$0	1	\$145	\$145	1	\$145	\$145
73EHC	MODULE MODE SWI	\$96	\$224	1	\$96	\$96	1	\$96	\$96
73EHC	UNIT INERTIAL M	\$34,127	\$156,426	1	\$34,127	\$34,127	1	\$34,127	\$34,127

Weapon System A007D OCAMA Logistic Support Cost Breakdown
 AFM 65-110/66-1 Data as of 79 Mar Current Quarter Computation K051.PN4L

QUARTERLY VALUES					
WUC	NOUN	FIELD MAINT	SPEC REPAIR COST	PACK/SHIP COST	CONDEMNATION COST
73FAO	Unit Inertial M.	71,969	157,325	\$2,992	0
					0

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BIOGRAPHICAL SKETCHES OF THE AUTHORS

Captain Douglas C. Beckwith graduated from high school in Pembroke, New York, in 1967. He attended Oklahoma State University from which he received a Bachelor of Science degree in Hotel Administration in May 1973. Commissioned an officer in 1973, he received nine months of formal training at Fort Rucker, Alabama, for subsequent duty as a Flight Examiner Pilot at Minot Air Force Base, North Dakota. He was then transferred to Eglin Air Force Base, Florida, where he performed duties as the Wing H-1F Standardization Pilot and Wing Executive Officer. He then became a Maintenance Supervisor and was assigned to the Air Force Systems Command.

Captain Anthony R. Roclevitch was born 1 January 1953 in Bourne, Massachusetts. He graduated from high school in Wiesbaden, Germany, in 1971. He attended Troy State University where he earned a Bachelor of Science degree in History and received an officer commission through the AFROTC Program in June 1975. He cross-trained from the Administration career field in 1980 and was assigned as OIC of the Aircraft Branch, 1 TFW, Langley Air Force Base, Virginia, from 1980 to 1981. He graduated from the Squadron Officer School with Class 3-79.

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